

SEQUENTIAL NONPARAMETRIC TWO-WAY CLASSIFICATION WITH A PRESCRIBED MAXIMUM ASYMPTOTIC ERROR PROBABILITY¹

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1. Introduction. Consider the problem of classifying the iid random sample X_1, \dots, X_m into either of two populations π_1 and π_2 , characterized by cdf $F(x)$ and $G(x)$, respectively. It is assumed that $F(x)$ and $G(x)$ are continuous and satisfy the relation $\int (F - G) dF > 0$. Further assume that independent reference random samples Y_1, \dots, Y_n and Z_1, \dots, Z_n are available from π_1 and π_2 , respectively. A classification procedure based on the use of two Mann-Whitney [12] statistics can be defined as follows: Let

$$(1.1) \quad t_{gn} = (mn)^{-1} \sum_{j=1}^m \sum_{i=1}^n [c(Y_i - X_j) - c(X_j - Z_i)]$$

where

$$c(x) = \begin{cases} 1 & x > 0 \\ 0 & x \leq 0 \end{cases}$$

and classify $(X_1, \dots, X_m) = \mathbf{X}_m$ into π_1 if $t_{gn} > 0$ and into π_2 if $t_{gn} \leq 0$. In addition, consider the situation where there is one reference sample Y_1, \dots, Y_n available from π_1 and the observer knows that $G(x) = F(x - s)$ and *knows* the value of the translation parameter $s > 0$. Then let

$$(1.2) \quad t_{sn} = (mn)^{-1} \sum_{j=1}^m \sum_{i=1}^n [c(Y_i - X_j) - c(X_j - Y_i - s)]$$

and classify \mathbf{X}_m into π_1 if $t_{sn} > 0$. Hudimoto [8] first proposed a classification rule similar to that given in (1.1). Gupta [5] gives a classification rule using magnitudes of Mann-Whitney statistics which is applicable to the two-sided problem.

The decision rules based on t_{gn} and t_{sn} have been studied [15], [16] for application to signal detection in a communication system. A signal detector samples the output of a communication channel which contains one of two stationary stochastic processes, corresponding to the conditions of "noise only" or signal imbedded in noise. The reference samples are stored in the detector and \mathbf{X}_m is obtained by the detector for each bit of information sent. The translation case using t_{sn} represents a constant signal level " s " imbedded in additive noise. The

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