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Comment

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In the beginning there was the Gibbs sampler and the Metropolis algorithm. We are now becoming more and more aware of the variety and power of MCMC methods. The article by Besag, Green, Higdon and Mengersen is a further step toward full control of the MCMC toolbox. I like the three applications, which show how to incorporate MCMC methods into inference and which also give rise to several methodological contributions. As the authors write, out of five main issues in MCMC, they concentrate primarily on the choice of the specific chain. The other four issues regard, in one way or another, the question of *convergence* of MCMC processes. I believe that choosing an MCMC algorithm and understanding its convergence are two steps that cannot be divided. Estimating rates of convergence (in some sense) before running the chain or stopping the iterations when the target is almost hit are needed operations if we would like to trust the inferential conclusions drawn on the basis of MCMC runs. This is especially true because convergence of MCMC processes is much harder to detect as compared to convergence of, say, Newton–Raphson.

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We can often read in applied papers that “100 iterations seem to be enough for approximate convergence,” the number being sometimes supported by studies on simulated data (see, e.g., Frigessi and Stander, 1994). This is really too weak to rely on the statistical conclusions, and more can be done. If $X^{(t)}$ is the MCMC process with target distribution π on Ω , the *burn-in* can be estimated by computing a t^* such that

$$(1) \quad \forall t > t^*, \quad \|P(X^{(t)} = \cdot | x^{(1)}) - \pi(\cdot)\| \leq \varepsilon,$$

for some fixed accuracy ε and for some chosen norm, say, total variation. Several techniques are available to bound the total variation error from above,

$$(2) \quad \|P(X^{(t)} = \cdot | x^{(1)}) - \pi(\cdot)\| \leq g(t),$$

where $g(t)$ is a nonincreasing function decaying to zero. Then an upper bound on t^* can be derived by inversion of g , probably a pessimistic estimate of the burn-in, but a “safe” choice. Tight bounds of the type (2) are hard to get and there are no precise general guidelines for the length of the burn-in. However a very *rough* reference value for t^* is available if π is a lattice-based Markov random field (MRF). In Section 1 of Frigessi, Martinelli and Stander (1993) we extend and adapt results originally developed in statistical mechanics and rather unknown to statisticians. Let π be a MRF on a