## Generalizations of bounded variation for  $1 \le p \le \infty$  and  $k \ge 1$ .

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## 1. Definitions and Notations.

 All functions to be considered will be defined on a finite interval [a,b] and may take real or complex values.

We denote by p any real number such that  $1 \le p < \infty$ , and by k any positive integer.

If  $a \le x_0 < x_1 < \ldots < x_n \le b$ , the sequence  $(x_i)$ ,  $i = 1, 2, \ldots, n$ , will be called a subdivision of [a,b].

The first divided difference  $[F(x_1) - F(x_0)]/(x_1 - x_0)$  is denoted by  $Q_1(F; x_0, x_1)$  and the k-th order divided difference over the points  $x_0, x_1, \ldots, x_k$  is defined inductively by

$$
Q_{k}(F; x_{0}, x_{1},..., x_{k}) = (x_{k} - x_{0})^{-1}[Q_{k-1}(F; x_{1},..., x_{k}) - Q_{k-1}(F; x_{0},..., x_{k-1})].
$$

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Then  $Q_k(F; x_0, x_1, ..., x_k)$  may be written as

$$
\sum_{i=0}^{k} \frac{F(x_i)}{\prod_{j\neq i} (x_i - x_j)},
$$

see [5].

For h > 0, the first forward difference  $F(x+h) - F(x)$  is denoted by  $\Delta_h F(x)$  and, for all  $k \ge 2$ ,  $\Delta_h^{k}F(x)$  is defined inductively by  $\Delta_h(\Delta_h^{k-1}F(x))$ . It admits the identity

$$
\Delta_h^{k}F(x) = k! h^{k}Q_k(F; x, x+h,..., x+kh)
$$

For any given variation V, the set of functions for which this variation is finite will be