

FAMILY K OF THE NON-LEWIS MODAL SYSTEMS

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In [6], p. 109, a regular modal formula α is defined as a modal formula which after deleting the modal functors L and M , if they occur in α , and after replacing the modal functors for more than one argument, if they occur in α , by the corresponding classical functors, throughout α , this formula becomes a thesis of the bi-valued propositional calculus. If a regular modal formula α is such that its addition as a new axiom to S5 reduces such extension of the latter system to the classical propositional calculus, I say that α is non-Lewis modal formula. Correspondingly, the modal systems which are irreducible to the classical propositional calculus and which are obtained by the addition of one or more non-Lewis modal formulas to the proper subsystems of S5 will be called here the non-Lewis modal systems. Such a system, for example, is constructed by McKinsey, cf. [2], by adding to S4 the new axiom

$$K1 \quad \mathcal{C}KLMpMLqMKpq$$

which, clearly, is non-Lewis modal formula. As I have proved in [7], pp. 77-78, in this system, which is called by McKinsey S4.1, but which I call more conveniently system K1, axiom K1 can be substituted equivalently by several other formulas, as, e.g., by

$$K2 \quad \mathcal{C}LMpMLp$$

or by

$$K4 \quad LMLCpLp$$

This fact will be used later.

In this paper I shall present some investigations, which are far from being complete, concerning certain family K of the non-Lewis modal systems. I define this family K as a class of such and only such modal systems that each of them satisfies the following three conditions:

- 1) it is a proper normal extension of S4,
- 2) it is irreducible to the classical propositional calculus,
- 3) it contains as its axiom or its consequence formula K2.