## BOUNDED COHOMOLOGY AND TOPOLOGICALLY TAME KLEINIAN GROUPS

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The notion of bounded cohomology was introduced by Gromov [5]. The bounded cohomology  $H_b^*(X; \mathbb{R})$  for any topological space X is defined with the subcomplex  $C_b^*(X)$  of the usual cochain complex  $C^*(X)$  consisting of bounded cochains. This cohomology has the advantage of admitting the naturally defined pseudonorm  $|| \cdot ||$ . According to Soma [18], in general, this pseudonorm is not a norm. So, we also consider the quotient space

 $HB^{*}(X; \mathbf{R}) = H_{b}^{*}(X; \mathbf{R}) / \{ [c] \in H_{b}^{*}(X; \mathbf{R}); ||[c]|| = 0 \},\$ 

and denote the element of  $HB^*(X; \mathbb{R})$  corresponding to  $[c] \in H^*_b(X; \mathbb{R})$  by  $[c]_B$ . Note that  $HB^*(X; \mathbb{R})$  is a Banach space with the norm  $|| \cdot ||$ .

The second bounded cohomology of a closed surface of genus g > 1 was studied by Brooks-Series [2], Mitsumatsu [11], and Barge-Ghys [1], and the third by Yoshida [22] and Soma [17]. Here, we will study further the third bounded cohomology and connections with hyperbolic 3-manifolds.

For a torsion-free Kleinian group  $\Gamma$ , the bounded 3-cocycle  $\omega_{\Gamma}$  on the hyperbolic 3-manifold  $M_{\Gamma} = \mathbf{H}^3/\Gamma$  is defined by  $\omega_{\Gamma}(\sigma) = \Omega_{\Gamma}(\operatorname{straight}(\sigma))$  for any singular simplex  $\sigma: \Delta^3 \longrightarrow M_{\Gamma}$ , where  $\Omega_{\Gamma}$  is the volume form on  $M_{\Gamma}$ . In fact, since the volume of any straight simplex is less than the volume  $\mathbf{v}_3$  of a regular ideal simplex  $v_0$  in  $\mathbf{H}^3$ , and since  $v_0$  is well approximated by a usual straight simplex in  $\mathbf{H}^3$ , the norm  $||\omega_{\Gamma}||$  is equal to  $\mathbf{v}_3$ . So, the *fundamental class*  $[\omega_{\Gamma}] \in H_b^3(M_{\Gamma}; \mathbf{R})$  of  $M_{\Gamma}$  has the pseudonorm  $||[\omega_{\Gamma}]|| \leq \mathbf{v}_3$ . In [17], we were mainly concerned with Kleinian groups,  $\Gamma$ , isomorphic to closed surface groups and such that the injectivity radii  $\operatorname{inj}(M_{\Gamma}) = {\operatorname{inj}_{M_{\Gamma}}(x); x \in M_{\Gamma}} > 0$ , in which Minsky's ending lamination theorem [10] played an important role. In particular, this theorem was used effectively to prove rigidity theorems [20, Theorems A and D] for certain hyperbolic 3-manifolds  $M_{\Gamma}$  in terms of the "distance" between the fundamental classes  $[\omega_{\Gamma}]$  with respect to the pseudonorm.

In this paper, we consider the case where  $\Gamma$  are topologically tame Kleinian groups. Our proofs here are based on Canary's results about topologically tame Kleinian groups in [3] and his covering theorem in [4].

THEOREM 1. Suppose that  $\Gamma$  is a topologically tame Kleinian group such that the volume of  $M_{\Gamma}$  is infinite. Then  $[\omega_{\Gamma}] = 0$  in  $H^3_b(M_{\Gamma}; \mathbf{R})$  if and only if  $\Gamma$  is either

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