THE STABILITY OF SOLUTIONS OF LINEAR DIFFERENTIAL EQUATIONS

By Richard Bellman

1. Introduction. We want to consider differential equations of the form

(1.1)
$$y^{(n)}(x) + P_2(x)y^{(n-2)}(x) + \cdots + P_n(x)y(x) = 0$$
 $(x \ge 0, n = 2, 3, \cdots)$

and prove that under sufficiently small variations of the coefficients $P_k(x)$ the solutions, and their derivatives, will preserve boundedness. We shall estimate the variation between $P_k(x)$ and $Q_k(x)$ by means of

(1.2)
$$a_k(x) = \int_0^x |P_k(x) - Q_k(x)| dx.$$

Levinson [2] considered the case n = 2, with $Q_2(x) \equiv a$, and derived the following theorem:

If x(t) satisfies the differential equation

(1.3)
$$x''(t) + \phi(t)x(t) = 0$$

and

(1.4)
$$\alpha(t) = \int_0^t |\phi(t) - a| dt,$$

then, $a \neq 0$,

(1.5)
$$x(t) = O(\exp(\frac{1}{2}a^{-\frac{1}{2}}\alpha(t))).$$

In particular, if $\alpha(t)$ is bounded, x(t) is bounded. He showed by example that this is a "best possible" result.

Cesari [1] proved the more general theorem:

If the differential equation

(1.6)
$$z^{(n)}(x) + a_1 z^{(n-1)}(x) + \cdots + a_n z(x) = 0,$$

where the a_k are constants, has only bounded solutions, and if

(1.7)
$$\lim_{x \to \infty} f_i(x) = a_i \qquad (j = 1, 2, \dots, n),$$

(1.8)
$$\int_0^\infty |f_i(x) - a_i| dx < \infty,$$

then the differential equation

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