

Semi-groups of isometries and the representation and multiplicity of weakly stationary stochastic processes

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1. Introduction and Summary

It is the purpose of this paper to examine the work of J. L. B. Cooper on the representation of a continuous semigroup $\{S_t, t \geq 0\}$ of isometries on a separable Hilbert space \mathcal{H} and to show how it can be adapted to give a complete discussion of the representation theory of a very general class of continuous parameter, weakly stationary stochastic processes which include finite as well as infinite dimensional processes [12]. The possibility of such a connection between Cooper's results and representations of stationary processes has been noted by P. Masani and J. Robertson [15] (also [14]). However, the approach of these authors has been to reduce the study of continuous parameter processes to certain discrete parameter processes associated with them ([15], § 4).

The point of view adopted in this paper enables us to dispense with the associated discrete parameter process and to give a time domain analysis based directly on the stochastic process itself. A significant tool in our analysis is the fundamental notion of multiplicity of a stochastic process introduced recently by H. Cramér [2] and T. Hida [10], and studied extensively by the former author in subsequent papers ([3], [4]). Before we can bring out the relevance of Cooper's ideas to our present aims, it is necessary to complete his basic result in two essential respects: firstly, to introduce the definition of multiplicity of Cooper's representation and secondly to show that it is equal to the dimension of the deficiency subspace R^\perp , R being the range of the Cayley transform V of the maximal symmetric operator H , where iH is the infinitesimal generator of $\{S_t\}$. Cooper's result thus completed and amplified is presented as Theorem 2.1 in section 2.

In sections 3 and 4 we obtain some interesting points of contact with more recent work on isometric operators in Hilbert space. We show in section 3 that Theorem 2.1 immediately yields in a simple and natural way a direct integral representation in terms of "differential innovation" subspaces obtained earlier by Masani [14]. Indeed, the vector valued integral of [14] turns out to be nothing other than the orthogonal sum of N "stochastic integrals", N being the multiplicity of the representation. Section 4 carries the study of the differential innovation subspaces further. Each such subspace is shown to be a "weighted" orthogonal sum of $V^n(R^\perp)$ ($n=0,1,\dots$) which are the innovation subspaces of the associated discrete representation (1.1) of [14]. We believe that this theorem (Theorem 4.1) puts in better perspective, the intrinsic relationship between the given continuous parameter process and its associated discrete parameter process.