GEOMETRY OF INTEGRAL SUBMANIFOLDS OF A CONTACT DISTRIBUTION

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1. A differentiable (2n + 1)-dimensional manifold M is said to be a contact manifold if it carries a 1-form η such that $\eta \wedge (d\eta)^n \neq 0$. This condition, roughly speaking, means that the 2n-dimensional "(tangent) subbundle" D defined by $\eta = 0$ is as far from being integrable as possible. In particular, the maximum dimension of an integral submanifold of D is n [3]. However, not much seems to be known about the immersion of such submanifolds into the ambient space, especially from Riemannian point of view. Thus we consider in this paper a normal contact metric (Sasakian) manifold, especially one with constant ϕ -sectional curvature, and study the immersion of its n-dimensional integral submanifolds.

The main result of this paper (Theorem 4.2) is that a compact minimal integral submanifold of a Sasakian space form M is totally geodesic if the square of the length of the second fundamental form is bounded by

$$\frac{n\{n(\tilde{c}+3)+\tilde{c}-1\}}{4(2n-1)}$$

where \tilde{c} is the ϕ -sectional curvature of M. In addition to giving other properties of integral submanifolds, we give examples in Section 5 of totally geodesic and minimal nontotally geodesic integral submanifolds.

2. Let *M* be a contact manifold with contact form η . It is well known that a contact manifold carries an *associated almost contact metric structure* (ϕ, ξ, η, G) where ϕ is a tensor field of type (1, 1), ξ a vector field, and *G* a Riemannian metric satisfying

 $\phi^2 = -I + \xi \otimes \eta, \quad \eta(\xi) = 1, \quad G(\phi X, \phi Y) = G(X, Y) - \eta(X)\eta(Y)$ (2.1) and

$$\Phi(X, Y) = G(X, \phi Y) = d\eta(X, Y).$$
(2.2)

The existence of tensors ϕ , ξ , η , G on a differentiable manifold M satisfying equations (2.1) is equivalent to a reduction of the structural group of the tangent bundle to $U(n) \times 1$ [2].

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