# PROJECTIVE DIFFERENTIAL INVARIANTS OF A CURVE OF A SURFACE 

By P. O. Bell


#### Abstract

1. Introduction. Let $S_{0}$ denote a general analytic surface in ordinary projective space and let $C$ denote a curve of $S_{0}$ which passes through a general one of its points $x_{0}$. This paper is devoted to the study of (I) the projective curvature and the projective torsion of $C$ at $x_{0}$, (II) the projective first fundamental form of $S_{0}$, and (III) the projective curvature tensor of $S_{0}$. A new geometric characterization of each of the above named invariants is presented. In association with the projective curvature tensor and the projective first fundamental form, the projective total curvature of $S_{0}$ is defined. Upon choosing the $R$-conjugate line to be the Euclidean normal to $S_{0}$ at $x_{0}$ and replacing the projective group by its subgroup of orthogonal transformations, the projective first fundamental form, the projective curvature tensor, and the projective total curvature of $S_{0}$ actually become the corresponding metric quantities. Moreover, if the Fubini fundamental form is replaced by the first fundamental form in the characterization of the projective curvature of $C$, the geodesic curvature of $C$ results. Finally, the covariant points are determined which will be called the $R$-centers of projective principal curvatures of $S_{0}$ at $x_{0}$ and the $R$-center of projective mean curvature of $S_{0}$ at $x_{0}$. Again, these points become the corresponding metric points when the $R$-conjugate line is chosen to be the metric normal to $S_{0}$ at $x_{0}$.


2. Differential invariants of a curve of a surface. Let $S$ be referred to a reference tetrahedron ( $x_{0}, x_{1}, x_{2}, x_{3}$ ) whose first three vertices are defined by the vector equations

$$
x_{0}=x, \quad x_{1}=\frac{\partial x}{\partial u^{1}}, \quad x_{2}=\frac{\partial x}{\partial u^{2}}
$$

the line $l$ joining the points $x_{1}, x_{2}$ being covariantly determined with respect to $S$ at $x$. Let the fourth vertex be a geometrically determined point $x_{3}$. Under an arbitrary transformation of parameters

$$
\begin{equation*}
u^{\alpha}=u^{\alpha}\left(\bar{u}^{1}, \bar{u}^{2}\right) \tag{2.1}
\end{equation*}
$$

the vertices are transformed according to the relations

$$
\bar{x}_{p}\left(\bar{u}^{1}, \bar{u}^{2}\right)=x_{p}, \quad \bar{x}_{\beta}=x_{\alpha} \frac{\partial u^{\alpha}}{\partial \bar{u}^{\beta}} .
$$

Received April 23, 1951.

