A generalization of F. Schur's theorem

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The following theorem, due to F. Schur, is well-known:

THEOREM A. Let M be a Riemannian manifold with dim $M \ge 3$. If the sectional curvature K of M is constant at each point of M, then K is actually constant on M.

There are several other theorems of this type; we mention a few of them. THEOREM B. Let M be an Einstein manifold, that is, assume the Ricci curvature of M is a scalar multiple λ of the metric tensor of M. If dim $M \ge 3$, then λ is constant.

THEOREM C (Thorpe [2]). Let M be a Riemannian manifold with dim M $\geq 2p+1$. If the 2pth sectional curvature γ_{2p} is constant at each point of M, then γ_{2p} is constant on M.

THEOREM D. Let M be a Kähler manifold with dim $M \ge 4$. If the holomorphic sectional curvature K_h is pointwise constant, then it is actually constant.

THEOREM E (M. Berger, unpublished). Let M be a Riemannian manifold with metric tensor g_{ij} and Riemann curvature tensor R_{ijkl} . Suppose

$$\sum_{i,j,k} R_{ijks} R^{ijkt} = \lambda g_{st} \, .$$

If dim $M \ge 5$, then λ is constant.

In this paper we prove a result (theorem 2) which includes theorems A, B, C, and D as special cases. Although theorem E is not a consequence of theorem 2, it almost is, in the sense that it would be if a slightly different contraction were used.

We shall use the notation of [1]. Recall that a *double form* of type (p, q) is a function $\omega : \mathfrak{X}(M)^{p+q} \to \mathfrak{F}(M)$ which is skew-symmetric in the first p variables and also in the last q variables. Here, as usual, $\mathfrak{X}(M)$ denotes the Lie algebra of vector fields on the C^{∞} manifold M and $\mathfrak{F}(M)$ the ring of C^{∞} real valued functions on M. We write $\omega(X_1, \dots, X_p)(Y_1, \dots, Y_q)$ for the value of ω on $X_1, \dots, X_p, Y_1, \dots, Y_q$. If p=q and

 $\omega(X_1, \cdots, X_p)(Y_1, \cdots, Y_p) = \omega(Y_1, \cdots, Y_p)(X_1, \cdots, X_p)$ for $X_1, \cdots, X_p, Y_1, \cdots, Y_p \in \mathfrak{X}(M),$