

APPROACHABILITY IN A TWO-PERSON GAME

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1. Introduction. Let $M = \|M(i, j)\|$ be an $r \times s$ matrix whose elements $M(i, j)$ are probability distributions with finite $E\|\cdot\|^\alpha$, $\|\cdot\|$ is the Euclidean norm and $\alpha > 1$, in a Euclidean k -space \mathcal{E}^k . We associate with M a game between two players, I and II, with the following infinite sequence of engagements: At the n th engagement, $n = 1, 2, \dots$, player I selects $i = 1, \dots, r$ with probability $p_n(1), \dots, p_n(r)$, $\sum_{i=1}^r p_n(i) = 1$, and player II selects $j = 1, \dots, s$ with probability $q_n(1), \dots, q_n(s)$, $\sum_{j=1}^s q_n(j) = 1$. Each selection is made without either player knowing the choice of the other player. Having chosen i and j , payoff $Y_n \in \mathcal{E}^k$ is then determined according to the distribution $M(i, j)$. The point Y_n and probabilities

$$(1.1) \quad p_n = (p_n(1), \dots, p_n(r)) \quad \text{and} \quad q_n = (q_n(1), \dots, q_n(s))$$

are announced to both players after each engagement. We call p_n player I's move and q_n player II's move.

A strategy for player I is a sequence of functions $f = \{f_n\}$, $n = 0, 1, 2, \dots$, where f_n is defined on the $3n$ -tuples $(p_1, q_1, Y_1; \dots; p_n, q_n, Y_n)$ with value p_{n+1} in

$$(1.2) \quad P = \{p = (p(1), \dots, p(r)): \sum_1^r p(i) = 1 \quad \text{and} \quad p(i) \geq 0\},$$

and $p_1 = f_0$ is simply a point of P . For player II, a strategy $g = \{g_n\}$ is defined similarly, except that

$$(1.3) \quad g_n(p_1, q_1, Y_1; \dots; p_n, q_n, Y_n) = q_{n+1} \in Q \quad \text{and} \quad q_1 = g_0 \in Q,$$

where

$$(1.4) \quad Q = \{q = (q(1), \dots, q(s)): \sum_1^s q(j) = 1 \quad \text{and} \quad q(j) \geq 0\}.$$

For a given M , each strategy pair f, g determines a sequence of random variables Y_1, Y_2, \dots (vector payoffs) in \mathcal{E}^k .

Our objective here is to investigate the controllability of the center of gravity of the actual payoffs $\bar{Y}_n = \sum_1^n Y_m/n$ in a long series of plays.

We denote the Euclidean distance between \bar{Y}_n and a nonempty set S in k -space by $\delta(\bar{Y}_n, S)$. For a given M , the set S is said to be approachable (see [1] and [2]) by I in M , if there exists an f^* for I such that, for every g ,

$$(1.5) \quad \delta(\bar{Y}_n, S) \rightarrow 0 \quad \text{a.s.},$$

where Y_1, Y_2, \dots are the payoffs determined by f^*, g . The set S is excludable by

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