NEW GEOMETRICAL CHARACTERIZATIONS OF SOME SPECIAL CONJUGATE NETS

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1. Introduction. Let N_x be a conjugate net with parameters u, v on an analytic proper surface S in ordinary space, and let x_{-1} , x_1 be respectively the ray-points, or Laplace transformed points, of a general point P_x of the surface S with respect to the *v*-curve and the *u*-curve of the conjugate net N_x . As u, v vary the loci of the points x_{-1} , x_1 are two surfaces S_{-1} , S_1 on which the parametric curves form two conjugate nets N_{-1} , N_1 , which are called as usual the minus-first and first Laplace transformed nets of N_x , respectively. The purpose of the present paper is to give new geometrical characterizations of the conjugate net N_x in some special cases by introducing two quadrics, called *the associated quadrics at the point* P_x of the conjugate net N_x , one of which has contact of the second order with the surface S_{-1} at the point x_{-1} and contact of the first order with the surface S_1 at the point x_1 , and the other has similar properties with the roles of u, v interchanged.

2. The associated quadrics. Let N_x be a conjugate net with parameters u, v on an analytic proper surface S in ordinary space. For the sake of convenience we take the conjugate net N_x on the surface S as parametric, so that the projective homogeneous coördinates $x^{(1)}, \dots, x^{(4)}$ of a point P_x on the surface S can be given as analytic functions of the two independent variables u, v by equations of the form

$$(1) x = x(u, v).$$

The four coördinates x and the four coördinates y of the point P_y which is the harmonic conjugate of the point P_x with respect to the foci of the axis of the point P_x satisfy a system of partial differential equations of the form [2; 138]

(2)

$$x_{uu} = px + \alpha x_u + Ly,$$

$$x_{uv} = cx + ax_u + bx_v,$$

$$x_{vv} = qx + \delta x_v + Ny \qquad (LN \neq 0),$$

subscripts indicating partial differentiation and the coefficients being functions of u, v which satisfy certain integrability conditions. It is easy to verify that

(3)
$$y_u = fx - nx_u + sx_v + Ay, \quad y_v = gx + tx_u + nx_v + By,$$

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