

Motion of hypersurfaces and geometric equations

Dedicated to Professor Noboru Tanaka on his 60th birthday

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1. Introduction.

We are concerned with the motion of a hypersurface whose speed locally depends on the normal vector field and its derivatives. To be specific let Γ_t denote the hypersurface expressed as the boundary of a bounded open set D_t in \mathbf{R}^n ($n \geq 2$) at time t . Let \mathbf{n} denote the unit exterior normal vector field to $\Gamma_t = \partial D_t$. It is convenient to extend \mathbf{n} to a vector field (still denoted by \mathbf{n}) on a tubular neighborhood of Γ_t such that \mathbf{n} is constant in the normal direction of Γ_t . Let $V = V(t, x)$ denote the speed of Γ_t at $x \in \Gamma_t$ in the exterior normal direction. The equation for Γ_t we consider here is of form

$$(1.1) \quad V = f(t, x, \mathbf{n}(x), \nabla \mathbf{n}(x)) \quad \text{on } \Gamma_t,$$

where f is a given function and ∇ stands for spatial derivatives. Material science provides a lot of examples of (1.1) where Γ_t is an interface bounding two phases of materials (see [2, 11, 12] and references therein). For example if

$$(1.2) \quad V = -\operatorname{div} \mathbf{n},$$

the hypersurface Γ_t moves by its $(n-1)$ times mean curvature and (1.2) is known as the mean curvature flow equation. We note that this equation arises as a singular limit of some reaction-diffusion equations [3, 17]. It is also important to consider anisotropic properties of materials. A typical model (cf. [11, 12]) is

$$(1.3) \quad \beta(\mathbf{n})V = - \sum_{i=1}^n \frac{\partial}{\partial x_i} \left(\frac{\partial H}{\partial p_i}(\mathbf{n}) \right) + c,$$

where H is convex on \mathbf{R}^n and positively homogeneous of degree one, β is a positive function on a unit sphere S^{n-1} in \mathbf{R}^n and c is a constant. The equation (1.3) includes (1.2) as a particular example with $H(p) = |p|$, $\beta = 1$ and $c = 0$. We remark that in general the right hand side of (1.3) is *not* expressed as a