

## *A Remark to Existence and Uniqueness of Certain Stable Solutions of a Weakly Nonlinear System*

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### 1. Introduction.

In this note, we consider the  $n$ -dimensional system

$$(1) \quad x' = Ax + f(t, x) \quad \left( ' = \frac{d}{dt} \right)$$

such that

1° the  $k$  ( $k \leq n$ ) characteristic roots  $\lambda_i$  ( $i=1, 2, \dots, k$ ) of the constant matrix  $A$  have negative real parts;

2° the remaining  $(n-k)$  characteristic roots  $\lambda_i$  ( $i=k+1, \dots, n$ ) have non-negative real parts;

3° for a certain  $\Delta > 0$ ,

$$(2) \quad f(t, x) = (|x|^{1+\Delta})^1$$

uniformly in  $t$  as  $|x| \rightarrow 0$ .

For such a system, in the book of E. A. Coddington and N. Levinson [1], there is stated a theorem<sup>2)</sup> as follows:

When  $\lambda_i$ 's ( $i=1, 2, \dots, k$ ) are arranged so that  $R\lambda_i \leq R\lambda_{i+1}$  ( $i=1, 2, \dots, k-1$ ), if  $x = \varphi(t)$  is a solution of (1) and it holds that

$$\limsup_{t \rightarrow \infty} \frac{\log |\varphi(t)|}{t} = b < 0,$$

then there exist integers  $p$  and  $q$  ( $1 \leq p \leq q \leq k$ ) such that

$$R\lambda_{p-1} < R\lambda_p = R\lambda_{p+1} = \dots = R\lambda_q = b < R\lambda_{q+1}$$

and there exists a  $\delta > 0$  and a solution

$$(3) \quad x = \psi(t) = \sum_{j=p}^q Q_j(t) e^{\lambda_j t}$$

of  $x' = Ax$  such that

$$(4) \quad \varphi(t) = \psi(t) + O(e^{(b-\delta)t})$$

as  $t \rightarrow \infty$ . Here  $Q_j(t)$ 's are column vectors each component of which is a polynomial in  $t$ .

1)  $|x|$  means  $\sum_{i=1}^n |x^i|$ , where  $x^i$ 's are the components of the vector  $x$ . In the sequel, we use this convention.

2) In the sequel, we call this theorem the theorem of Coddington and Levinson.