

METRIC TRANSFORMATIONS OF THE REAL LINE

DARYL TINGLEY

1. A metric transformation between two metric (or semi-metric) spaces M_1 and M_2 is defined to be a function f such that for some function $\rho: \mathbf{R}^+ \rightarrow \mathbf{R}^+$, called the scale function associated with f , $\rho(d_1(x, y)) = d_2(f(x), f(y))$, where $x, y \in M$. The set $f(M_1)$ is said to be a metric transform of M_1 . In this paper all metric transforms from the real line in Euclidean n -space are characterized.

The notion of a metric transformation was introduced by Wilson [10] in 1935. In 1938 von-Neumann and Schoenberg [8] characterized all continuous metric transformations of the real line, \mathbf{R} , into Hilbert space. This powerful result shows that the scale functions ρ corresponding to such transformations are those, and only those, functions which satisfy the condition

$$\rho^2(t) = \left(\int_0^\infty \frac{\sin^2 tu}{u^2} d\alpha(u) \right),$$

where α is non-decreasing and $\int_1^\infty u^{-2} d\alpha(u) < \infty$. They also showed that, in order that $f(\mathbf{R})$ be embeddable in \mathbf{E}^n (finite dimensional Hilbert space), it is necessary and sufficient that α increase at only a finite number of points. In this case

$$\rho^2(t) = \sum_1^m A_i^2 \sin^2 k_i t + c^2 t^2,$$

and in a suitable coordinate system,

$$(1) \quad f(t) = (A_1 \cos k_1 t, A_1 \sin k_1 t, \dots, A_m \cos k_m t, A_m \sin k_m t, ct)$$

If $f(\mathbf{R})$ is embeddable in E^n , but not in E^{n-1} , then, for n odd, $2m = n - 1$ and $c \neq 0$, while $2m = n$ and $c = 0$ for n even. As a helix is typical, von-Neumann and Schoenberg refer to continuous metric transforms of \mathbf{R} as screw curves.

Metric transformations, including the von-Neumann and Schoenberg result, have appeared in the literature of late in connection with a method of data analysis known as Multidimensional Scaling. (See [1], [3], [6] and [7]). Here one takes a semi-metric space M_1 and some other metric