

## Some differential equations on Riemannian manifolds

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### § 1. Introduction.

Let  $(M, g)$  be a Riemannian manifold of dimension  $m \geq 2$  and let  $\nabla$  denote the Riemannian connection defined by  $g$ . In this paper we study the following system of differential equations of order three :

$$(1.1) \quad \nabla_h \nabla_j \nabla_i f + k(2\nabla_h f g_{ji} + \nabla_j f g_{ih} + \nabla_i f g_{hj}) = 0$$

where  $k$  is a positive constant. Originally the differential equations (1.1) come from some study of the Laplacian on a Euclidean sphere  $(S^m; k)$  of constant curvature  $k$ . The first eigenvalue of the Laplacian on  $(S^m; k)$  is  $mk$  and each eigenfunction  $h$  corresponding to  $mk$  satisfies the following system of differential equations of order two :

$$(1.2) \quad \nabla_j \nabla_i h + k h g_{ji} = 0.$$

The second eigenvalue is  $2(m+1)k$  and each eigenfunction  $f$  corresponding to  $2(m+1)k$  satisfies (1.1).

Assuming the existence of a non-constant function  $h$  satisfying (1.2) on a Riemannian manifold  $(M, g)$  many mathematicians studied differential geometric properties of  $(M, g)$  (cf. S. Ishihara and Y. Tashiro [11], M. Obata [14], [15], Y. Tashiro [22], etc.). In this case  $\text{grad } f$  is an infinitesimal conformal transformation.

Assume that there is a non-constant function  $f$  satisfying (1.1) on  $(M, g)$ . Then  $\text{grad } f$  is an infinitesimal projective transformation and is a  $k$ -nullity vector field on  $(M, g)$ . The converse is also true (cf. Proposition 2.1). This gives a geometric meaning of (1.1).

The system of differential equations (1.1) was first studied by M. Obata [15] and he announced the following.

**THEOREM A.** *Let  $(M, g)$  be a complete and simply connected Riemannian manifold. In order for  $(M, g)$  to admit a non-constant function  $f$  satisfying (1.1)*

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