Global rigidity of compact classical Lie groups

Dedicated to Professor Nobuo Shimada on his 60-th birthday

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Introduction.

The subject we treat in the present paper is the problem of global rigidity of compact classical Lie groups as Riemannian manifolds imbedded isometrically in the spaces of matrices.

Let F be one of the fields R, C and Q, where we mean by R, C and Q the field of real numbers, the field of complex numbers and the field of quaternions. We denote by G(n, F) the compact classical Lie group SO(n), U(n) or Sp(n) according as F=R, C or Q. Let M(n, F) be the space of all $n \times n$ matrices over F. Then there can be defined a euclidean inner product in M(n, F) invariant under left and right multiplications of matrices contained in G(n, F). With this euclidean inner product M(n, F) may be regarded as a real euclidean space of dimension $n^2 \cdot \dim_R F$. Then the induced metric on the submanifold G=G(n, F) in M(n, F) defines a Riemannian metric on G invariant under left and right actions of G on itself. The focus of this paper is the problem of global rigidity of the inclusion map of the Riemannian manifold G=G(n, F) into M(n, F), which is an isometric imbedding.

Lef \mathbf{f} be an isometric immersion of a Riemannain manifold M into the N-dimensional euclidean space \mathbf{R}^N . In his paper [9], N. Tanaka showed that there is a linear differential operator L associated with \mathbf{f} whose kernel is naturally isomorphic with the space of infinitesimal isometric deformations of \mathbf{f} . He introduced the notion of elliptic isometric immersions and then established the global rigidity theorem for elliptic isometric immersions : Assume that an isometric immersion $\mathbf{f}: M \to \mathbf{R}^N$ satisfies the following conditions: i) M is compact; ii) \mathbf{f} is elliptic; iii) \mathbf{f} is globally infinitesimally rigid, i. e., dim $Ker \ L = \frac{1}{2}N(N+1)$. Then if two immersions \mathbf{f}_1 and \mathbf{f}_2 of M into \mathbf{R}^N lie both near to \mathbf{f} with respect to the C^3 -topology, and if they induce the same Riemannian metric, then there exists a unique euclidean transformation a of \mathbf{R}^N such that $\mathbf{f}_2 = a\mathbf{f}_1$.

In the present paper we prove the following fact : Assume that G is one