

GEODESIC COORDINATES AND REST SYSTEMS FOR GENERAL LINEAR CONNECTIONS

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Let x_1, x_2, \dots, x_n denote the "original variables", i.e., the coordinates of a point in an n -dimensional manifold L_n with an (asymmetric) linear connection. Then the components $\Gamma_{\alpha\beta}^\lambda(x_1, \dots, x_n)$ of this connection transform according to [3; 327]

$$(1) \quad \bar{\Gamma}_{ik}^l = \Gamma_{\alpha\beta}^\lambda \frac{\partial x_\alpha}{\partial \bar{x}_i} \frac{\partial x_\beta}{\partial \bar{x}_k} \frac{\partial \bar{x}_l}{\partial x_\lambda} + \frac{\partial^2 x_\lambda}{\partial \bar{x}_i \partial \bar{x}_k} \frac{\partial \bar{x}_l}{\partial x_\lambda}.$$

From (1) we get the transformation formula for the torsion tensor $S_{\alpha\beta}^\lambda$ of the L_n :

$$(2) \quad \bar{S}_{ik}^l = S_{\alpha\beta}^\lambda \frac{\partial x_\alpha}{\partial \bar{x}_i} \frac{\partial x_\beta}{\partial \bar{x}_k} \frac{\partial \bar{x}_l}{\partial x_\lambda}, \quad S_{\alpha\beta}^\lambda = -S_{\beta\alpha}^\lambda = \frac{1}{2} (\Gamma_{\alpha\beta}^\lambda - \Gamma_{\beta\alpha}^\lambda) = \Gamma_{[\alpha\beta]}^\lambda.$$

It is well known [2; 105] that L_n permits the introduction of geodesic coordinate systems if and only if the torsion tensor vanishes either locally or everywhere. Indeed from $\Gamma_{\alpha\beta}^\lambda = 0$ (in geodesic coordinates), the symmetry of the second derivatives in the suffixes i and k , and (1), it follows that the connection $\bar{\Gamma}_{ik}^l$ is symmetric; thus from (2), $\bar{S}_{ik}^l = 0$ in this (and so in every) system.

After an affine parameter s has been chosen the geodesics of L_n satisfy the differential equations

$$(3) \quad (x^i)'' + \Gamma_{\alpha\beta}^i(x^\alpha)'(x^\beta)' = 0.$$

Denote the symmetric part of the connection $\Gamma_{\alpha\beta}^i$ by $\Gamma_{(\alpha\beta)}^i$, and take into account the symmetry of the products $(x^\alpha)'(x^\beta)'$. Then we get from (3) and (2)

$$(4) \quad \begin{aligned} (x^i)'' + \Gamma_{\alpha\beta}^i(x^\alpha)'(x^\beta)' &= (x^i)'' + (\Gamma_{(\alpha\beta)}^i + S_{\alpha\beta}^i)(x^\alpha)'(x^\beta)' \\ &= (x^i)'' + \Gamma_{(\alpha\beta)}^i(x^\alpha)'(x^\beta)' = 0, \end{aligned}$$

$$\Gamma_{(\alpha\beta)}^i = \frac{1}{2}(\Gamma_{\alpha\beta}^i + \Gamma_{\beta\alpha}^i),$$

because $S_{\alpha\beta}^i(x^\alpha)'(x^\beta)'$ vanishes as a consequence of the skew-symmetry of the torsion tensor. This means that *the geodesics of an L_n are independent of the torsion* [2; 97]. If we introduce geodesic coordinates with respect to $\Gamma_{(\alpha\beta)}^i$ [2; 100], then from (4), we get, locally in these coordinates, $\Gamma_{(\alpha\beta)}^i = 0$, and thus $(x^i)'' = 0$. Following common usage in theory of relativity we call such systems *rest systems*.

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