

Linear differential systems with singularities and an application to transitive Lie algebras

By Tadashi NAGANO*

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Introduction

In this note we will first define linear differential systems *with* singularities, and then give a sufficient condition for their integrability (Theorem 1 below), similar to Frobenius' theorem. As an application we will prove that a compact manifold M is completely determined by the Lie algebra $L(M)$ of all analytic vector fields on M along with an isotropy subalgebra of $L(M)$ (Theorem 2). On this regard we recall that Myers [4] proved that M is completely determined by the ring $F(M)$ of all analytic functions on M .

We shall always be in the analytic category. The Lie algebra $L(M)$ of the vector fields is a module over the function ring $F(M)$.

DEFINITION. A linear differential system on M is an $F(M)$ -submodule of $L(M)$.

This notion is a generalization of the usual linear differential system (without singularities), i. e., a vector subbundle of the tangent bundle $T(M)$ (indeed any real analytic vector bundle has sufficient ample sections, [5]), or a "distribution" as Chevalley calls [2]. A vector subspace L of $L(M)$ over the reals \mathbf{R} generates a unique $F(M)$ -module L^F . We shall understand L^F under the linear differential system of L . Given a subspace L of $L(M)$ and a point x of M , we put $L(x) = \{u(x) \mid u \in L\}$ and $L_x = \{u \in L \mid u(x) = 0\}$ ($0 \rightarrow L_x \rightarrow L \rightarrow L(x) \rightarrow 0$ is exact). $L(x)$ is a subspace of the tangent space $T_x(M)$ to M at x , which we call *the integral element* of L at x . An *integral manifold* N of L is by definition a connected submanifold of M such that each tangent space to N is an integral element of L ; $T_x(N) = L(x)$, $x \in N$. The linear differential system L^F of L has the same integral elements and integral manifolds as L . If L is a Lie subalgebra of $L(M)$, then so is L^F and L_x is a subalgebra of L , which we call *the isotropy subalgebra* of L at x .

THEOREM 1. If L is a Lie subalgebra of $L(M)$, then M has a unique partition $\mathfrak{N} = \{N\}$ by integral manifolds N of L . (That is, M is the disjoint union

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