

## A problem on the existence of an Einstein metric

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(Received June 21, 1966)

This note is to present a variational problem, to which the problem of the existence of an Einstein metric is reduced. The latter has called certain geometers' attention from various points of view; for instance, if an Einstein metric is proved to exist on a compact simply connected 3-manifold then the Poincaré conjecture for the 3-sphere is answered affirmatively (see e. g. [1]). The variational problem arises from the characterization of Einstein metrics in the following theorem.

**THEOREM.** *Let  $M$  be an  $n$ -dimensional compact orientable manifold with a fixed volume element  $\Omega$  (or an  $SL(n, \mathbf{R})$ -structure  $P$ ). And let  $\mathcal{G}$  be the family of all Riemannian metrics with  $\Omega$  on  $M$  (or all  $SO(n)$ -structures contained in  $P$ ). Then a Riemannian metric  $g_0$  in  $\mathcal{G}$  is Einstein if and only if the function  $I = I(g) = \int_M R\Omega$  on  $\mathcal{G}$  attains a critical value at  $g_0$ , where  $R$  is the scalar curvature of  $g$ .*

Before the proof some comments will be adequate. An  $SL(n, \mathbf{R})$ -structure is essentially unique on  $M$  [2].  $I$  attains its critical value at  $g_0$  by definition if one has  $D(I(g(t))) = g_0$  at  $t=0$ ,  $D = d/dt$ , for any differentiable one-parameter family  $\{g(t)\}$  with  $g(0) = g_0$  of Riemannian metrics in  $\mathcal{G}$ . The theorem is trivial when  $n=2$ , since  $I$  is then a constant by the Gauss-Bonnet formula.

Now the proof is given by a straightforward tensor calculus. We put  $a = Dg(t)$ . Such an  $a = (a_{ij})$  is characterized as a symmetric covariant tensor field of degree 2 whose "trace"  $a_a^a = g^{ij}a_{ij}$  vanishes identically due to the assumption on the volume element. It is easy to obtain  $DR_{ij} = \nabla_a D\left\{ \begin{smallmatrix} a \\ i \ j \end{smallmatrix} \right\}$  by noting  $D\left\{ \begin{smallmatrix} a \\ a \ j \end{smallmatrix} \right\} = 0$ , so that we have  $DI(g) = D\int_M R\Omega = \int_M (DR)\Omega = \int_M (g^{ab}DR_{ab} + R_{ab}Dg^{ab})\Omega = \int_M (\nabla_a g^{bc}D\left\{ \begin{smallmatrix} a \\ b \ c \end{smallmatrix} \right\} - R_{ab}g^{ab})\Omega = -\int_M R_{ab}a^{ab}\Omega$ , since the second integrand in the third integral is the divergence of the vector field  $(v^i) = (g^{bc}D\left\{ \begin{smallmatrix} i \\ b \ c \end{smallmatrix} \right\})$ . Thus  $DI(g)$  vanishes if and only if  $R_{ab}a^{ab}$  vanishes everywhere on  $M$ . This occurs when and only when  $(R_{ab})$  is a scalar multiple of  $g$ . The theorem is proved.