

RIEMANNIAN MANIFOLDS OF CONSTANT NULLITY

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1. INTRODUCTION

Let m be a point of a (C^∞) Riemannian manifold M , and let M_m denote the tangent space to M at m . A vector $z \in M_m$ is called a *nullity vector* if $R_{xy}z = 0$ for all $x, y \in M_m$, where R_{xy} denotes the curvature transformation associated with the vectors x and y . The *nullity* $\mu(m)$ is the dimension of the space of nullity vectors at m . The purpose of this paper is to prove the following theorem concerning Riemannian manifolds with constant positive nullity.

THEOREM (*). *Let M^n be a complete, connected, and simply connected C^∞ Riemannian manifold of constant positive nullity $\mu \leq n - 3$, and suppose that one of the following conditions is satisfied:*

- (1*) *$n - \mu$ is odd, and the sectional curvatures of all planes orthogonal to the spaces of nullity vectors are nonzero;*
- (2*) *the restriction of the curvature tensor to the space of bivectors generated by vectors orthogonal to the space of nullity vectors at each $m \in M$ is a positive or negative definite bilinear form on this space.*

Then M^n is a direct metric product, $M^n = N^\mu \times C^{n-\mu}$, where N^μ is complete and flat, and $C^{n-\mu}$ is complete.

Nullity was defined by Chern and Kuiper [2]. Theorem (*) is a C^∞ intrinsic-manifold analogue of a theorem due to Hartman [4], who assumed the existence of an immersion.

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2. PRELIMINARIES: THE NULLITY VARIETIES AND CONULLITY OPERATORS

Throughout this paper, M will denote an n -dimensional differentiable Riemannian manifold (of class C^∞). The frame bundle, solder form, connexion form, and curvature form of M will be denoted respectively by $\overline{F}(M)$, $\overline{\theta}$, $\overline{\omega}$, and $\overline{\Omega}$ [1]. The natural projection of $\overline{F}(M)$ onto M will be denoted by $\overline{\pi}$. We shall use the index convention in which a repeated index means summation through all possible values of the index. The subspace N_m of M_m generated by the nullity vectors at m is called the *nullity space* at m . A *conullity vector* is a vector orthogonal to N_m , and the subspace C_m of conullity vectors at m is called the *conullity space* at m .

In this section we shall suppose only that the nullity is positive and constant in some open set of M . With this assumption, we can find (locally) the flat factor of the

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