Generalized Minkowski formulas for closed hypersurfaces in a Riemannian manifold

Dedicated to Professor Yoshie Katsurada on her Sixtieth Birthday

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Introduction.

Our starting point is the following well known formula for an ovaloid F in an Euclidean space E^3 of three dimensions:

(0.1)
$$\iint_{\mathbb{F}} (Kp + H) dA = 0,$$

where H and K are the mean curvature and the Gauss curvature at a point P of F, p denotes the oriented distance from a fixed point 0 in E^3 to the tangent space of F at P and dA is the area element of F at P. For convex hypersurfaces, these formulas have been obtained by H. Minkowski for m=2 [11]¹⁾ and by T. Kubota for a general m [9] (cf. also [2], p. 64).

As a generalization of this formula for a closed orientable hypersurface, C. C. Hsiung derived the following integral formulas of Minkowski type which are valid in an Euclidean space E^{m+1} [4].

THEOREM A (C. C. Hsiung) Let V^m be a closed orientable hypersurface twice differentiably imbedded in an Euclidean space E^{m+1} of m+1 (≥ 3) dimensions, then

(0.2)
$$\int_{V^m} H_{\nu+1} p \, dA + \int_{V^m} H_{\nu} \, dA = 0 \quad for \quad \nu = 0, 1, \cdots, m-1,$$

where $H_0=1$, $H_{\nu}(1 \leq \nu \leq m)$ be the ν -th mean curvature of V^m at P, p denotes the oriented distance from a fixed point 0 in E^{m+1} to the tangent hyperplane of V^m at P, and dA be the area element of V^m at P.

Extension of this formulas in a Riemannian manifold R^{m+1} has been established by Y. Katsurada [5] [6]. Main result for a hypersurface V^m in a Riemannian manifold is as follows:

THEOREM B (Y. Katsurada) Let V^m be a closed orientable hypersurface of class C^3 imbedded in an (m+1)-dimensional Riemannian manifold R^{m+1} which admits an infinitesimal point transformation, then

¹⁾ Numbers in brackets refer to the references at the end of the paper.