

BOOK REVIEW

H. KUNITA, *Stochastic Flows and Stochastic Differential Equations*. Cambridge University Press, Cambridge, 1990, 346 pages, \$69.50.

REVIEW BY T. E. HARRIS

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A stochastic flow is a family of random mappings  $\phi_{s,t}$ ,  $0 \leq s \leq t \leq T$ , of  $R^d$  (or other space) into itself, satisfying the composition relation  $\phi_{t,u} \circ \phi_{s,t} = \phi_{s,u}$  if  $s \leq t \leq u$ . There are interesting cases with coalescence, but most treatments have dealt with homeomorphic or diffeomorphic flows. Then  $\bar{\phi}$  defined by  $\bar{\phi}_{s,t} = \phi_{s,t}$  for  $s \leq t$  and  $\bar{\phi}_{s,t} = (\phi_{t,s})^{-1}$  for  $s \geq t$ , is a flow satisfying the composition relation for  $0 \leq s, t \leq T$ . If  $\phi_t, t \geq 0$  is a homeomorphism-valued process, then  $\phi_{s,t} := \phi_t \circ (\phi_s)^{-1}$ ,  $0 \leq s, t \leq T$  is a flow. If  $\phi$  is a flow defined for  $0 \leq s, t \leq T$ , the restriction to  $s \leq t$  is called a *forward* flow, and is usually considered for fixed  $s$ . The restriction to  $s \geq t$  is a *backward* flow. We speak mostly of forward flows, but there are parallel backward results, and the interplay between the two is important.  $\phi_t$  denotes  $\phi_{0,t}$ .

In an important case  $\phi_{s,t}(x)$  is continuous in  $s, t$  and  $x$ , and  $s_1 \leq t_1 \leq s_2 \leq t_2 \leq \dots$  implies that  $\phi_{s_1,t_1}, \phi_{s_2,t_2}, \dots$  are independent mappings; such flows are called *Brownian*. For Brownian flows with some regularity conditions, the paths of a set of  $k$  points are a  $dk$ -dimensional diffusion. In the time-homogeneous case, the law of  $\phi_{s,t}$  depends on  $t - s$ .

It is known that Brownian stochastic flows arise as solutions of Itô systems in  $R^d$ :

$$(1) \quad d\phi_{s,t}^i(x) = \sum_{j=1}^m \sigma_j^i(\phi_{s,t}(x), t) dW_{jt} + b^i(\phi_{s,t}(x), t) dt, \quad t \geq s;$$

$$\phi_{s,s}^i(x) = x^i, \quad 1 \leq i \leq d.$$

Here the  $W$ 's are independent Wiener processes in  $R^1$ . The  $\sigma$ 's and  $b$ 's satisfy familiar conditions. If we change  $\sigma$  without changing  $\sigma\sigma^T$ , the one-point motions are unchanged but in general the flow will be different. However, the flow is determined by the two-point motions, or alternatively by the *infinitesimal mean* (drift)  $b(x, t)$  and the *infinitesimal covariance matrix*:

$$(2) \quad \begin{aligned} a^{ij}(x, y, t) &= \sum_k \sigma_k^i(x, t) \sigma_k^j(y, t) \\ &= \lim_{u \downarrow t} E\{(\phi_{tu}^i(x) - x^i)(\phi_{tu}^j(y) - y^j)\} / (u - t), \\ b^i(x, t) &= \lim_{u \downarrow t} E\{\phi_{tu}^i(x) - x^i\} / (u - t). \end{aligned}$$

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