Holomorphic Motions of Hyperbolic Sets

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0. Introduction

Let *M* be a complex Hermitian manifold and $\{f_a\}_{a \in \mathbf{D}}$ a holomorphic family of endomorphisms of *M*, where **D** is the unit disk. This means that the map $\mathbf{D} \times M \rightarrow M$, defined by $(a, x) \rightarrow f_a(x)$, is holomorphic. Suppose that $f = f_0$ has a compact surjectively invariant subset *K*, that is, f(K) = K. For example, *K* could be a fixed point or a periodic orbit, but also a more complicated set such as the Julia set of a rational function. We may then ask if *K* is persistent under the perturbation f_a of the map *f*. For instance, if *K* is a fixed point of *f*, then we ask if f_a has a fixed point K_a near *K* for *a* small enough. A sufficient (albeit not necessary) condition for this is that the fixed point *K* be hyperbolic, meaning that the derivative of *f* at *K* has no eigenvalue of modulus 1.

There is a natural notion of hyperbolicity for general sets K. Let us first consider the case when the maps f_a are diffeomorphisms. The precise definition (which can be found e.g. in [R]) will not be stated here, but it says that the tangent bundle over K splits continuously into two invariant subbundles on which the derivative of f is expanding and contracting, respectively.

One basic result in real dynamics is that hyperbolic sets are persistent under perturbations in the map f (see [R]). In our case this means that if a is small enough, then f_a has a hyperbolic set K_a close to K, and there exists a homeomorphism h_a close to the identity conjugating $f|_K$ to $f_a|_{K_a}$.

If K is a hyperbolic fixed point, then it follows from the implicit function theorem that the fixed point K_a of f_a depends holomorphically on a. The natural generalization of this to more general sets K is the notion of a holomorphic motion, the definition of which is given in Section 1.

THEOREM A. Let $\{f_a\}_{a \in \mathbf{D}}$ be a holomorphic family of diffeomorphisms of a Hermitian manifold M parameterized by the unit disk \mathbf{D} . Suppose that $f = f_0$ has a hyperbolic subset K. Then K moves holomorphically with the parameter a at a =0. More precisely, there exist r > 0 and a holomorphic motion $h: \mathbf{D}_r \times K \to M$ such that, for each $a \in \mathbf{D}_r$:

(1) $K_a := h(a, K)$ is a hyperbolic subset for f_a ;

(2) the map $h_a := h(a, \cdot) : K \to K_a$ is a homeomorphism and $f_a \circ h_a = h_a \circ f$.

Received March 17, 1997.

Partially supported by a grant from NFR (Swedish Natural Science Research Council) Michigan Math. J. 45 (1998).