

Homogeneous Riemannian manifolds with a fixed isotropy representation

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1. Introduction.

In this paper we give a classification of simply-connected homogeneous Riemannian manifolds $M=G/H$ where H is isomorphic to a product of rotation groups and the linear isotropy representation of H is a direct sum of standard representations with a trivial representation. This situation arises naturally in the study of homogeneous Riemannian manifolds which admit a large group of isometries. In fact if $M=I_0(M)/H$, where

$$(1.1) \quad \dim I(M) > \frac{n^2}{4} + n, \quad n = \dim M \geq 11$$

then it follows that $H \cong SO(k) \times K$, with $k > n/2$, $K \subseteq SO(n-k)$ and the linear isotropy representation of H splits [5, Theorem 1.18].

Our results are quite simple to state if each of the rotation groups has order at least 3. In that case M is isometric to a product of a certain number of simply-connected manifolds of constant curvature together with a simply-connected Lie group with a left-invariant metric. (Theorem B). If H is isomorphic to a single rotation group, this appears to be consistent with some local results obtained by Kurita [8] a number of years ago. If some of the rotation groups in the decomposition of H have order 2, then the description of the corresponding manifolds becomes more complicated. This is done in Section 4, where, in particular, we obtain a generalization of Cartan's classification [3] of 3-dimensional manifolds which admit a transitive group of motions of dimension 4.

In Section 5, we apply the above results to give an explicit description of those manifolds satisfying (1.1) and $n-3 \leq k \leq n$. This turns up some inaccuracies and extends some results in [7], while at the same time exhibiting the differences with the compact case studied by Lukesh. In [9] it is shown that if M is compact and satisfies (1.1), then it must split isometrically with one factor being a standard sphere S^k , $k > n/2$. As we shall see in Section 5, there

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