

SMOOTH S^1 -MANIFOLDS IN THE HOMOTOPY TYPE OF $\mathbb{C}P^3$

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0. INTRODUCTION

Four years ago T. Petrie [6] conjectured that *if X is a closed, smooth, $2n$ -dimensional homotopy $\mathbb{C}P^n$ that admits a nontrivial action of S^1 , and if $h: X \rightarrow \mathbb{C}P^n$ is a homotopy equivalence, then h preserves Pontrjagin classes.*

In the present paper we prove the conjecture for the case $n = 3$:

THEOREM 0.1. *Let X be a closed, smooth S^1 -manifold such that $X^{S^1} \neq X$, and let $f: X \rightarrow \mathbb{C}P^3$ be a homotopy equivalence. Then*

$$f^* \hat{\mathcal{A}}(\mathbb{C}P^3) = \hat{\mathcal{A}}(|X|),$$

where $|X|$ denotes the underlying smooth manifold of X ,

$$\hat{\mathcal{A}}(|X|) = (x_i/2) (\sinh x_i/2)^{-1} \in H^*(|X|; \mathbb{Q}),$$

and the elementary symmetric functions of the x_i^2 give the Pontrjagin classes of $|X|$. In particular, f preserves the Pontrjagin classes of $|X|$.

Furthermore, a theorem of D. Montgomery and C. T. Yang [5] implies that there is a bijective application

$$P: \mathbb{Z} \rightarrow \{\text{diffeomorphism classes of smooth manifolds homotopy equivalent to } \mathbb{C}P^3\}$$

such that, for every $\alpha \in \mathbb{Z}$,

$$p_1(P(\alpha)) = (24\alpha + 4)z^2,$$

where p_1 is the first Pontrjagin class and z is a generator of $H^2(\mathbb{C}P^3)$.

THEOREM 0.2. *A closed smooth S^1 manifold X , homotopy-equivalent to $\mathbb{C}P^3$ and such that $X^{S^1} \neq X$, is diffeomorphic to $\mathbb{C}P^3$.*

Theorem 0.1 follows from Theorem 2.1, as indicated subsequently. This is intimately related to the proof of Theorem 1.3, which completely determines the rational torsion-free equivariant K-theory of X .

1. EQUIVARIANT COHOMOLOGIES

Let G be a compact abelian Lie group that is topologically cyclic, in other words, such that there exists a dense generator g in G . Let $R(G)$ be the representation ring of G . Let Z be a closed, smooth G -manifold such that $Z^G \neq Z$, and let $\hat{K}_G^*(Z)$ be the quotient of the equivariant K-theory $K_G^*(Z)$ by its $R(G)$ -torsion.

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