

## STOCHASTICALLY PERTURBED DYNAMICAL SYSTEMS

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**1. Introduction.** A variety of natural phenomena have been modeled by stochastic differential equations containing one or more small parameters. Such models allow one to study the effects of random perturbations of small magnitude. When the parameters are set equal to 0, the stochastic effects disappear from the problem; the resulting ordinary differential equations describe the evolution of the unperturbed dynamical system. Examples can be found in the study of wave propagation in random media [17], of noise in electronic systems [19] or in a control system [6]. Yet another class of examples, which we mention in § 6, arises from population genetics models.

For simplicity, we consider only one small positive parameter  $\epsilon$ . The state space of the system being modeled is taken as  $n$ -dimensional  $R^n$ . The state process  $\xi^\epsilon = (\xi_1^\epsilon, \dots, \xi_n^\epsilon)$  is assumed to be a Markov diffusion, with generator  $\mathcal{L}^\epsilon$  the partial differential operator

$$(1.1) \quad \mathcal{L}^\epsilon \psi = \epsilon \operatorname{tr} \alpha \psi_{xx} + \psi_x \cdot f.$$

Here  $\psi$  denotes any function of class  $C^2$  (continuous second order partial derivatives); the functions  $\alpha, f$  are respectively matrix and vector valued:

$$\begin{aligned} \alpha(x) &= (\alpha_{ij}(x)), \quad i, j = 1, \dots, n, \\ f(x) &= (f_1(x), \dots, f_n(x)). \end{aligned}$$

The vector  $\psi_x = (\psi_{x_1}, \dots, \psi_{x_n})$  is the gradient of  $\psi$ , and

$$\operatorname{tr} \alpha \psi_{xx} = \sum_{i,j=1}^n \alpha_{ij} \psi_{x_i x_j}.$$

In fact, we shall take  $\xi^\epsilon$  as the solution of a stochastic differential equation of Ito type (§ 2).

A variety of questions can be asked about the perturbed process  $\xi^\epsilon$ . Which of these has a reasonable answer in a particular instance

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