

GLOBAL ASYMPTOTIC STABILITY IN A PERIODIC INTEGRODIFFERENTIAL SYSTEM

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A set of easily verifiable sufficient conditions are derived for the existence of a globally stable periodic solution in a system of nonlinear Volterra integrodifferential equations with periodic coefficients.

1. Introduction. The purpose of this article is to derive a set of "easily verifiable" sufficient conditions for the existence of a globally asymptotically stable strictly positive (componentwise) periodic solution of the integrodifferential system

$$(1.1) \quad \frac{dx_i(t)}{dt} = x_i(t) \left\{ b_i(t) - a_{ii}(t)x_i(t) - \sum_{\substack{j=1 \\ j \neq i}}^n a_{ij}(t) \int_{-\infty}^t K_{ij}(t-u)x_j(u)du \right\},$$

$$i = 1, 2, \dots, n; t > t_0; t_0 \in (-\infty, \infty)$$

where b_i, a_{ij} ($i, j = 1, 2, \dots, n$) are continuous, positive periodic functions with a common period ω and $K_{ij}: [0, \infty) \rightarrow [0, \infty)$, ($i, j = 1, 2, \dots, n; i \neq j$) denote delay kernel about which more will be said below. In mathematical ecology (1.1) denotes a model of the dynamics of an n -species system in which each individual competes with all others of the system for a common pool of resources and the interspecific competition involves a time delay extending over the entire past as typified by the delay kernels K_{ij} in (1.1). The assumption of periodicity of the parameters b_i, a_{ij} ($i, j = 1, 2, \dots, n$) is a way of incorporating the periodicity of the environment (e.g. seasonal effects of weather, food supplies, mating habits etc.). We will need the following preparation.

LEMMA 1.1. *Assume that the delay kernels K_{ij} ($i, j = 1, 2, \dots, n; i \neq j$) are piecewise (locally) continuous such that the series $\sum_{r=0}^{\infty} K_{ij}(u + rw)$ converges uniformly with respect to u on $[0, \omega]$. Then any ω -periodic solution of (1.1) is also an ω -periodic solution of*

$$(1.2) \quad \frac{dx_i(t)}{dt} = x_i(t) \left\{ b_i(t) - a_{ii}(t)x_i(t) - \sum_{\substack{j=1 \\ j \neq i}}^n a_{ij}(t) \int_{t-\omega}^t H_{ij}(t-u)x_j(u)du \right\},$$

$$i = 1, 2, \dots, n,$$