

# NEUTRAL GEOMETRY AND THE GAUSS-BONNET THEOREM FOR TWO-DIMENSIONAL PSEUDO-RIEMANNIAN MANIFOLDS

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**1. Introduction.** The Gauss-Bonnet theorem was first extended to pseudo-Riemannian manifolds by Avez [1] and Chern [3]. These authors produced a global Gauss-Bonnet theorem. For example, Chern [3] considers oriented pseudo-Riemannian vector bundles of even rank over compact manifolds and interprets the Gauss-Bonnet formula as the assertion that the relevant curvature form (that which appears as the integrand in the Gauss-Bonnet formula) equals the Euler class of the bundle. This is now the standard abstract formulation of the generalized Gauss-Bonnet theorem, though usually stated only for the Riemannian case (cf., e.g., Milnor and Stasheff [7]). For the tangent bundle of a compact, oriented, pseudo-Riemannian manifold, this statement reduces to the usual Gauss-Bonnet result.

The obvious elegance of this global Gauss-Bonnet-Chern theorem does not preclude interest in a pseudo-Riemannian version of the classical Gauss-Bonnet formula for a two-dimensional domain  $D$  with piecewise smooth boundary  $\Gamma$ :

$$(1.1) \quad \int_D K dV + \int_\Gamma k_g ds + \sum \theta_{\text{exterior}} = 2\pi$$

where  $K$  is the Gaussian curvature of some metric on  $D$ ,  $k_g$  the geodesic curvature, and  $\theta_{\text{exterior}}$  the exterior angle at a nonsmooth point of  $\Gamma$ . It is fairly straightforward to carry over the differential-geometric aspects of a proof of this result to the pseudo-Riemannian context. The only two-dimensional indefinite signature is Lorentzian, and the essential difference that occur between the Riemannian and Lorentzian versions of the Gauss-Bonnet formula arise from the differences between the corresponding orientation-preserving isometry groups  $\mathbf{SO}(2)$  and  $\mathbf{SO}(1,1)$ . In particular, these groups essentially determine the relevant notion of angle and hence  $\theta_{\text{exterior}}$ .

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