

Remarks on the formula for the curvature

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To Professor Noboru Tanaka on his sixtieth birthday

(Received November 22, 1990)

Let $\omega^1, \dots, \omega^n$ be a base of 1-forms on a manifold M . Then a Riemann metric, say g , on M has an expression

$$(1) \quad g = g_{jk} \omega^j \omega^k.$$

Where $g = (g_{jk})$ is a $n \times n$ matrix valued function on M . We denote by $\langle X, Y \rangle_g$ the inner product of tangent vectors X, Y with a common source. We set

$$(2) \quad \xi = \omega(X), \quad \eta = \omega(Y)$$

where ω denotes the \mathbf{R}^n -valued 1-form $(\omega^1, \dots, \omega^n)$. We set $\langle \xi, \eta \rangle_g = g_{jk} \xi^j \eta^k$ so that

$$(3) \quad \langle X, Y \rangle_g = \langle \xi, \eta \rangle_g.$$

Write

$$(4) \quad d\omega^j = \frac{1}{2} \beta_{kl}^j \omega^k \wedge \omega^l, \quad \beta_{kl}^j + \beta_{lk}^j = 0.$$

Define a linear map $\beta : \mathbf{R}^n \rightarrow \text{Hom}(\mathbf{R}^n, \mathbf{R}^n)$ by

$$(5) \quad (\beta(\xi)\eta)^j = \beta_{kl}^j \xi^k \eta^l.$$

Actually β should be regarded as a map of M into $\text{Hom}(\mathbf{R}^n, \text{Hom}(\mathbf{R}^n, \mathbf{R}^n))$. Then the formula (4) can be rewritten as

$$(6) \quad (d\omega)(X, Y) = \beta(\xi)\eta.$$

We wrote down in [3] the formula for the sectional curvature of g which is expressed by means of g_{jk} and β . In this paper we write down the formula for the curvature tensor. We then write down the O'Neill's formula [4] for the submersion using only g and β .

When we set

$$(7) \quad R(X, Y) = \nabla_X \nabla_Y - \nabla_Y \nabla_X - \nabla_{[X, Y]},$$

the curvature tensor is given by