# THE BINARY POLYHEDRAL GROUPS, AND OTHER GENERALIZATIONS OF THE QUATERNION GROUP 

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## 1. Introduction. Hamilton's formulas

$$
i^{2}=j^{2}=k^{2}=i j k=-1
$$

suggest the following definition for the quaternion group:

$$
R^{2}=S^{2}=T^{2}=R S T \neq 1
$$

The natural generalization is

$$
\begin{equation*}
R^{l}=S^{m}=T^{n}=R S T \tag{1.1}
\end{equation*}
$$

Let $\langle l, m, n\rangle$ denote the (largest) group defined by (1.1). This is symmetrical among $l, m, n$ : for cyclic permutation, obviously; and for transposition, by changing $R, S, T$ into $T^{-1}, S^{-1}, R^{-1}$, respectively.

Any two of $R, S, T$ suffice to generate $\langle l, m, n\rangle$. For, if

$$
\begin{equation*}
R^{l}=S^{m}=T^{n}=R S T=Z \tag{1.2}
\end{equation*}
$$

we can substitute $Z T^{-1} S^{-1}$ for $R$, obtaining

$$
\begin{equation*}
S^{m}=T^{n}=Z, \quad(S T)^{l}=Z^{l-1} \tag{1.3}
\end{equation*}
$$

In particular, $\langle 2, m, n\rangle$ is simply defined by

$$
\begin{equation*}
S^{m}=T^{n}=(S T)^{2} \tag{1.4}
\end{equation*}
$$

Another definition for $\langle 2, m, n\rangle$ comes from the observation that $R=S T$. Substituting $S^{-1} R$ for $T$ in (1.1), we obtain $R^{2}=S^{m}=\left(S^{-1} R\right)^{n}$, or, writing $S^{-1}$ for $S$,

$$
\begin{equation*}
R^{2}=S^{-m}=(R S)^{n} \tag{1.5}
\end{equation*}
$$

In particular, $\langle 2,2, m\rangle$ is the same group as $\langle 2,2,-m\rangle$.
The relations (1.4) and (1.5) are reminiscent of Miller's ${ }^{1}$

$$
s_{1}^{m}=s_{2}^{n}, \quad\left(s_{1} s_{2}\right)^{2}=1
$$

and

$$
s_{1}^{2}=s_{2}^{n}, \quad\left(s_{1} s_{2}\right)^{l}=1
$$

but are by no means identical with them.
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${ }^{1}$ G. A. Miller, Generalization of the groups of genus zero, Transactions of the American Mathematical Society, vol. 8(1907), pp. 1-13.

