

Asymptotic behavior of one-dimensional random dynamical systems

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0. Introduction.

Let S be a measurable space and let $\{\tau_s\}_{s \in S}$ be a family of transformations from the unit interval I into itself which are nonsingular with respect to the Lebesgue measure m on I . Given a measure preserving transformation σ and an S -valued random variable ξ on a probability space (Ω, \mathcal{F}, P) , consider a model of a random dynamical system whose time evolution is given by

$$x_{n+1} = \tau_{\xi_{n+1}(\omega)}(x_n) \quad \text{for } n \geq 1,$$

where $\xi_n = \xi \circ \sigma^{n-1}$.

Following S. Kakutani [4], we introduce a skew product transformation T on $I \times \Omega$ which is defined by

$$T(x, \omega) = (\tau_{\xi_1(\omega)}x, \sigma\omega) \quad \text{for } (x, \omega) \in I \times \Omega.$$

Since $\text{proj}_I \circ T^n(x, \omega) = \tau_{\xi_n(\omega)} \tau_{\xi_{n-1}(\omega)} \cdots \tau_{\xi_1(\omega)}x$, we investigate the asymptotic behavior of the dynamical system $(T, m \times P)$ instead of the above random dynamical system. This was done in [3], [6], and [7], in the simplest case when ξ_n 's are independent and identically distributed. The aim of this paper is to show that even if $\{\xi_n\}_{n=1}^\infty$ is a stationary sequence of dependent random variables, the skew product transformation T has $(m \times P)$ -absolutely continuous invariant measures under some mild conditions and T admits various spectral decompositions according to the ergodic property of $\{\xi_n\}_{n=1}^\infty$. To do this as in previous paper [6], we introduce the so-called Perron-Frobenius operator \mathcal{L} of T and investigate the asymptotic property of $\mathcal{L}^n \Phi$ for $\Phi \in L^1(m \times P)$. However, instead of estimating $\mathcal{L}^n \Phi$ itself we here estimate $\int_B \mathcal{L}^n \Phi d(m \times P)$ for $B \in \mathcal{B}(I) \times \mathcal{F}$. In Basic Lemma we will give a fundamental inequality on which the whole proof depends heavily (see section 3).

In section 1 we will give the definitions of some basic concepts. The main results are collected in Theorem 2.1. Sections 3 and 4 are devoted to the proof of Theorem 2.1. In section 5 we will give an application of the theorem to random stochastic matrices.