

A NOTE ON STRONG HOMOLOGY OF INVERSE SYSTEMS

By

Sibe MARDEŠIĆ

1. Introduction.

Ju. T. Lisica and the author have defined in [4] strong homology groups $H_p(\mathbf{X}; G)$ of inverse systems of spaces $\mathbf{X} = (X_\lambda, p_{\lambda\lambda'}, A)$ over directed cofinite sets A (every element $\lambda \in A$ has only finitely many predecessors). It was shown in [5] that these groups are functors on the coherent prohomotopy category CPHTop , introduced in [2] and [3]. The notion of strong or Steenrod homology $H_p^s(\mathbf{X}; G)$ of an arbitrary space X was then defined [1], [6] and shown to be a functor on the strong shape category SSh [2], [3]. The procedure consisted in choosing a cofinite ANR-resolution $p: X \rightarrow \mathbf{X}$ of X ([7], [8], [9]) and of defining $H_p^s(\mathbf{X}; G)$ as $H_p(\mathbf{X}; G)$. That the group $H_p^s(\mathbf{X}; G)$ does not depend on the choice of the resolution is a consequence of the following factorization theorem ([3], Theorem II.2.3). If $p: X \rightarrow \mathbf{X}$ is a resolution and $f: X \rightarrow Y$ is a coherent map into a cofinite ANR-system, then there exists a unique coherent homotopy class of coherent maps $g: \mathbf{X} \rightarrow Y$ such that gp and f are coherently homotopic.

The definition of composition in CPHTop and the proof of the factorization theorem essentially used the assumption that the index sets A be cofinite. On the other hand, the construction of the homology groups $H_p(\mathbf{X}; G)$ did not require this assumption. Therefore, it remained unclear whether one can use also non-cofinite ANR-resolutions to determine the homology groups $H_p^s(\mathbf{X}; G)$ of the space X . To prove that this is indeed the case is the main purpose of this paper. Such an information can prove useful in situations where a non-cofinite ANR-resolution naturally arises.

The main idea of the proof is to replace a given ANR-resolution $p: X \rightarrow \mathbf{X}$ by a cofinite ANR-resolution $p^*: X \rightarrow \mathbf{X}^*$ using the “trick” described in ([9], Theorem I, 1.2). What remains to be done is to exhibit a natural isomorphism $u_*: H_p(\mathbf{X}; G) \rightarrow H_p(\mathbf{X}^*; G)$. The correct formula for u_* is easily found. However, the formula for the inverse v_* of u_* is less obvious. Even more complicated is the verification of the two equalities $u_*v_* = 1$, $v_*u_* = 1$.

In order to simplify notations throughout the paper we omit the coefficient groups G , although all results hold for an arbitrary G .