

On the Definition of Convolutions for Distributions

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The main purpose of this paper is to show the equivalence of the definitions of convolutions available in the theory of distributions.

Let S and T be two distributions on R^n , n -dimensional Euclidean space. L. Schwartz ([12], exposé 21) defined the convolution $S * T$ by the relation

$$\langle S * T, \varphi \rangle = \iint (S_x \otimes T_y) \varphi(x+y) dx dy \quad \text{for any } \varphi \in (\mathcal{D}),$$

if the following condition is satisfied:

$$(*) \quad (S_x \otimes T_y) \varphi(x+y) \in (\mathcal{D}'_{L^1}) \quad \text{for any } \varphi \in (\mathcal{D}).$$

In his lecture notes [4], C. Chevalley gave two definitions of convolutions. His first definition (in more precise form) is: $S * T$ is defined as

$$(1) \quad \int_{R^n} S(y) T(x-y) dy,$$

when this makes sense. This last phrase is interpreted as in the case of integration of vector-valued functions, that is, (1) has the meanings if and only if

$$(\bar{*})' \quad S(\check{T} * \varphi) \in (\mathcal{D}'_{L^1}) \quad \text{for any } \varphi \in (\mathcal{D}).$$

And

$$\langle \int_{R^n} S(y) T(x-y) dy, \varphi \rangle = \int_{R^n} S(y) (\check{T} * \varphi)(y) dy.$$

Then in the terminology of L. Schwartz ([14], p. 130), the definition is equivalent to saying that $S * T$ is the integral (1) when the integrand $S(y) T(x-y)$ is partially summable with respect to y . The second definition (generalized convolution in his sense, [4], p. 112) is:

$S * T$ is defined when the condition

$$(\bar{*}) \quad (S * \varphi)(\check{T} * \psi) \in L^1 \quad \text{for any } \varphi, \psi \in (\mathcal{D})$$

is satisfied, and $S * T$ is given by

$$\langle (S * T) * \varphi, \psi \rangle = \int_{R^n} (S * \varphi)(x) (\check{T} * \psi)(x) dx.$$

In sec. 3, we show that these definitions of convolutions are equivalent, and furthermore that it remains valid that the definitions obtained by replacing (\mathcal{D}) by (\mathcal{S}) in the above discussions are also equivalent. After Hirata and Ogata [8] we say that the (\mathcal{S}) -convolution $S * T$ is defined when