

# A GENERALIZED ERROR FUNCTION\*

By

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## I. INTRODUCTION

Given a set of observed values  $t_i$  ( $i = 1, 2, 3, \dots, n$ ) obtained from  $n$  observations assumed to be made on the same quantity,  $t$ , under the same conditions. We seek to determine two functions  $f(P, t_i)$  and  $\phi(P, t_i)$  such that

$$f(P, t_i) = 0, \quad (i = 1, 2, 3, \dots, n)$$

defines  $P$  as a unique value assigned to the observed quantity; and  $\phi(P, t_i)dt_i$  gives to within infinitesimals of higher order the probability that if another observation is made, the observed value will lie in the interval

$$t_i \leq t \leq t_i + dt_i.$$

Gauss determined the  $\phi$  function to be the so-called normal error law namely,

$$\phi(P, t_i) = c e^{-h^2(P-t_i)^2}$$

on the basis of the following assumptions.

(a) The product  $\eta_i \phi(P, t_i)$  is to be a maximum with respect to  $P$ .

Thus

$$\sum_i \frac{\partial}{\partial P} \log \phi(P, t_i) = 0,$$

$$\sum_i \frac{\partial^2}{\partial P^2} \log \phi(P, t_i) \neq 0.$$

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