

The Sylvester's law of inertia in simple graded Lie algebras

Dedicated to Professor Ichiro Satake on the occasion of his seventieth
anniversally birthday

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Introduction.

Let $H_n(\mathbf{R})$ be the vector space of $n \times n$ real symmetric matrices. The group $GL(n, \mathbf{R})^0$ (= the identity component of $GL(n, \mathbf{R})$) acts on $H_n(\mathbf{R})$ by the rule: $X \mapsto AX'A$, $X \in H_n(\mathbf{R})$, $A \in GL(n, \mathbf{R})^0$. The Sylvester's law of inertia asserts that, by this action of $GL(n, \mathbf{R})^0$, X is transformed into the canonical form $\text{diag}(1, \dots, 1, -1, \dots, -1, 0, \dots, 0)$, which is uniquely determined by X . The simple Lie algebra $\mathfrak{sp}(n, \mathbf{R})$ has a unique gradation $\mathfrak{sp}(n, \mathbf{R}) = \mathfrak{g}_{-1} + \mathfrak{g}_0 + \mathfrak{g}_1$, where $\mathfrak{g}_{-1} = H_n(\mathbf{R})$ and $\mathfrak{g}_0 \simeq \mathfrak{gl}(n, \mathbf{R})$. The $GL(n, \mathbf{R})^0$ -module $H_n(\mathbf{R})$ is imbedded in $\mathfrak{sp}(n, \mathbf{R})$ as the G_0^0 -module \mathfrak{g}_{-1} , where G_0^0 is the analytic subgroup of $\text{Aut } \mathfrak{g}$ generated by \mathfrak{g}_0 . The Sylvester's law of inertia for $H_n(\mathbf{R})$ is no other than obtaining the complete representatives of G_0^0 -orbits in \mathfrak{g}_{-1} . As a generalization of this situation, one can pose:

PROBLEM. Let $\mathfrak{g} = \sum_{k=-\nu}^{\nu} \mathfrak{g}_k$ be a real simple graded Lie algebra, G_0 the group of grade-preserving automorphisms of \mathfrak{g} and let G_0^0 be the identity component of G_0 . Find the G_0^0 -orbit decomposition and the G_0 -orbit decomposition of \mathfrak{g}_{-1} .

When $\nu = 1$, this problem is equivalent to the problem of finding the orbits in a compact simple Jordan triple system under the structure group or the identity component of the structure group. Also it is equivalent to finding the orbit decomposition of a tangent space by the linear isotropy group for a symmetric R -space.

The purpose of this paper is to settle the above problem for the case $\nu = 1$ by a unified method. Partial answers have been obtained by Satake [22, 23], Kaneyuki [9, 10] and Takeuchi [27]. In the following we shall describe briefly how to get the two kinds of orbit decompositions of \mathfrak{g}_{-1} . The sections 1 and 2 are preliminary sections. We give a quick review for the followings: classification and construction of gradations in semisimple Lie algebras [13, 12], the root theory in simple graded Lie algebras $\mathfrak{g} = \mathfrak{g}_{-1} + \mathfrak{g}_0 + \mathfrak{g}_1$ ([13]), the Jordan triple system \mathfrak{B} on \mathfrak{g}_{-1} (Loos [18]) and the root-theoretic version of a frame (= a maximal system of pairwise orthogonal idempotents) $\{e_1, \dots, e_r\}$ in \mathfrak{g}_{-1} , and the Jordan algebra structure \mathfrak{A}_p ($0 \leq p \leq r$) in \mathfrak{g}_{-1} . In §3, applying a result of Matsumoto [19], we get a set of good representatives of $G_0 \bmod G_0^0$, which allows us to get the G_0 -orbit decomposition from the G_0^0 -orbit decomposition. We consider the root system Δ^* corresponding to a certain symmetric real flag domain M^* . It turns out that the Weyl group $W(\Delta^*)$ of Δ^* , viewed as a subgroup of G_0^0 , acts on the frame $\{e_1, \dots, e_r\}$ as signed permutations. Then we can choose the candidates $o_{p,q}$ ($0 \leq p, q \leq r, p + q \leq r$) of representatives of the G_0^0 -orbits, which are defined in