of ill-posed problems, of loss-based methods for choosing smoothing parameters, supplemented by empirical checks that the resulting smoothed estimates are acceptable from a practical point of view. I look forward, in particular, to reading about the future exploits of the present author in this important area!

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Comment

Grace Wahba

Professor O'Sullivan has given us a nice overview of some of the issues in ill-posed inverse problems as well as some new ideas. The most important of these new ideas I believe are the following: a) the extension of the idea of averaging kernel to reproducing kernel spaces, with the resulting formula

$$\underset{\|\theta\|^2 \leq \mu^2}{\operatorname{supremum}} \|\theta(t) - E\hat{\theta}(t)\|^2 = \|e_t - A(t)\|^2 \mu^2$$

and b) a new approach to the history matching problem of reservoir engineering. The formula bears a not coincidental relationship to Scheffé's S method of multiple comparisons (Scheffé, 1959, page 65). In atmospheric sciences and possibly elsewhere, extensive historical data allows the construction of a prior covariance for the unknown θ , from which reasonable norms can often be constructed via the well known duality between prior covariances and optimization problems in reproducing kernel spaces. An example of the use of prior covariances based on historical meteorological data to establish penalty functions can be found in Wahba (1982a). The problems of reservoir engineering are extremely important and would benefit from the attention of statisticians. Letting

$$z_{ij} = u(x_i, t_j, a) + \varepsilon_i,$$

as in Section 4.2, the method of regularization estimate of a is the minimizer of

$$\frac{1}{n}\sum_{ij}(z_{ij}-u(x_i,\,t_j,\,a))^2+\lambda J(a)$$

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(see especially Kravaris and Seinfeld, 1985). This problem is particularly difficult since, not only is u a nonlinear function of a, but in general the relationship is only known implicitly as the solution to a partial differential equation. It is a good conjecture that the GCV for nonlinear problems as proposed in O'Sullivan and Wahba (1985) can be used to choose λ in this problem. The details are far from obvious but it looks like the present paper provides an important first step. Of course this history matching setup leads to some juicy experimental design problems—choice of the forcing function q, the location of the wells, and the times of observation.

Concerning robustness of the PMSE criteria (that is, minimizing PMSE also tends to minimize other, possibly more interesting loss functions), further remarks on that can be found in Wahba (1985, page 1381). The GCV extension proposed by the author is an interesting one. Let C be the matrix with ijth entry $c_i'c_j$. If C is the identity then the extension is the same as GCV. If C is a well conditioned matrix, then it appears that one can show that the minimizer of $EV(\lambda)$ is asymptotically near the minimizer of $EL(\lambda)$, the associated (estimable) loss function. You need (1/T)tr HC to be small near the minimizer of EL. I think a problem may arise if you try to choose C to approximate $L(\lambda)$ of the form

$$L(\lambda) = \frac{1}{T} \sum_{i=1}^{T} |\theta(t_i) - \hat{\theta}_{\lambda}(t_i)|^2$$

where the problem is very ill-posed. Consider the operator which maps θ to euclidean m space via the formula $\theta - (\eta(x_1, \theta), \ldots, \eta(x_m, \theta))$. In practice the theoretical dimension of the range space of this