## **ON A CRANK-NICOLSON SCHEME FOR NONLINEAR PARABOLIC EQUATIONS**

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**1. Introduction.** In this paper we consider a Crank-Nicolson type scheme for the problem:

(1.1) 
$$
u_t = f(t, x, u, u_x, u_{xx}) \text{ in } (0, T] \times (a, b)
$$

(1.2) 
$$
u(0, x) = \varphi(x), u(t, a) = \varphi_0(t), \text{ and } u(t, b) = \varphi_1(t)
$$

where  $\varphi(a) = \varphi_0(0)$  and  $\varphi(b) = \varphi_1(0)$ .

**In [11],** the author was able to obtain a convergence theorem for a set of finite difference analogues of  $(1.1)$ ,  $(1.2)$  with  $(0, T] \times (a, b)$ replaced by  $[0, T] \times (a, b)$ . For the Crank-Nicolson type scheme included among the methods in [11] a  $O(\Delta t + h^2)$  convergence result was obtained. No method was given for solving the nonlinear system of difference equations.

For the Crank-Nicolson type scheme presented here, three improvements are possible. We obtain  $O((\Delta t)^2 + h^2)$  convergence, we give a convergent iterative scheme for solving the nonlinear system of difference equations, and we obtain our results without assuming that the solution of  $(1.1)$  has continuous derivatives at  $t = 0$ .

Consideration of this iterative procedure yields an existence and uniqueness theorem for the solution of the nonlinear system of difference equations. This existence and uniqueness theorem is a slight improvement over the analogous result in **[11],** in that we obtain it by requiring that  $f(t, x, z, p, r)$  satisfies certain Lipschitz conditions with respect to  $z$ ,  $p$ , and  $r$  whereas in [11], we assumed  $f$  had continuous partial derivatives with respect to *z, p,* and r.

## 2. **Notation and Preliminary Results.** Let

(2.1) 
$$
h = \frac{b-a}{n+1} \text{ and } \Delta t = T/m
$$

where *n* and *m* are positive integers. Also let  $x_i = a + ih$  for  $i = 0, 1$ ,  $\cdots$ ,  $n + 1$  and  $t_i = \overline{j} \Delta t$  for  $j = 0, 1, \dots, m$ .

For the remainder of the paper, we will suppose 2.1 defines a mesh on  $[0, T] \times [a, b]$ , and if  $v(t, x)$  is any function defined on this mesh we denote  $v(t_i, x_i)$  by  $v_{i,i}$ . For any such mesh function, we let

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