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## ON THE TANGENT SPHERE BUNDLE OF A 2-SPHERE

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**Introduction.** Let  $S^2$  be the unit sphere in a Euclidean space  $E^3$  with the induced metric  $g$ . Then, the set of all unit tangent vectors  $T_1(S^2)$ with the natural topology is the total space of the tangent sphere bundle  $p: T_1(S^2) \to S^2$ .  $T_1(S^2)$  has a natural Riemannian metric. In this paper, we prove first that  $T_1(S^2)$  with this metric is isometric with the elliptic space of constant curvature 1/4 (Theorem 1). Then, we give two proofs of a theorem which characterizes each geodesic on  $T_1(S^2)$  as a vector field along a circle in *S<sup>2</sup>* (Theorem 2 and §4). Finally, we give a theorem on the set of tangent vectors of a one parameter family of circles, the set corresponds to a Clifford surface in  $T<sub>1</sub>(S<sup>2</sup>)$  regarded as an elliptic space (Theorem 4).

## 1.  $T_1(S^2)$  as a Riemannian manifold. First we shall show

LEMMA 1. ) *is diffeomorphic with the real projective space* P<sup>3</sup> .

PROOF. For  $y \in T_1(S^2)$ , we consider the unit vector  $e_1(y)$  which issues from the center O of  $S^2$  and ends at the point  $p(y)$ . Then, the map  $f(x) \rightarrow \text{SO}(3)$  defined by  $y \rightarrow (e_1(y), e_2(y), e_1(y) \times e_2(y))$ , where  $e_2(y) \equiv y$ and  $\times$  means vector product in  $E^3$ , is a diffeomorphism. On the other hand, it is well known that  $SO(3)$  is diffeomorphic with  $P<sup>3</sup>$  (cf. for ex ample [3] p. 115). Hence,  $T_1(S^2)$  is diffeomorphic with  $P^3$ .

Now, let *U* be an arbitrary coordinate neighborhood with local coordi nates  $x^a$ (*a*, *b*, *c* = 1, 2) and  $y^a$  be components of a tangent vector *y* in *U* with respect to the natural frame  $\partial/\partial x^a$ . Then,  $p^{-1}(U)$  gives a coordinate neighborhood of  $T_1(S^2)$  with local coordinates  $(x^a, y^a)$ . By virtue of the induced metric  $g$  on  $S^2$  in  $E^3$ , the natural Riemannian metric  $\hat{g}$  on  $T_1(S^2)$ is given by the following line element:

(1.1) 
$$
d\sigma^2 = g_{\iota\iota}(x)dx^{\iota}dx^{\iota} + g_{\iota\iota}(x)\delta y^{\iota}\delta y^{\iota},
$$

([2]) where we have put

(1.2) 
$$
g_{\nu\sigma}(x)y^{\nu}y^{\sigma}=1, \qquad \delta y^{\nu}=dy^{\nu}+\begin{Bmatrix}b\\ef\end{Bmatrix}y^{\sigma}dx^{\sigma}.
$$

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