

## Varying Modal Theories

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**Abstract** The notion of modal theory is extended by accepting the idea that axioms and language itself vary over a plurality of possible worlds. Inference rules involving different worlds are introduced and completeness is proved by using a notion of 'ugly diagram', which is a graphical means of detecting when a family of modal theories has no model.

Models of modal theories are indexed by a plurality of possible worlds equipped with a binary accessibility relation. It seems natural to extend the notion of modal theory by accepting that axioms, and even language itself, vary over a similar structure.

Here is an argument which supports our point of view, as opposed to already existing work on modal model theory (e.g. [1]). Consider a language  $L$  for a modal theory in the usual sense ( $L$  is constant). Consider a modal structure  $M$ : it varies with the elements of a set  $I$ . We may define the "theory of  $M$ " as the set of sentences satisfied in the "actual world", but we could as well consider for each  $i \in I$  the set  $T_i$  of sentences satisfied by  $M_i$  in  $L$ . A further step consists in the adjunction for each  $i \in I$  of constants  $a_i$  for  $a_i \in M(i)$ , giving rise to languages  $L_i = L \cup \{a_i \mid a_i \in M(i)\}$  varying over the set  $I$  of indices.

The aim of this paper is to answer the following preliminary question: when is a family of usual modal theories the theory (in our sense) of a model?

To be specific, we will deal with the system  $K$  in the main body of the text but discuss in the last section the extension to other systems.

In the first section, we propose a notion of ( $K$ -) theory  $(T_i)_{i \in I}$  varying over a structure  $\langle I, R \rangle$ . Structures and models for these theories are essentially the usual ones (see e.g. [3]), but we note that models validate rules of deduction involving different indices. To take a simple example: if a sentence  $\Box\varphi$  is satisfied in  $i$  and if  $iRj$ , then  $\varphi$  is satisfied in  $j$ .

In the second section we describe a notion of consistency. It is clearly necessary but not sufficient to say that for each  $i \in I$ ,  $T_i$  is  $K$ -consistent; if  $T_i$  proves  $\Box\varphi$  in  $K$ , if  $iRj$  and  $T_j$  proves  $\neg\varphi$  in  $K$ , then  $T = (T_i)_{i \in I}$  has no model. It is