

**PROPERTIES AND FACTORIZATIONS OF MATRICES
DEFINED BY THE OPERATION OF PSEUDO-TRANSPOSITION**

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1. **Introduction.** A matrix $C: n \times n$ (i.e., of n rows and n columns) is (p, q) pseudo-orthogonal if it satisfies the relation

$$(1.1) \quad CJC' = J,$$

where C' is the transpose of C , $J = I_p \dot{+} (-I_q)$, $\dot{+}$ is the direct sum, I_p is the identity matrix of order p , and $p + q = n$. This implies the invariance of the quadratic form $x'Jx$, $x: n \times 1$ under a pseudo-orthogonal transformation. In this sense, a pseudo-orthogonal transformation is a rotation in a pseudo-Euclidean space of p and q dimensions. Throughout this paper, we shall consider p and q as fixed.

Many writers have investigated properties of pseudo-orthogonal matrices; in particular, Lee [1] and Hsu [2] have obtained factorizations of such matrices. Lorentz matrices and symplectic matrices (after a permutation on rows and columns) are examples of p -orthogonal matrices, the former being a special case with $p = 1$, $q = 3$.

By defining the operation of pseudo-transposition, we obtain unified definitions of pseudo-symmetric, pseudo-skew, and pseudo-orthogonal matrices (henceforth denoted by the prefix p -, e.g., p -orthogonal), which are analogous to the definitions using ordinary transposition. Also, certain analogs of theorems involving transposition hold for p -transposition. We obtain, in Theorem 4.2, a new factorization of a p -orthogonal matrix in terms of a p -skew matrix, and in Theorem 5.2, the analog of the Toeplitz factorization (see [3; 80]). The matrices considered in this paper are real.

2. **Definitions.** Postmultiplication of both sides of (1.1) by J gives $C(JC'J) = I$, which is strongly reminiscent of the form $CC' = I$ for orthogonal matrices and suggests the Fundamental Operation: $C^0 = JC'J$ is the p -transpose of C . If

$$X = \begin{pmatrix} X_1 & X_2 \\ X_3 & X_4 \end{pmatrix},$$

where $X: n \times n$, $X_1: p \times p$, $X_4: q \times q$, $p + q = n$, then

$$(2.1) \quad X^0 = \begin{pmatrix} X_1' & -X_3' \\ -X_2' & X_4' \end{pmatrix}.$$

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