

# TOPOLOGIES DEFINED BY BOUNDED SETS

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**1. Introduction.** It is well known that in some linear spaces certain topological concepts can be characterized with the help of a notion of boundedness. For instance, a functional (additive, numerical valued function) on a Banach space is continuous if and only if it is bounded on the unit sphere of the Banach space. Mackey [10,11] and the author [3] have shown that similar situations can arise in much more general linear spaces. Hu [4] has discussed boundedness as a fundamental concept in a non-linear space. In the present paper, we suppose given a vector space  $S$  and a family  $\mathfrak{B}$  of subsets of  $S$  satisfying certain axioms and called the bounded subsets of  $S$ . We inquire into the existence and properties of a topology in  $S$  in which the sets of  $\mathfrak{B}$  are bounded in a topological sense.

In §2, we give the axioms concerning  $\mathfrak{B}$  and explain the notation which we will use.

§3 develops some algebraic consequences of our axioms. Theorem 1 shows that an  $n$ -dimensional set is in  $\mathfrak{B}$  if and only if it can be enclosed in an  $n$ -dimensional cube.

A topology in  $S$  is defined in §4 which makes all the sets of  $\mathfrak{B}$  topologically bounded. The space  $S$  may fail to be a Hausdorff space and the addition in  $S$  may not be continuous in both arguments jointly. However, the instances in which  $S$  is a normed linear space are easily characterized (Theorem 3).

The collection  $\mathfrak{J}$  of all subsets of  $S$  which are topologically bounded is discussed in §5. It is proved (Lemma 6) that  $\mathfrak{J} \supset \mathfrak{B}$  and (Theorem 5) that  $\mathfrak{J}$  and  $\mathfrak{B}$  define the same topology in  $S$ . The sets of  $\mathfrak{J}$  are characterized in two ways (Lemma 7, Theorem 4).

Convergence properties of  $S$  are given in §6 and several examples and counter examples appear in §7.

**2. Notation, axioms and definitions.** The definitions for some of the standard terms are given at the end of this section.

Let  $S = \{\theta, a, b, x, y, \dots\}$  be a vector space over the real number field with zero vector  $\theta$ . We use Roman capitals for subsets of  $S$ , script  $\mathfrak{B}$  and  $\mathfrak{J}$  for collections of subsets of  $S$ . The letters  $i, j, k, n$  index countable sets;  $\alpha, \beta, \gamma$  index arbitrary (sometimes directed) systems; other Greek letters (except  $\theta$ ) denote real scalars. The symbols  $+$  and  $\sum$  indicate linear additions;  $\cup$  is used for point set union. A prime is used for point set complementation and for negation with the symbol  $\epsilon$ .

Let  $\mathfrak{B}$  be any collection of subsets of  $S$  satisfying the following axioms.

(B1). For any  $x \in S$ ,  $\{x\} \in \mathfrak{B}$ .

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