

# A note on minimal submanifolds in Riemannian manifolds

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In this note we shall prove the following: Let  $\bar{M}^{n+p}$  be a Riemannian manifold of constant curvature  $\bar{c}$ , and let  $M^n$  be a minimal submanifold in  $\bar{M}$  of constant curvature  $c$ . Then either  $M$  is totally geodesic, i.e.  $\bar{c}=c$ , or  $\bar{c} \geq (2p-n+1)c/(p-n+1)$ , in the latter case the equality arising only when  $\bar{c} > 0$ . Our method is based on the Simons' type formula which has been given by Simons [4].

On the other hand, we shall study the Laplacian of the Ricci operator of a minimal submanifold of codimension 1 in a Riemannian manifold of constant curvature and give some inequality. And combining the theorems of Lawson [2], we shall prove some theorems for compact minimal hypersurfaces in a unit sphere.

## 1. Preliminaries

In this section we shall summarize the basic formulas for submanifolds in Riemannian manifolds.

Let  $\bar{M}$  be a Riemannian manifold of dimension  $n+p$ , and let  $M$  be a submanifold of  $\bar{M}$  of dimension  $n$ . Let  $\langle, \rangle$  be the metric tensor field of  $\bar{M}$  as well as the metric induced on  $M$ . We denote by  $\bar{\nabla}$  the covariant differentiation in  $\bar{M}$  and by  $\nabla$  the covariant differentiation in  $M$  determined by the induced metric on  $M$ . Then the Gauss-Weingarten formulas are given by

$$\begin{aligned}\bar{\nabla}_X Y &= \nabla_X Y + B(X, Y), & X, Y \in \mathfrak{X}(M), \\ \bar{\nabla}_X N &= -A^N(X) + D_X N, & X \in \mathfrak{X}(M), \quad N \in \mathfrak{X}(M)^\perp\end{aligned}$$

Where  $D$  is the linear connection in the normal bundle  $T(M)^\perp$ . We call  $A$  and  $B$  the second fundamental form of  $M$  and they satisfy  $\langle B(X, Y), N \rangle = \langle A^N(X), Y \rangle$ . The Riemannian curvature tensors of  $\bar{M}$  and  $M$  will be denoted by  $\bar{R}$  and  $R$  respectively. From the Gauss-Weingarten formulas, we have

$$\bar{R}_{X,Y}Z = R_{X,Y}Z - A^{B(Y,Z)}(X) + A^{B(X,Z)}(Y) + (\bar{\nabla}_X B)(Y, Z) - (\bar{\nabla}_Y B)(X, Z),$$

where  $\bar{\nabla}$  denotes the covariant differentiation for  $B$ . And we obtain the