# ON ( $f, \boldsymbol{g}, \boldsymbol{u}, \boldsymbol{v}, \lambda)$-STRUCTURES 

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## § 0. Introduction.

Tashiro [10] has shown that hypersurfaces of an almost complex manifold carry almost contact structures. In particular, an odd-dimensional hypersphere in an evendimensional Euclidean space carries an almost contact structure.

Blair, Ludden and one of the present authors [3] (see also, Ako [1], Blair and Ludden [2], Goldberg and Yano [4, 5], Okumura [7], Yano and Ishihara [13]) have studied submanifolds of codimension 2 of almost complex manifolds. These submanifolds admit, under certain conditions, what we call an ( $f, U, V, u, v, \lambda$ ) -structure and, if the ambient space is an almost Hermitian manifold, the submanifolds admit what we call an ( $f, g, u, v, \lambda$ )-structure. In particular, an even-dimensional sphere of codimension 2 of an even-dimensional Euclidean space carries an ( $f, g, u, v, \lambda$ )structure.

They also studied hypersurfaces of almost contact manifolds and found that the hypersurfaces also admit the same kind of structure (see also Okumura [8], Watanabe [11], Yamaguchi [12]).

The main purpose of the present paper is to study the ( $f, g, u, v, \lambda$ )-structure and to give characterizations of even-dimensional spheres.

In §1, we define and discuss ( $f, U, V, u, v, \lambda$ )-structure and $(f, g, u, v, \lambda)$-structure.
In $\S 2$, we prove that a totally umbilical submanifold of codimension 2 of a Kählerian manifold whose connection induced in the normal bundle is flat admits a normal ( $f, g, u, v, \lambda$ )-structure and that the vector fields $U$ and $V$ define infinitesimal conformal transformations of the submanifold.

In $\S 3$, we prove that a hypersurface of a Sasakian manifold for which the tensor $f$ and the second fundamental tensor $h$ commute admits a normal ( $f, g, u, v, \lambda$ )structure and that if the hypersurface is totally umbilical, then the vectors $U$ and $V$ define infinitesimal conformal transformations.
$\S 4$ is devoted to prove some identities valid in $M$ with $\operatorname{normal}(f, g, u, v, \lambda)$-structure for later use.

In $\S 5$, we prove that if a manifold $M$ with normal $(f, g, u, v, \lambda)$-structure satisfies $d u=\phi f$ and $d v=f$ and if $\lambda\left(1-\lambda^{2}\right)$ is an almost everywhere non-zero function, then the vector fields $U$ and $V$ define infinitesimal conformal transformations.

In $\S 6$, we prove a formula which gives the covariant derivative of $f$.
The last $\S 7$ is devoted to prove two theorems which characterize even-dimensional spheres.

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## §1. ( $f, U, V, u, v, \lambda)$-structure.

Let $M$ be an $m$-dimensional differentiable manifold of class $C^{\infty}$. We assume that there exist on $M$ a tensor field of type (1,1), vector fields $U$ and $V, 1$-forms $u$ and $v$, and a function $\lambda$ satisfying the conditions:

$$
\begin{equation*}
f^{2} X=-X+u(X) U+v(X) V \tag{1.1}
\end{equation*}
$$

for any vector field $X$,

$$
\begin{array}{ll}
u \circ f=\lambda v, & f U=-\lambda V, \\
v \circ f=-\lambda u, & f V=\lambda U, \tag{1.3}
\end{array}
$$

where 1 -forms $u \circ f$ and $v \circ f$ are respectively defined by

$$
(u \circ f)(X)=u(f X), \quad(v \circ f)(X)=v(f X)
$$

for any vector field $X$, and

$$
\begin{array}{ll}
u(U)=1-\lambda^{2}, & u(V)=0  \tag{1.4}\\
v(U)=0, & v(V)=1-\lambda^{2} .
\end{array}
$$

In this case, we say that the manifold $M$ has an ( $f, U, V, u, v, \lambda$ )-structure. Examples of manifolds with ( $f, U, V, u, v, \lambda$ )-structure will be given in $\S \S 2$ and 3.

First of all, we prove
Theorem 1.1. A differentiable manifold with ( $f, U, V, u, v, \lambda$ )-structure is of even dimension.

Proof. Let P be a point of $M$ at which $\lambda^{2} \neq 1$. Then, from (1.4) and (1.5), we see that

$$
U \neq 0, \quad V \neq 0
$$

at P . The vectors $U$ and $V$ are linearly independent. For, if there are two numbers $a$ and $b$ such that

$$
a U+b V=0,
$$

then evaluating $u$ and $v$ at $a U+b V$ and using (1.4) and (1.5), we obtain

$$
u(a U+b V)=a u(U)=a\left(1-\lambda^{2}\right)=0,
$$

and

$$
v(a U+b V)=b v(V)=b\left(1-\lambda^{2}\right)=0 .
$$

Thus we have $a=b=0$.
Thus $U$ and $V$ being linearly independent at P , we can choose $m$ linearly independent vectors $X_{1}=U, X_{2}=V, X_{3}, \cdots, X_{m}$ which span the tangent space $T_{\mathrm{P}}(M)$
of $M$ at P and such that $u\left(X_{\alpha}\right)=0, v\left(X_{\alpha}\right)=0$, for $\alpha=3, \cdots, m$. Consequently, we have from (1.1),

$$
f^{2} X_{\alpha}=-X_{\alpha}, \quad \alpha=3,4, \cdots, m
$$

which shows that $f$ is an almost complex structure in the subspace $V_{\mathrm{P}}$ of $T_{\mathrm{P}}(M)$ at P spanned by $X_{3}, \cdots, X_{m}$ and that $V_{\mathrm{P}}$ is even dimensional. Thus $T_{\mathrm{P}}(M)$ is also even dimensional.

Next, let P be a point of $M$ at which $\lambda^{2}=1$. In this case, we see, from (1.4) and (1.5), that

$$
\begin{array}{ll}
u(U)=0, & u(V)=0, \\
v(U)=0, & v(V)=0 .
\end{array}
$$

We also see, from (1.2) and (1.3), that

$$
\begin{array}{llll}
\text { if } & u \neq 0, & \text { then } & v \neq 0, \\
\text { if } & u=0, & \text { then } & v=0 .
\end{array}
$$

We first consider the case in which $u \neq 0, v \neq 0$. In this case, $u$ and $v$ are linearly independent. Because, if there are two numbers $a$ and $b$ such that

$$
a u+b v=0
$$

then, from (1.2), (1.3) and

$$
(a u+b v) \circ f=0
$$

we have

$$
\lambda(b u-a v)=0,
$$

from which

$$
b u-a v=0
$$

$\lambda$ being different from zero. Thus from $a u+b v=0$ and $b u-a v=0$ we have

$$
\left(a^{2}+b^{2}\right) u=0
$$

from which $a=0, b=0$.
Thus, $u$ and $v$ being linearly independent at P , we can choose $n$ linearly independent covectors $w_{1}=u, w_{2}=v, w_{3}, \cdots, w_{m}$ which span the cotangent space ${ }^{\circ} T_{\mathrm{P}}(M)$ of $M$ at P . We denote the dual basis by ( $X_{1}, X_{2}, \cdots, X_{m-1}, X_{m}$ ).

If $U$ and $V$ are linearly independent at P , we can assume that

$$
X_{m-1}=U, \quad X_{m}=V
$$

Then we have

$$
f^{2} X_{\alpha}=-X_{\alpha}+u\left(X_{\alpha}\right) U+v\left(X_{\alpha}\right) V=-X_{\alpha}, \quad \alpha=3,4, \cdots, m
$$

which shows that $f$ is an almost complex structure in the subspace $V_{\mathrm{P}}$ of $T_{\mathrm{P}}(M)$ at P spanned by $X_{3}, \cdots, X_{m}$ and that $V_{\mathrm{P}}$ is even-dimensional and consequently $T_{\mathrm{P}}(M)$ is also even- dimensional.

If $U$ and $V$ are linearly dependent, there exist two numbers $a$ and $b$ such that

$$
a U+b V=0
$$

and $a^{2}+b^{2} \neq 0$. Applying $f$ to the equation above and using (1.2) and (1.3), we find

$$
\lambda(-a V+b U)=0
$$

from which

$$
b U-a V=0 .
$$

Thus, we must have

$$
U=V=0
$$

Thus, from (1.1), we have

$$
f^{2} X=-X
$$

for any vector $X$ in $T_{\mathrm{P}}(M)$. Thus $T_{\mathrm{P}}(M)$ is even dimensional.
The case left to examine is the case in which $u=0, v=0$. But in this case also we have, from (1.1), $f^{2} X=-X$ for any vector $X$ in $T_{\mathrm{P}}(M)$ and consequently $T_{\mathrm{P}}(M)$ is even dimensional. Thus we have completed the proof of Theorem 1.1.

Definition. The structure ( $f, U, V, u, v, \lambda$ ) is said to be normal if the Nijenhuis tensor $N$ of $f$ satisfies

$$
\begin{equation*}
S(X, Y) \equiv N(X, Y)+d u(X, Y) U+d v(X, Y) V=0 \tag{1.6}
\end{equation*}
$$

for any vector field $X$ and $Y$ of $M$.
We consider a product manifold $M \times R^{2}$, where $R^{2}$ is a 2 -dimensional Euclidean space. Then, $(f, U, V, u, v, \lambda)$-structure gives rise to an almost complex structure $J$ on $M \times R^{2}$ :

$$
(J)=\left(\begin{array}{ccc}
f & U & V  \tag{1.7}\\
-u & 0 & -\lambda \\
-v & \lambda & 0
\end{array}\right)
$$

as we can easily check using (1.1)~(1.5).
Computing the Nijenhuis tensor of $J$, we can easily prove
Proposition 1.2. If $J$ is integrable, then ( $f, U, V, u, v, \lambda$ )-structure is normal.
We assume that, in $M$ with ( $f, U, V, u, v, \lambda$ )-structure, there exists a positive definite Riemannian metric $g$ such that

$$
\text { on }(f, g, u, v, \lambda) \text {-Structures }
$$

(1. 8)

$$
\begin{equation*}
g(U, X)=u(X) \tag{1.9}
\end{equation*}
$$

$g(V, X)=v(X)$,
and
(1. 10)

$$
g(f X, f Y)=g(X, Y)-u(X) u(Y)-v(X) v(Y)
$$

for any vector fields $X, Y$ of $M$. We call such a structure a metric ( $f, U, V, u, v, \lambda$ )structure and denote it sometimes by ( $f, g, u, v, \lambda$ ).

We prove
Proposition 1. 3. Let $\omega$ be a tensor field of type (0.2) of $M$ defined by

$$
\begin{equation*}
\omega(X, Y)=g(f X, Y) \tag{1.11}
\end{equation*}
$$

for any vector fields $X$ and $Y$ of $M$, then we have

$$
\begin{equation*}
\omega(X, Y)=-\omega(Y, X) \tag{1.2}
\end{equation*}
$$

that is, $\omega$ is a 2 -form.
Proof. From the definition (1.11) of $\omega$, we have

$$
\omega(f X, f Y)=g(f(f X), f Y)
$$

from which, using (1.10),

$$
\omega(f X, f Y)=g(f X, Y)-u(f X) u(Y)-v(f X) v(Y)
$$

or

$$
\omega(f X, f Y)=\omega(X, Y)-\lambda v(X) u(Y)+\lambda u(X) v(Y)
$$

by virtue of (1.2) and (1.3).
On the other hand, using (1.1), we have

$$
\begin{aligned}
\omega(f X, f Y) & =g\left(f^{2} X, f Y\right) \\
& =g(-X+u(X) U+v(X) V, f Y) \\
& =-g(X, f Y)+u(X) u(f Y)+v(X) v(f Y),
\end{aligned}
$$

by virtue of (1.8) and (1.9) and consequently

$$
\omega(f X, f Y)=-\omega(Y, X)+\lambda u(X) v(Y)-\lambda v(X) u(Y)
$$

Thus we have

$$
\omega(X, Y)=-\omega(Y, X) .
$$

## § 2. Submanifolds of codimension 2 of an almost Hermitian manifold.

In this section, we study submanifolds of codimension 2 of an almost Hermitian manifold as examples of the manifold with ( $f, g, u, v, \lambda$ )-structure.

Let $\tilde{M}$ be a $(2 n+2)$-dimensional almost Hermitian manifold covered by a system of coordinate neighborhoods $\left\{\tilde{U} ; y^{\kappa}\right\}$, where here and in this section the indices $\kappa, \lambda, \mu, \nu$, $\cdots$ run over the range $\{1,2, \cdots, 2 n+2\}$, and let ( $F_{\lambda}{ }^{\kappa}, G_{\mu \lambda}$ ) be the almost Hermitian structure, that is, let $F_{2}{ }^{k}$ be the almost complex structure:

$$
\begin{equation*}
F_{\alpha}{ }^{\alpha} F_{\lambda}^{\alpha}=-\delta_{\alpha}^{\kappa}, \tag{2.1}
\end{equation*}
$$

and $G_{\mu \lambda}$ a Riemannian metric such that

$$
\begin{equation*}
G_{\gamma \beta} F_{\mu}{ }^{\gamma} F_{\lambda}^{\beta}=G_{\mu \lambda} . \tag{2.2}
\end{equation*}
$$

We denote by $\left\{{ }^{\prime}{ }^{\kappa}{ }^{\kappa}\right\}$ \} the Christoffel symbols formed with $G_{\mu \lambda}$.
Let $M$ be a $2 n$-dimensional differentiable manifold which is covered by a system of coordinate neighborhoods $\left\{U ; x^{h}\right\}$, where here and in the sequel the indices $h, i, j$, $\ldots$ run over the range $\{1,2, \cdots, 2 n\}$ and which is differentiably immersed in $\tilde{M}$ as a submanifold of codimension 2 by the equations

$$
\begin{equation*}
y^{k}=y^{k}\left(x^{h}\right) . \tag{2.3}
\end{equation*}
$$

We put

$$
\begin{equation*}
B_{i}{ }^{k}=\partial_{i} y^{k}, \quad\left(\partial_{i}=\partial / \partial x^{i}\right) \tag{2.4}
\end{equation*}
$$

then $B_{i}{ }^{\text {e }}$ is, for each fixed $i$, a local vector field of $\tilde{M}$ tangent to $M$ and vectors $B_{i}{ }^{\text { }}$ are linearly independent in each coordinate neighborhood. $B_{i}{ }^{\kappa}$ is, for each fixed $\kappa$, a local 1-form of $M$.

We choose two mutually orthogonal unit vectors $C^{k}$ and $D^{c}$ of $\tilde{M}$ normal to $M$ in such a way that $2 n+2$ vectors $B_{i}{ }^{k}, C^{k}, D^{\kappa}$ give the positive orientation of $M$.

The transforms $F_{\lambda}{ }^{k} B_{i}{ }^{\lambda}$ of $B_{i}{ }^{\lambda}$ by $F_{\lambda}{ }^{k}$ can be expressed as linear combinations of $B_{i}{ }^{\kappa}, C^{\kappa}$ and $D^{\kappa}$, that is,

$$
\begin{equation*}
F_{i}{ }^{\kappa} B_{i}{ }^{2}=f_{i}{ }^{h} B_{h}{ }^{\kappa}+u_{i} C^{k}+v_{i} D^{\kappa}, \tag{2.5}
\end{equation*}
$$

where $f_{i}{ }^{h}$ is a tensor field of type (1.1) and $u_{i}, v_{i}$ are 1 -forms of $M$. Similarly the transform $F_{\lambda}{ }^{k} C^{k}$ of $C^{\lambda}$ by $F_{\lambda}{ }^{\kappa}$ and the transform $F_{\lambda}{ }^{k} D^{\lambda}$ by $F_{\lambda}{ }^{k}$ can be written as

$$
F_{\lambda}{ }^{\kappa} C^{\lambda}=-u^{i} B_{i}{ }^{\kappa}+\lambda D^{\kappa},
$$

$$
\begin{equation*}
F_{\lambda}{ }^{k} D^{\lambda}=-v^{i} B_{i}{ }^{k}-\lambda C^{k} \tag{2.6}
\end{equation*}
$$

where

$$
u^{2}=u_{t} g^{t i}, \quad v^{2}=v_{t} g^{t i},
$$

$g_{j i}$ being the Riemannian metric on $M$ induced from that of $\tilde{M}$.

$$
\begin{aligned}
& \text { ON }(f, g, u, v, \lambda) \text {-STRUCTURES } \\
& \quad g_{j i}=G_{\mu \lambda} B_{j}{ }^{\mu} B_{i}{ }^{\lambda}
\end{aligned}
$$

and $\lambda$ is a function on $M$. The function $\lambda$ seems to depend on the choice of normals $C^{\boldsymbol{c}}$ and $D^{\kappa}$, but we can easily verify that $\lambda$ is independent of the choise of normals and consequently that $\lambda$ is a function globally defined on $M$.

Applying $F_{\kappa}{ }^{\mu}$ again to (2.5) and taking account of (2.5) itself and (2.6), we find

$$
\begin{equation*}
f_{j}^{h} f_{i}{ }^{3}=-\delta_{i}^{h}+u_{i} u^{h}+v_{i} v^{h} \tag{2.7}
\end{equation*}
$$

$$
\begin{equation*}
u_{h} f_{i}^{h}=\lambda v_{i}, \quad v_{h} f_{i}^{h}=-\lambda u_{i} . \tag{2.8}
\end{equation*}
$$

Applying $F_{k}{ }^{\mu}$ again to (2.6) and taking account of (2.5) and (2.6) itself, we find

$$
\begin{equation*}
f_{i}^{h} u^{\imath}=-\lambda v^{h}, \quad u_{i} u^{\imath}=1-\lambda^{2}, \quad u_{i} v^{2}=0 \tag{2.9}
\end{equation*}
$$

$$
\begin{equation*}
f_{i}^{h} v^{2}=\lambda u^{h}, \quad v_{i} u^{2}=0, \quad v_{i} v^{i}=1-\lambda^{2} \tag{2.10}
\end{equation*}
$$

On the other hand, we have, from (2.2),

$$
G_{\gamma \beta} F_{\mu}{ }^{r} F_{\lambda}{ }^{\beta} B_{j}{ }^{\mu} B_{i}{ }^{\lambda}=G_{\mu \lambda} B_{j}{ }^{\mu} B_{i}{ }^{2},
$$

from which

$$
g_{k h} f_{j}^{k} f_{i}^{h}+u_{j} u_{i}+v_{j} v_{i}=g_{j i}
$$

or

$$
\begin{equation*}
g_{k h} f_{j}^{k} f_{i}^{h}=g_{j i}-u_{j} u_{i}-v_{j} v_{i} . \tag{2.11}
\end{equation*}
$$

Equations (2.7), (2.8), (2.9), (2.10) and (2.11) show that a submanifold of codimension 2 of an almost Hermitian manifold admits a $(f, g, u, v, \lambda)$-structure.

We denote by $\left\{j^{h_{i}}\right\}$ and $\nabla_{i}$ the Christoffel symbols formed with $g_{j i}$ and the operator of covariant differentiation with respect to $\left\{{ }_{j}{ }^{h}{ }_{i}\right\}$ respectively.

The so-called van der Waerden-Bortolotti covariant derivative of $B_{i}{ }^{\kappa}$ is given by

$$
\begin{equation*}
\nabla_{j} B_{i}{ }^{\kappa}=\partial_{j} B_{i}{ }^{\kappa}+\left\{{ }_{\mu}{ }^{\kappa}{ }_{k}\right\} B_{j}{ }^{\mu} B_{i}{ }^{\alpha}-B_{h}{ }^{k}\left\{{ }_{j}{ }^{h}{ }_{i}\right\} \tag{2.11}
\end{equation*}
$$

and is orthogonal to $M$ and consequently can be written as

$$
\begin{equation*}
\nabla_{j} B_{i}{ }^{\kappa}=h_{j i} C^{\kappa}+k_{j i} D^{\kappa}, \tag{2.12}
\end{equation*}
$$

which are equations of Gauss, where $h_{j i}$ and $k_{j i}$ are the second fundamental tensors of $M$ with respect to the normals $C^{\kappa}$ and $D^{\kappa}$ respectively.

For the covariant derivatives of $C^{\kappa}$ and $D^{\kappa}$ along $M$, we have equations of Weingarten

$$
\begin{equation*}
\nabla_{j} C^{\kappa}=-h_{j}{ }^{i} B_{i}{ }^{\kappa}+l_{j} D^{\kappa} \tag{2.13}
\end{equation*}
$$

$$
\nabla_{j} D^{\kappa}=-k_{j}{ }^{2} B_{i}{ }^{\kappa}-l_{j} C^{\kappa},
$$

where

$$
\left.\left.\nabla_{j} C^{\kappa}=\partial_{j} C^{\kappa}+\left\{\mu_{\mu}{ }^{\kappa}\right\}\right\} B_{j}{ }^{\mu} C^{\lambda}, \quad \nabla_{j} D^{\kappa}=\partial_{j} D^{\kappa}+\left\{\begin{array}{l}
\mu \\
\end{array}{ }_{\lambda}\right\}\right\} B_{j}{ }^{\mu} D^{\lambda},
$$

$$
h_{j}{ }^{2}=h_{J g} g^{g^{\imath}}, \quad k_{j}{ }^{2}=k_{J s} g^{s \imath}
$$

and $l_{l}$ is the so-called third fundamental tensor.
As we see from (2.13), equations

$$
\begin{gather*}
\nabla_{j} C^{\kappa}=l_{j} D^{\kappa}, \\
\nabla_{j} D^{\kappa}=-l_{j} C^{k} \tag{2.14}
\end{gather*}
$$

define the connexion induced in the normal bundle. If this induced connexion is flat, then we can choose $C^{k}$ and $D^{k}$ in such a way that we have $l_{j}=0$.

Differentiating (2.5) covariantly along $M$, we have, taking account of equations of Gauss and those of Weingarten,

$$
\begin{aligned}
& \left(\nabla_{\mu} F_{\lambda}{ }^{k}\right) B_{j}{ }^{\mu} B_{i}{ }^{\lambda}+F_{\lambda}{ }^{k}\left(h_{j i} C^{\lambda}+k_{j i} D^{\lambda}\right) \\
& =\left(\nabla_{j} f_{i}{ }^{h}\right) B_{h}{ }^{\kappa}+f_{i}{ }^{t}\left(h_{j t} C^{k}+k_{j t} D^{c}\right) \\
& +\left(\nabla_{j} u_{i}\right) C^{x}+u_{i}\left(-h_{j}{ }^{h} B_{h}{ }^{k}+l_{j} D^{x}\right) \\
& +\left(\nabla_{j} v_{i}\right) D^{\kappa}+v_{i}\left(-k_{j}{ }^{h} B_{h}{ }^{\kappa}-l_{j} C^{\kappa}\right),
\end{aligned}
$$

or

$$
\begin{aligned}
& \left(\nabla_{\mu} F_{i}{ }^{\kappa}\right) B_{j}{ }^{\mu} B_{i}{ }^{2}-\left(h_{j i} u^{h}+k_{j i} v^{h}\right) B_{h}{ }^{\kappa}-\lambda k_{j i} C^{\kappa}+\lambda h_{j i} D^{\kappa} \\
= & \left(\nabla_{j} f_{i}{ }^{h}-h_{j}{ }^{h} u_{i}-k_{j}{ }^{{ }^{k}} v_{i}\right) B_{h}{ }^{\kappa} \\
& +\left(\nabla_{j} u_{i}+h_{j t} f_{i}{ }^{t}-l_{j} v_{i}\right) C^{x} \\
& +\left(\nabla_{j} v_{i}+k_{j t} f_{i}{ }^{t}+l_{j} u_{i}\right) D^{\kappa} .
\end{aligned}
$$

Thus, if $\tilde{M}$ is a Kählerian manifold, that is, if $\nabla_{\mu} F_{\lambda}{ }^{\kappa}=0$, then we have

$$
\begin{align*}
& \nabla_{j} f_{\imath}{ }^{h}=-h_{j i} u^{h}+h_{\jmath}{ }^{h} u_{i}-k_{j i} v^{h}+k_{j}{ }^{h} v_{i},  \tag{2.15}\\
& \nabla_{j} u_{i}=-h_{j t} f_{\imath}{ }^{t}-\lambda k_{j i}+l_{j} v_{i},  \tag{2.16}\\
& \nabla_{j} v_{i}=-k_{j t} f_{\imath}+\lambda h_{j i}-l_{j} u_{i} . \tag{2.17}
\end{align*}
$$

Using (2.15), (2.16) and (2.17) to compute

$$
S_{j i}{ }^{h}=N_{j i}{ }^{h}+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h},
$$

we find

$$
\begin{aligned}
S_{j i}{ }^{h}= & \left(f_{\jmath}{ }^{r} h_{r}{ }^{h}-h_{\jmath}{ }^{r} f_{r}{ }^{h}\right) u_{i}-\left(f_{2}{ }^{r} h_{r}{ }^{h}-h_{i}{ }^{r} f_{r}{ }^{h}\right) u_{\jmath} \\
& +\left(f_{\jmath}{ }^{r} k_{r}{ }^{h}-k_{\jmath}{ }^{r} f_{r}{ }^{h}\right) v_{i}-\left(f_{2}{ }^{r} k_{r}{ }^{h}-k_{i}{ }^{r} f_{r}{ }^{h}\right) v_{j} \\
& +u^{h}\left(l_{j} v_{i}-l_{i} v_{j}\right)-v^{h}\left(l_{j} u_{i}-l_{i} u_{j}\right) .
\end{aligned}
$$

Thus we have

Proposition 3.1. Let $M$ be a submanifold of codimension 2 of a Kählerian manifold whose connection induced in the normal bundle is flat. If $f$ commutes with both of $h$ and $k, M$ admits a normal ( $f, g, u, v, \lambda)$-structure.

Corollary 3.2 A totally umbilical submanifold of codimension 2 of a Kählerian manifold whose connection induced in the normal bundle is flat admits a normal ( $f, g, u, v, \lambda$ )-structure.

Corollary 3.2. holds of course for a totally geodesic submanifold. A plane or a sphere of codimension 2 in an even-dimensional Euclidean space are examples for which the corollary holds.

For a totally umbilical submanifold whose connection induced in the normal bundle is flat, we have, for suitably chosen unit normals $C$ and $D$,

$$
h_{j i}=h g_{j i}, \quad k_{j i}=k g_{j i}, \quad l_{j}=0
$$

and consequently (2.16) and (2.17) become

$$
\begin{equation*}
\nabla_{j} u_{i}=h f_{j i}-\lambda k g_{j i}, \tag{2.18}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{j} v_{i}=k f_{j i}+\lambda h g_{j i} \tag{2.19}
\end{equation*}
$$

respectively. These equations give

$$
\begin{equation*}
\nabla_{j} u_{i}+\nabla_{i} u_{j}=-2 \lambda k g_{j i} \tag{2.20}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{j} v_{i}+\nabla_{i} v_{j}=2 \lambda h g_{j i} \tag{2.21}
\end{equation*}
$$

which show that $u^{h}$ and $v^{h}$ define infinitesimal conformal transformations in $M$.

## § 3. Hypersurfaces of an almost contact metric manifold.

In this section, we study hypersurfaces of an almost contact metric manifold as examples of the manifold with ( $f, g, u, v, \lambda$ )-structure.

Let $\tilde{M}$ be a $(2 n+1)$-dimensional almost contact metric manifold covered by a system of coordinate neighborhoods $\left\{\tilde{U} ; y^{k}\right\}$, where here and in this section, the indices $\kappa, \lambda, \mu, \nu, \cdots$ run over the range $\{1,2, \cdots, 2 n+1\}$ and let ( $F_{\lambda}{ }^{\kappa}, G_{\mu \lambda}, v_{\lambda}$ ) be the almost contact metric structure, that is [9],

$$
\begin{equation*}
F_{\mu}{ }^{{ }^{k}} F_{\lambda}{ }^{\mu}=-\delta_{\lambda}^{\varepsilon}+v_{\lambda} v^{k}, \tag{3.1}
\end{equation*}
$$

$$
\begin{equation*}
v_{k} F_{\lambda}{ }^{\kappa}=0, \quad F_{\lambda}{ }^{\kappa} v^{2}=0 \tag{3.2}
\end{equation*}
$$

$$
\begin{equation*}
v_{v} v^{2}=1 \tag{3.3}
\end{equation*}
$$

and
(3. 4)

$$
G_{\gamma \beta} F_{\mu}{ }^{\gamma} F_{\lambda}{ }^{\beta}=G_{\mu \lambda}-v_{\mu} v_{\lambda} .
$$

Let $M$ be a $2 n$-dimensional differentiable manifold which is covered by a system of coordinate neighborhoods $\left\{U ; x^{h}\right\}$, and which is differentiably immersed in $\tilde{M}$ as a hypersurface by the equations

$$
\begin{equation*}
y^{k}=y^{k}\left(x^{h}\right) \tag{3.5}
\end{equation*}
$$

We put $B_{i}{ }^{k}=\partial_{i} y^{k}$ and choose a unit vector $C^{k}$ of $\tilde{M}$ normal to $M$ in such a way that $2 n+1$ vectors $B_{i}{ }^{c}$ and $C^{k}$ give the positive orientation of $M$.

The transforms $F_{\lambda}{ }^{k} B_{i}{ }^{2}$ of $B_{i}{ }^{2}$ by $F_{\lambda}{ }^{k}$ can be expressed as linear combinations of $B_{i}{ }^{\kappa}$ and $C^{k}$, that is

$$
\begin{equation*}
F_{\lambda}{ }^{k} B_{i}{ }^{2}=f_{i}{ }^{h} B_{h}{ }^{\kappa}+u_{i} C^{\kappa} \tag{3.6}
\end{equation*}
$$

where $f_{i}{ }^{h}$ is a tensor field of type $(1,1)$ and $u_{i}$ is a 1 -form of $M$. Similarly, the transform $F_{\lambda}{ }^{\kappa} C^{\lambda}$ of $C^{\lambda}$ by $F_{\lambda}{ }^{\kappa}$ can be written as
where

$$
u^{i}=u_{f} g^{f i}
$$

$g_{j i}$ being the Riemannian metric on $M$ induced from that of $\tilde{M}$.
We put

$$
\begin{equation*}
v^{k}=B_{i}^{k} v^{2}+\lambda C^{\varepsilon} \tag{3.8}
\end{equation*}
$$

where $v^{i}$ is a vector field of $M$ and $\lambda$ a function of $M$.
Applying $F_{\star}{ }^{\mu}$ again to (3.6) and taking account of (3.6) itself, (3.7) and (3.8), we find

$$
\begin{align*}
f_{i}^{t} f_{t}^{h} & =-\delta_{i}^{h}+u_{i} u^{h}+v_{i} v^{h}  \tag{3.9}\\
u_{t} f_{i}^{t} & =\lambda v_{i} . \tag{3.10}
\end{align*}
$$

Applying $F_{\star}{ }^{\mu}$ again to (3.7) and taking account of (3.6), (3.7) and (3.8), we obtain

$$
\begin{align*}
& f_{i}^{h} u^{i}=-\lambda v^{h},  \tag{3.11}\\
& u_{i} u^{i}=1-\lambda^{2} .
\end{align*}
$$

Finally applying $F_{*}^{\mu}$ to (3.8), we find

$$
\begin{align*}
f_{i}{ }^{h} v^{i} & =\lambda u^{h},  \tag{3.13}\\
u_{i} v^{i} & =0 . \tag{3.14}
\end{align*}
$$

Since $u^{\varepsilon}$ is a unit vector, we have, from (3.8),

$$
\begin{equation*}
v_{i} v^{i}=1-\lambda^{2} \tag{3.15}
\end{equation*}
$$

On the other hand, we have, from (3.4)

$$
G_{\gamma \beta} F_{\mu}{ }^{\gamma} F_{\lambda}{ }^{\beta} B_{j}{ }^{\mu} B_{i}{ }^{2}=G_{\mu \lambda} B_{j}{ }^{\mu} B_{i}{ }^{2}-u_{\mu} B_{j}{ }^{\mu} u_{\lambda} B_{i}{ }^{\lambda}
$$

from which

$$
g_{k h} f_{j}{ }^{k} f_{i}^{h}+u_{j} u_{i}=g_{j i}-v_{j} v_{i}
$$

that is

$$
\begin{equation*}
g_{k h} f_{j}{ }^{k} f_{i}{ }^{h}=g_{j i}-u_{j} u_{i}-v_{j} v_{i} . \tag{3.16}
\end{equation*}
$$

Equations (3.9) $\sim(3.16)$ show that a hypersurface of an almost contact metric manifold admits a ( $f, g, u, v, \lambda$ )-structure.

For the hypersurface $M$, the equations of Gauss and those of Weingarten are

$$
\begin{equation*}
\nabla_{j} B_{i}{ }^{\kappa}=h_{j i} C^{\kappa}, \tag{3.17}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{j} C^{k}=-h_{j}{ }^{i} B_{i}{ }^{k} \tag{3.18}
\end{equation*}
$$

respectively.
Differentiating (3.6) covariantly along $M$, we have, taking account of (3.17) and (3.18),

$$
\begin{aligned}
& \left(\nabla_{\mu} F_{\lambda}{ }^{k}\right) B_{j}{ }^{\mu} B_{i}{ }^{2}+F_{\lambda}{ }^{k} h_{j i} C^{\lambda} \\
= & \left(\nabla_{j} f_{i}{ }^{h}\right) B_{h}{ }^{\kappa}+f_{i}^{t} h_{j t} C^{k}+\left(\nabla_{j} u_{i}\right) C^{k}-u_{i} h_{j}{ }^{h} B_{h}{ }^{k}
\end{aligned}
$$

or

$$
\begin{aligned}
& \left(\nabla_{\mu} F_{\lambda}{ }^{\kappa}\right) B_{j}{ }^{\mu} B_{i}{ }^{2}-h_{j i} u^{h} B_{h}{ }^{\kappa} \\
= & \left(\nabla_{j} f_{i}^{h}-h_{j}{ }^{h} u_{i}\right) B_{h}{ }^{\kappa}+\left(\nabla_{j} u_{i}+h_{j t} f_{i}{ }^{t}\right) C^{\kappa} .
\end{aligned}
$$

Thus, if $\tilde{M}$ is a Sasakian manifold, that is, if

$$
\nabla_{\mu} F_{\lambda}{ }^{\mathrm{k}}=-g_{\mu \lambda} v^{\mathrm{c}}+\delta_{\mu}^{\mathrm{k}} v_{\lambda,},
$$

then we have

$$
\begin{aligned}
& -g_{j i}\left(B_{h}{ }^{\kappa} v^{h}+\lambda C^{k}\right)+B_{j}{ }^{\kappa} v_{i}-h_{j i} u^{h} B_{h}{ }^{\kappa} \\
= & \left(\nabla_{j} f_{i}{ }^{h}-h_{j}{ }^{h} u_{i}\right) B_{h}{ }^{\kappa}+\left(\nabla_{j} u_{i}+h_{j t} f_{\imath}\right) C^{\kappa},
\end{aligned}
$$

from which

$$
\begin{equation*}
\nabla_{j} f_{i}^{h}=-h_{j i} u^{h}+h_{j}{ }^{h} u_{i}-g_{j i} v^{h}+\delta_{j}^{h} v_{i}, \tag{3.19}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{j} u_{i}=-h_{j t} f_{i}^{t}-\lambda g_{j i} . \tag{3.20}
\end{equation*}
$$

On the other hand, differentiating (3.8) covariantly along $M$ and taking account of (3.17), (3.18), and

$$
\nabla_{\lambda} v^{k}=F_{\lambda}{ }^{\kappa},
$$

we find

$$
F_{\lambda}{ }^{{ }^{k}} B_{j}{ }^{\lambda}=h_{j i} v^{i} C^{\kappa}+B_{i}{ }^{\kappa} \nabla_{j} v^{i}+\left(\nabla_{j} \lambda\right) C^{\kappa}+\lambda\left(-h_{j}{ }^{h} B_{h}{ }^{\kappa}\right),
$$

or

$$
f_{j}{ }^{h} B_{h}{ }^{\kappa}+u_{j} C^{k}=\left(\nabla_{j} v^{h}-\lambda h_{j}{ }^{h}\right) B_{h}{ }^{\kappa}+\left(\nabla_{j} \lambda+h_{j i} v^{i}\right) C^{k},
$$

from which

$$
\begin{equation*}
\nabla_{j} v^{h}=f_{j}{ }^{h}+\lambda h_{j}{ }^{h}, \tag{3.21}
\end{equation*}
$$

or

$$
\begin{equation*}
\nabla_{j} v_{i}=f_{j i}+\lambda h_{j i} \tag{3.22}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{j} \lambda=u_{j}-h_{j i} v^{i} . \tag{3.23}
\end{equation*}
$$

Thus, computing $S_{j i}{ }^{h}$ we obtain

$$
\begin{equation*}
S_{j i}{ }^{h}=\left(f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{t}{ }^{h}\right) u_{i}-\left(f_{i}{ }^{t} h_{t}{ }^{h}-h_{i}{ }^{t} f_{t}^{h}\right) u_{j} . \tag{3.24}
\end{equation*}
$$

Now we prove
Proposition 4.1. In order that the induced ( $f, g, u, v, \lambda$ )-structure on a hypersurface of a Sasakian manifold be normal it is necessary and sufficient that $f$ commutes with $h$.

Proof. The sufficiency of the condition is trivially seen from (3.24). So we prove the necessity of the condition.

Suppose that the ( $f, g, u, v, \lambda$ )-structure be normal, then we have, from $S_{j i}{ }^{h}=0$,

$$
\begin{equation*}
\left(f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{t}{ }^{h}\right) u_{i}=\left(f_{i}{ }^{t} h_{t}{ }^{h}-h_{i}{ }^{t} f_{t}{ }^{h}\right) u_{j} . \tag{3.25}
\end{equation*}
$$

Thus, for some vector field $w^{h}$, we have

$$
\begin{equation*}
f_{J}^{t} h_{t}{ }^{h}-h_{j}^{t} f_{t}^{h}=w^{h} u_{J} . \tag{3.26}
\end{equation*}
$$

Since the covariant components of the tensor defined by the left hand members of the above equation are symmetric, it follows that $w$ is proportional to $u$, that is,

$$
f_{j}^{t} h_{t h}+f_{h}^{t} h_{t J}=\alpha u_{j} u_{h}
$$

$\alpha$ being a function, from which, by transvection of $g^{j h}, \alpha=0$ or $u_{J}=0$. This, together with (3.26), shows that $f$ commutes with $h$.

It is known [12] that if $f$ commutes with $h$ and $\lambda^{2} \neq 1$ almost everywhere, the hypersurface is totally umbilical. So we get

Proposition 4.2. If the ( $f, g, u, v, \lambda$ )-structure induced on a hypersurface of a Sasakian manifold is normal, the hypersurface is totally umbilical.

For a hypersurface with the induced normal ( $f, g, u, v, \lambda$ ) -structure, we have from (3.20),

$$
\begin{equation*}
\nabla_{j} u_{i}+\nabla_{i} u_{j}=-2 \lambda g_{j i} \tag{3.27}
\end{equation*}
$$

and from (3.22)

$$
\begin{equation*}
\nabla_{j} v_{i}+\nabla_{i} v_{j}=2 \lambda h g_{j i} \tag{3.28}
\end{equation*}
$$

which show that $u^{h}$ and $v^{h}$ define infinitesimal conformal transformations in $M$.

## §4. Identities in manifolds with normal (f, $g, u, v, \lambda)$-structure.

In this section we shall prove some identities in manifolds with normal ( $f, g, u, v, \lambda$ )-structure for later use.

Let $M$ be a manifold with normal $(f, g, u, v, \lambda)$-structure. The structure being normal, we have

$$
f_{j}{ }^{t} \nabla_{t} f_{i}{ }^{h}-f_{2}{ }^{t} \nabla_{t} f_{j}{ }^{h}-\left(\nabla_{J} f_{\imath}{ }^{t}-\nabla_{v} f_{j}{ }^{t}\right) f_{t}^{h}
$$

$$
\begin{equation*}
+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h}=0 \tag{4.1}
\end{equation*}
$$

We first prove
Lemma 4.1. In a manifold $M$ with normal ( $f, g, u, v, \lambda$ )-structure, we have

$$
\lambda\left(f_{j}^{t} u_{t i}-f_{\imath}{ }^{t} u_{t j}\right)+f_{j}{ }^{t} f_{\imath}^{s} v_{t s}-v_{j i}
$$

$$
\begin{equation*}
+\left(f_{j}^{t} u_{i}-f_{i}^{t} u_{j}\right) \nabla_{t} \lambda-\lambda\left\{\left(\nabla_{j} \lambda\right) v_{i}-\left(\nabla_{i} \lambda\right) v_{j}\right\}=0 \tag{4.2}
\end{equation*}
$$

and

$$
\lambda\left(f_{j}^{t} v_{t i}-f_{i}^{t} v_{t j}\right)-f_{j}^{t} f_{i}{ }^{s} u_{t s}+u_{j i}+\left(f_{j}^{t} v_{i}-f_{\imath}^{t} v_{j}\right) \nabla_{t} \lambda
$$

$$
\begin{equation*}
+\lambda\left\{\left(\nabla_{j} \lambda\right) u_{i}-\left(\nabla_{i} \lambda\right) u_{j}\right\}=0, \tag{4.3}
\end{equation*}
$$

where

$$
u_{j i}=\nabla_{j} u_{i}-\nabla_{i} u_{j}, \quad v_{j i}=\nabla_{j} v_{i}-\nabla_{i} v_{j} .
$$

Proof. Transvecting (4.1) with $v_{h}$, we find

$$
\begin{gathered}
f_{j}^{t}\left(\nabla_{t} f_{i}^{h}\right) v_{h}-f_{\imath}^{t}\left(\nabla_{t} f_{j}^{h}\right) v_{h}+\lambda\left(\nabla_{j} f_{\imath}^{t}-\nabla_{i} f_{j}^{t}\right) u_{t} \\
+\left(1-\lambda^{2}\right)\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right)=0
\end{gathered}
$$

by virtue of (1.3) and (1.5), or

$$
\begin{gathered}
f_{j}^{t}\left\{\nabla_{t}\left(f_{i}{ }^{h} v_{h}\right)-f_{i}{ }^{h} \nabla_{t} v_{h}\right\}-f_{\imath}{ }^{t}\left\{\nabla_{t}\left(f_{j}{ }^{h} v_{h}\right)-f_{j}{ }^{h} \nabla_{t} v_{h}\right\} \\
+\lambda\left\{\nabla_{j}\left(f_{\imath}^{t} u_{t}\right)-f_{\imath} \nabla_{j} \nabla_{j}-\nabla_{i}\left(f_{j}^{t} u_{t}\right)+f_{j}^{t} \nabla_{i} u_{t}\right\}+\left(1-\lambda^{2}\right)\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right)=0,
\end{gathered}
$$

from which

$$
\begin{aligned}
& f_{j}^{t}\left\{-\left(\nabla_{t} \lambda\right) u_{i}-\lambda \nabla_{t} u_{i}-f_{i}{ }^{h} \nabla_{t} v_{h}\right\}+f_{i}{ }^{t}\left\{\left(\nabla_{t} \lambda\right) u_{j}+\lambda \nabla_{t} u_{j}+f_{j}{ }^{h} \nabla_{l} v_{h}\right\} \\
+ & \lambda\left\{\left(\nabla_{j} \lambda\right) v_{i}+\lambda \nabla_{j} v_{i}-f_{i}^{t} \nabla_{j} u_{t}-\left(\nabla_{i} \lambda\right) v_{j}-\lambda \nabla_{i} v_{j}+f_{j} \nabla_{i} u_{t}\right\} \\
+ & \left(1-\lambda^{2}\right)\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right)=0,
\end{aligned}
$$

by virtue of (1.2) and (1.3), from which

$$
\begin{aligned}
& \lambda\left\{f_{j}^{t}\left(\nabla_{t} u_{i}-\nabla_{i} u_{t}\right)-f_{i}^{t}\left(\nabla_{t} u_{j}-\nabla_{j} u_{t}\right)\right\}+f_{j}^{t} f_{i}^{s}\left(\nabla_{t} v_{s}-\nabla_{s} v_{t}\right)-\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) \\
+ & \left(f_{j}^{t} u_{i}-f_{i}^{t} u_{j}\right) \nabla_{t} \lambda-\lambda\left\{\left(\nabla_{j} \lambda\right) v_{i}-\left(\nabla_{i} \lambda\right) v_{j}\right\}=0,
\end{aligned}
$$

which proves (4.2)
Similarly, transvecting (4.1) with $u_{h}$, we can prove (4.3).
In order to get further results on manifolds with $\operatorname{normal}(f, g, u, v, \lambda)$-structure, we put the condition

$$
\begin{equation*}
v_{j i}=2 f_{j i .} \tag{4.4}
\end{equation*}
$$

As we have seen in the preceding section, for a hypersurface of Sasakian manifold, we have

$$
\nabla_{j} v_{i}=f_{j i}+\lambda h_{j i}
$$

and consequently the condition (4.4) is always satisfied.
Lemma 4. 2. Let $M$ be a manifold with normal ( $f, g, u, v, \lambda)$-structure satisfying (4. 4). If the function $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero, then we have

$$
\begin{equation*}
u^{t} \nabla_{t} \lambda=1-\lambda^{2} . \tag{4.5}
\end{equation*}
$$

Proof. Transvecting (4.2) with $u^{j} v^{i}$ and using (1.2) (1.5), we find

$$
\begin{gathered}
\lambda\left(-\lambda u_{j i} v^{j} v^{i}-\lambda u_{i j} u^{i} u^{j}\right)+\lambda^{2} v_{t s} u^{t} v^{s}-v_{j i} u^{j} v^{i} \\
-\lambda\left(1-\lambda^{2}\right) u^{t} \nabla_{t} \lambda-\lambda\left(1-\lambda^{2}\right) u^{j} \nabla_{j} \lambda=0,
\end{gathered}
$$

or, using $v_{t s}=2 f_{t s}$,

$$
\text { ON }(f, g, u, v, \lambda) \text {-STRUCTURES }
$$

$$
2 \lambda\left(1-\lambda^{2}\right)^{2}-2 \lambda\left(1-\lambda^{2}\right) u^{t} \nabla_{t} \lambda=0
$$

which proves (4.5)
Lemma 4. 3. Let $M$ be a manifold with normal ( $f, g, u, v, \lambda$ )-structure satisfying (4. 4), then we have

$$
\begin{equation*}
f_{j}{ }^{t} \nabla_{h} f_{t i}-f_{i}{ }^{t} \nabla_{h} f_{t j}=u_{j}\left(\nabla_{i} u_{h}\right)-u_{i}\left(\nabla_{j} u_{h}\right)+v_{j}\left(\nabla_{i} v_{h}\right)-v_{i}\left(\nabla_{j} v_{h}\right) . \tag{4.6}
\end{equation*}
$$

Proof. Since $f_{j i}$ is given by

$$
f_{j i}=\frac{1}{2}\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right)
$$

we have

$$
\begin{equation*}
\nabla_{\jmath} f_{i h}+\nabla_{\imath} f_{h j}+\nabla_{h} f_{j i}=0 \tag{4.7}
\end{equation*}
$$

On the other hand, (4.1) can be written as

$$
\begin{aligned}
& f_{j}^{t} \nabla_{t} f_{i h}-f_{\imath}^{t} \nabla_{t} f_{j h}+\left(\nabla_{j} f_{i t}-\nabla_{i} f_{j t}\right) f_{h}^{t} \\
& \quad+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u_{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v_{h}=0
\end{aligned}
$$

and consequently

$$
\begin{aligned}
& -f_{j}^{t}\left(\nabla_{\imath} f_{h t}+\nabla_{h} f_{t i}\right)+f_{\imath}^{t}\left(\nabla_{j} f_{h t}+\nabla_{h} f_{t j}\right) \\
& +\left(\nabla_{j} f_{i t}-\nabla_{2} f_{j t}\right) f_{h}{ }^{t}+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u_{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v_{h}=0
\end{aligned}
$$

that is,

$$
\begin{aligned}
-\nabla_{i}\left(f_{j}^{t} f_{h t}\right) & -f_{j}^{t} \nabla_{h} f_{t i}+\nabla_{j}\left(f_{i}^{t} f_{h t}\right)+f_{i}^{t} \nabla_{h} f_{t j} \\
& +\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u_{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v_{h}=0
\end{aligned}
$$

Substituting

$$
f_{j}^{t} f_{h t}=g_{j h}-u_{j} u_{h}-v_{j} v_{h}
$$

we obtain

$$
u_{j}\left(\nabla_{i} u_{h}\right)+v_{j}\left(\nabla_{i} v_{h}\right)-f_{j}{ }^{t} \nabla_{h} f_{t i}-u_{i}\left(\nabla_{j} u_{h}\right)-v_{i}\left(\nabla_{j} v_{h}\right)+f_{i}^{t} \nabla_{h} f_{t \jmath}=0
$$

which gives (4.6).

## §5. Vector fields $\boldsymbol{U}$ and $V$.

In $\S 3$, we have seen that a totally umbilical submanifold of codimension 2 of a Kählerian manifold whose connection induced on the normal bundle is flat admits a normal $(f, g, u, v, \lambda)$-structure and that the vector fields $U$ and $V$ define
infinitesimal conformal transformations.
Also in §4, we have seen that a totally umbilical hypersurface of a Sasakian manifold admits a normal $(f, g, u, v, \lambda)$-structure and that the vector fields $U$ and $V$ define infinitesimal conformal transformations.

In this section, we prove that, under certain conditions, the vector fields $U$ and $V$ of a normal ( $f, g, u, v, \lambda$ )-structure both define infinitesimal conformal transformations.

In the sequel, we assume that

$$
\begin{equation*}
\nabla_{j} u_{i}-\nabla_{i} u_{j}=2 \phi f_{j i} \tag{5.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\nabla_{j} v_{i}-\nabla_{i} v_{j}=2 f_{j i}, \tag{5.2}
\end{equation*}
$$

where $\phi$ is a differentiable function on $M$.
Lemma 5.1. Let $M$ be a manifold with normal ( $f, g, u, v, \lambda$ )-structure satisfying (5.1) and (5.2). If the function $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero, then we have

$$
\begin{equation*}
v^{t} \nabla_{t} \lambda=-\phi\left(1-\lambda^{2}\right) . \tag{5.3}
\end{equation*}
$$

Proof. Transvecting (4.3) with $u^{\top} v^{2}$ and using (1.2)~(1.5), we find

$$
\begin{array}{r}
\lambda\left(-\lambda v_{j i} v^{j} v^{i}+\lambda v_{j i} u^{j} u^{i}\right)-\lambda^{2} u_{t s} u^{t} v^{s}+u_{j i} u^{j} v^{i} \\
-\lambda\left(1-\lambda^{2}\right) v^{t} \nabla_{t} \lambda-\lambda\left(1-\lambda^{2}\right) v^{i} \nabla_{i} \lambda=0,
\end{array}
$$

or, using $u_{t s}=2 \phi f_{t s}$,

$$
-2 \lambda\left(1-\lambda^{2}\right)^{2} \phi-2 \lambda\left(1-\lambda^{2}\right) v^{i} \nabla_{i} \lambda=0
$$

which proves (5.3).
Lemma 5.2. Under the same assumptions as those in Lemma 5.1, we have

$$
\begin{equation*}
\nabla_{i} \lambda=u_{i}-\phi v_{i} . \tag{5.4}
\end{equation*}
$$

Proof. From (4. 2), (5.1) and (5.2), we have

$$
2 f_{2}^{t} f_{v}^{s} f_{t s}-2 f_{j i}+\left(f_{j}{ }^{t} u_{i}-f_{i}{ }^{t} u_{j}\right) \nabla_{t} \lambda-\lambda\left\{\left(\nabla_{j} \lambda\right) v_{i}-\left(\nabla_{i} \lambda\right) v_{j}\right\}=0,
$$

or

$$
2 \lambda\left(u_{j} v_{i}-u_{i} v_{j}\right)+\left(f_{j}{ }^{t} u_{i}-f_{i}{ }^{t} u_{j}\right) \nabla_{t} \lambda-\lambda\left\{\left(\nabla_{j} \lambda\right) v_{i}-\left(\nabla_{i} \lambda\right) v_{j}\right\}=0 .
$$

Transvecting this equation with $v^{j}$, we find

$$
-2 \lambda\left(1-\lambda^{2}\right) u_{i}+\lambda u_{i} u^{t} \nabla_{t} \lambda-\lambda\left(v^{j} \nabla_{j} \lambda\right) v_{i}+\lambda\left(1-\lambda^{2}\right) \nabla_{i} \lambda=0
$$

from which, substituting (4.5) and (5.3),

$$
\begin{gathered}
\text { ON }(f, g, u, v, \lambda) \text {-STRUCTURES } \\
-2 \lambda\left(1-\lambda^{2}\right) u_{i}+\lambda\left(1-\lambda^{2}\right) u_{i}+\lambda\left(1-\lambda^{2}\right) \phi v_{i}+\lambda\left(1-\lambda^{2}\right) \nabla_{i} \lambda=0
\end{gathered}
$$

which proves (5.4).
Lemma 5.3. Under the same assumptions as those in Lemma 5.1, $\phi$ is constant.
Proof. Differentiating (5.4) covariantly, we have

$$
\nabla_{j} \nabla_{i} \lambda=\nabla_{j} u_{i}-\phi \nabla_{j} v_{i}-v_{i} \nabla_{j} \phi,
$$

from which, using (5.1) and (5.2),

$$
v_{j} \nabla_{i} \phi=v_{i} \nabla_{j} \phi
$$

which implies that

$$
\nabla_{i} \phi=\alpha v_{i}
$$

for some scalar function $\alpha$.
Differentiating the equation above covariantly, we get

$$
\nabla_{j} \nabla_{i} \phi=v_{i} \nabla_{j} \alpha+\alpha \nabla_{j} v_{i},
$$

from which, using (5.1)

$$
2 \alpha f_{j i}=v_{j} \nabla_{i} \alpha-v_{i} \nabla_{j} \alpha .
$$

Thus, if $n>2$, we have $\alpha=0$, because the rank of $f_{j i}$ is almost everywhere maximum. This shows that $\phi$ is constant.

Lemma 5.4. Under the same assumptions as those in Lemma 5.1, we have

$$
\begin{equation*}
\left(\nabla_{j} u_{i}+\nabla_{i} u_{j}\right) u^{i}=-2 \lambda u_{j} \tag{5.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(\nabla_{j} v_{i}+\nabla_{i} v_{j}\right) v^{i}=2 \lambda \phi v_{j} . \tag{5.7}
\end{equation*}
$$

Proof. Differentiating

$$
u_{i} u^{i}=1-\lambda^{2}
$$

covariantly and using (5.4), we find

$$
2\left(\nabla_{j} u_{i}\right) u^{i}=-2 \lambda\left(u_{j}-\phi v_{j}\right) .
$$

Substituting this into

$$
2\left(\nabla_{j} u_{i}\right) u^{i}=\left\{\left(\nabla_{j} u_{i}+\nabla_{i} u_{j}\right)+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right)\right\} u^{i},
$$

or

$$
2\left(\nabla_{j} u_{i}\right) u^{i}=\left(\nabla_{j} u_{i}+\nabla_{i} u_{j}\right) u^{i}+2 \lambda \phi v_{j},
$$

we find

$$
-2 \lambda\left(u_{j}-\phi v_{j}\right)=\left(\nabla_{j} u_{i}+\nabla_{i} u_{j}\right) u^{2}+2 \lambda \phi v_{j},
$$

which proves (5.6).
Similarly, we can prove (5.7).
Theorem 5.1. Under the same assumptions as those in Lemma 5.1, both of the vector fields $u^{h}$ and $v^{h}$ define infinitesimal conformal transformations.

Proof. Transvecting (4.6) with $v^{2}$ and using (1.3), we find

$$
\begin{aligned}
& f_{j}^{t}\left(\nabla_{h} f_{t i}\right) v^{2}-\lambda u^{t} \nabla_{h} f_{t \jmath} \\
= & u_{j}\left(v^{i} \nabla_{i} u_{h}\right)+v_{j}\left(v^{i} \nabla_{i} v_{h}\right)-\left(1-\lambda^{2}\right) \nabla_{j} v_{h},
\end{aligned}
$$

from which

$$
\begin{aligned}
& f_{j}^{t}\left\{\nabla_{h}\left(f_{t} v_{i}\right)-f_{t}{ }^{i} \nabla_{h} v_{i}\right\}+\lambda\left\{\nabla_{h}\left(f_{j}^{t} u_{t}\right)-f_{j}^{t} \nabla_{h} u_{t}\right\} \\
= & u_{j}\left(v^{i} \nabla_{i} u_{h}\right)+v_{j}\left(v^{i} \nabla_{i} v_{h}\right)-\left(1-\lambda^{2}\right) \nabla_{j} v_{h},
\end{aligned}
$$

or, again using (1.2) and (1.3),

$$
\begin{aligned}
& -f_{j}^{t}\left\{\left(\nabla_{h} \lambda\right) u_{t}+\lambda \nabla_{h} u_{t}+f_{t}{ }^{i} \nabla_{h} v_{i}\right\} \\
& +\lambda\left\{\left(\nabla_{h} \lambda\right) v_{j}+\lambda \nabla_{h} v_{j}-f_{j}^{t} \nabla_{h} u_{t}\right\} \\
= & u_{j}\left(v^{i} \nabla_{i} u_{h}\right)+v_{j}\left(v^{i} \nabla_{i} v_{h}\right)-\left(1-\lambda^{2}\right) \nabla_{j} v_{h},
\end{aligned}
$$

that is,

$$
\begin{aligned}
& -2 \lambda f_{j}{ }^{t} \nabla_{h} u_{t}+\left(\delta_{j}^{i}-u_{j} u^{2}-v_{j} v^{i}\right) \nabla_{h} v_{i}+\lambda^{2} \nabla_{h} v_{j} \\
= & u_{j}\left(v^{i} \nabla_{i} u_{h}\right)+v_{j}\left(v^{i} \nabla_{i} v_{h}\right)-\left(1-\lambda^{2}\right) \nabla_{j} v_{h},
\end{aligned}
$$

or

$$
\begin{aligned}
& -2 \lambda f_{j}{ }^{t} \nabla_{h} u_{t}+\left(\nabla_{h} v_{j}+\nabla_{j} v_{h}\right)+\lambda^{2}\left(\nabla_{h} v_{j}-\nabla_{j} v_{h}\right) \\
= & u_{j} v^{i}\left(\nabla_{i} u_{h}-\nabla_{h} u_{j}\right)+v_{j} v^{i}\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}\right),
\end{aligned}
$$

or

$$
\begin{aligned}
& -2 \lambda f_{j}{ }^{t} \nabla_{h} u_{t}+\left(\nabla_{h} v_{j}+\nabla_{j} v_{h}\right)+2 \lambda^{2} f_{h j} \\
= & 2 \lambda \phi u_{j} u_{h}+v_{j} v^{i}\left(\nabla_{i} v_{h}+\nabla_{h} v_{i}\right) .
\end{aligned}
$$

Substituting

$$
\begin{aligned}
2 \nabla_{h} u_{t} & =\left(\nabla_{h} u_{t}+\nabla_{t} u_{h}\right)+\left(\nabla_{h} u_{t}-\nabla_{t} u_{h}\right) \\
& =\nabla_{h} u_{t}+\nabla_{t} u_{h}+2 \phi f_{h t}
\end{aligned}
$$

and (5.7) into the equation above, we find

$$
\begin{aligned}
& -\lambda f_{j} t\left(\nabla_{h} u_{t}+\nabla_{t} u_{h}\right)-2 \lambda \phi\left(g_{j h}-u_{j} u_{h}-v_{j} v_{h}\right) \\
& +\left(\nabla_{h} v_{j}+\nabla_{j} v_{h}\right)+2 \lambda^{2} f_{h j} \\
= & 2 \lambda \phi u_{j} u_{h}+2 \lambda \phi v_{j} v_{h}
\end{aligned}
$$

or

$$
\begin{equation*}
\nabla_{h} v_{j}+\nabla_{j} v_{h}=\lambda f_{j}\left(\nabla_{h} u_{t}+\nabla_{t} u_{h}\right)+2 \lambda \phi g_{h_{j}}-2 \lambda^{2} f_{h j} \tag{5.8}
\end{equation*}
$$

Similarly, we have

$$
\begin{equation*}
\nabla_{h} u_{j}+\nabla_{j} u_{h}=-\lambda f_{j}{ }^{t}\left(\nabla_{h} v_{t}+\nabla_{t} v_{h}\right)-2 \lambda g_{h j}-2 \lambda^{2} \phi f_{h j} . \tag{5.9}
\end{equation*}
$$

Substituting (5.8) into (5.9), we obtain, using (5.6),

$$
\begin{equation*}
\left(1-\lambda^{2}\right)\left(\nabla_{h} u_{j}+\nabla_{j} u_{h}\right)=-2 \lambda\left(1-\lambda^{2}\right) g_{h j}-2 \lambda^{3} v_{h} v_{j}-\lambda^{2} v^{t}\left(\nabla_{h} u_{t}+\nabla_{t} u_{s}\right) v_{j} . \tag{5.10}
\end{equation*}
$$

Transvecting (5.10) with $v^{3}$, we find

$$
\left(1-\lambda^{2}\right)\left(\nabla_{h} u_{j}+\nabla_{j} u_{h}\right) v^{j}=-2 \lambda\left(1-\lambda^{2}\right) v_{h}-2 \lambda^{3}\left(1-\lambda^{2}\right) v_{h}-\lambda^{2}\left(1-\lambda^{2}\right) v^{t}\left(\nabla_{h} u_{t}+\nabla_{t} u_{h}\right),
$$

or

$$
\left(1+\lambda^{2}\right)\left(1-\lambda^{2}\right)\left(\nabla_{h} u_{j}+\nabla_{j} u_{h}\right) v^{j}=-2 \lambda\left(1+\lambda^{2}\right)\left(1-\lambda^{2}\right) v_{h},
$$

from which

$$
\begin{equation*}
\left(\nabla_{h} u_{j}+\nabla_{j} u_{h}\right) v^{j}=-2 \lambda v_{h} . \tag{5.11}
\end{equation*}
$$

Substituting (5.11) into (5.10), we obtain
(5.12)

$$
\nabla_{j} u_{i}+\nabla_{i} u_{j}=-2 \lambda g_{j i} .
$$

Substituting (5.12) into (5.8), we find

$$
\begin{equation*}
\nabla_{j} v_{i}+\nabla_{i} v_{j}=2 \lambda \phi g_{j i} . \tag{5.13}
\end{equation*}
$$

Equations (5.12) and (5.13) show that both of the vector fields $u^{h}$ and $v^{h}$ define infinitesimal conformal transformations.

Using (5.12), (5.3) and

$$
\nabla_{j} u_{i}-\nabla_{i} u_{j}=2 \phi f_{j i}, \quad \nabla_{j} v_{i}-\nabla_{i} v_{j}=2 f_{j i},
$$

we have

$$
\begin{equation*}
\nabla_{j} u_{i}=-\lambda g_{j i}+\phi f_{j i}, \tag{5.14}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{j} v_{i}=\lambda \phi g_{j i}+f_{j i} . \tag{5.15}
\end{equation*}
$$

## §6. Covariant derivative of $\mathbf{2}$-form $\boldsymbol{f}_{\boldsymbol{j} i}$.

Theorem 6.1 If a manifold with normal metric ( $f, g, u, v, \lambda$ )-structure satisfies (5.1) and (5.2), and if $\lambda\left(1-\lambda^{2}\right)$ is an almost everywhere non-zero function, then we have

$$
\begin{equation*}
\nabla_{J} f_{i h}=-g_{j i}\left(\phi u_{h}+v_{h}\right)+g_{j h}\left(\phi u_{i}+v_{i}\right) . \tag{6.1}
\end{equation*}
$$

Proof. Substituting (5.14) and (5.15) into (4.6), we find

$$
\begin{aligned}
& f_{j}^{t} \nabla_{h} f_{t i}-f_{\imath}^{t} \nabla_{h} f_{t \jmath} \\
& =u_{j}\left(-\lambda g_{i n}+\phi f_{i n}\right)-u_{i}\left(-\lambda g_{j h}+\phi f_{j h}\right) \\
& \quad+v_{j}\left(\lambda \phi g_{i n}+f_{i h}\right)-v_{i}\left(\lambda \phi g_{j h}+f_{j h}\right),
\end{aligned}
$$

or

$$
\begin{aligned}
& \nabla_{h}\left(f_{j}^{t} f_{t i}\right)-\left(\nabla_{h} f_{j}\right) f_{t i}-f_{\imath} \nabla_{h} f_{t j} \\
= & -\lambda\left(u_{j}-\phi v_{j}\right) g_{i h}+\lambda\left(u_{i}-\phi v_{i}\right) g_{j h} \\
& +\left(\phi u_{j}+v_{j}\right) f_{i h}-\left(\phi u_{i}+v_{i}\right) f_{j h},
\end{aligned}
$$

from which

$$
\begin{aligned}
& \nabla_{h}\left(-g_{j i}+u_{j} u_{i}+v_{j} v_{i}\right)+2 f_{\imath} \nabla_{h} f_{t j} \\
= & -\lambda\left(u_{j}-\phi v_{j}\right) g_{i h}+\lambda\left(u_{i}-\phi v_{i}\right) g_{j h} \\
& +\left(\phi u_{j}+v_{j}\right) f_{i h}-\left(\phi u_{i}+v_{i}\right) f_{j h},
\end{aligned}
$$

or, using (5.14) and (5.15),

$$
\begin{equation*}
f_{j}^{t} \nabla_{n} f_{i t}=\lambda\left(u_{j}-\phi v_{j}\right) g_{i n}+\left(\phi u_{i}+v_{i}\right) f_{j h} . \tag{6.2}
\end{equation*}
$$

Transvecting (6.2) by $f_{k^{3}}$ and using (1.1), we find

$$
\begin{aligned}
& -\nabla_{h} f_{i k}+u_{k} u^{t} \nabla_{h} f_{i t}+v_{k} v^{t} \nabla_{h} f_{i t} \\
= & \lambda^{2}\left(\phi u_{k}+v_{k}\right) g_{i h}-\left(\phi u_{i}+v_{i}\right)\left(g_{h k}-u_{h} u_{k}-v_{h} v_{k}\right),
\end{aligned}
$$

or

$$
\begin{aligned}
& -\nabla_{h} f_{i k}+u_{k}\left\{\nabla_{h}\left(f_{2}{ }^{t} u_{t}\right)-f_{2}{ }^{t} \nabla_{h} u_{t}\right\}+v_{k}\left\{\nabla_{h}\left(f_{\imath} v_{t}\right)-f_{\imath} \nabla_{h} v_{t}\right\} \\
= & \lambda^{2}\left(\phi u_{k}+v_{k}\right) g_{i h}-\left(\phi u_{i}+v_{i}\right)\left(g_{h k}-u_{h} u_{k}-v_{h} v_{k}\right),
\end{aligned}
$$

from which, using (1.2) and (1.3),

$$
\begin{aligned}
& -\nabla_{h} f_{i k}+u_{k}\left\{\left(\nabla_{h} \lambda\right) v_{i}+\lambda\left(\nabla_{h} v_{i}\right)-f_{i}{ }^{t} \nabla_{h} u_{t}\right\} \\
& -v_{k}\left(\left(\nabla_{h} \lambda\right) u_{i}+\lambda\left(\nabla_{h} u_{i}\right)+f_{2}{ }^{t} \nabla_{h} v_{t}\right\} \\
= & \lambda^{2}\left(\phi u_{k}+v_{k}\right) g_{i h}-\left(\phi u_{i}+v_{i}\right) g_{h k}+\left(\phi u_{i}+v_{i}\right)\left(u_{h} u_{k}+v_{h} v_{k}\right) .
\end{aligned}
$$

Substituting (5.4), (5.14) and (5.15) into this equation, we find

$$
\begin{aligned}
& -\nabla_{h} f_{i k}+u_{k}\left\{\left(u_{h}-\phi v_{h}\right) v_{i}+\lambda\left(\lambda \phi g_{h i}+f_{h i}\right)-f_{\imath}^{t}\left(-\lambda g_{h t}+\phi f_{h t}\right)\right\} \\
& -v_{k}\left\{\left(u_{h}-\phi v_{h}\right) u_{i}+\lambda\left(-\lambda g_{h i}+\phi f_{h i}\right)+f_{\imath}^{t}\left(\lambda \phi g_{h t}+f_{h t}\right)\right\} \\
= & \lambda^{2}\left(\phi u_{k}+v_{k}\right) g_{i h}-\left(\phi u_{i}+v_{i}\right) g_{h k}+\left(\phi u_{i}+v_{i}\right)\left(u_{h} u_{k}+v_{h} v_{k}\right),
\end{aligned}
$$

which proves (6.1).
We have seen that if a manifold with normal ( $f, g, u, v, \lambda$ )-structure satisfies

$$
\nabla_{j} u_{i}-\nabla_{i} u_{j}=2 \phi f_{j i}, \quad \nabla_{j} v_{i}-\nabla_{i} v_{j}=2 f_{j i},
$$

then

$$
\nabla_{J} f_{i h}=-g_{j i}\left(\phi u_{h}+v_{h}\right)+g_{j h}\left(\phi u_{i}+v_{i}\right)
$$

Conversely, we have
Theorem 6.2. If $a(f, g, u, v, \lambda)$-structure satisfies (5.1), (5.2) and (6.1) then the structure is normal.

Proof. Substituting (6.1) into

$$
\begin{aligned}
S_{j i}{ }^{h}= & f_{j}{ }^{t} \nabla_{t} f_{i}{ }^{h}-f_{\imath}{ }^{t} \nabla_{t} f_{j}{ }^{h}-\left(\nabla_{J} f_{i}^{t}-\nabla_{\imath} f_{j}{ }^{t}\right) f_{t}^{h} \\
& +\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h},
\end{aligned}
$$

we have

$$
\begin{aligned}
S_{j i}{ }^{h}= & f_{j}^{t}\left\{-g_{t i}\left(\phi u^{h}+v^{h}\right)+\delta_{t}^{h}\left(\phi u_{i}+v_{i}\right)\right\} \\
& -f_{\imath}^{t}\left\{-g_{t j}\left(\phi u^{h}+v^{h}\right)+\delta_{t}^{h}\left(\phi u_{j}+v_{j}\right)\right\} \\
& -\left\{\delta_{j}^{t}\left(\phi u_{i}+v_{i}\right)-\delta_{i}^{t}\left(\phi u_{j}+v_{j}\right)\right\} f_{t}^{h}+2 \phi f_{j i} u^{h}+2 f_{j i} v^{h} \\
= & 0,
\end{aligned}
$$

and consequently the structure is normal.

## §7. Characterizations of even dimensional spheres.

We prove
Theorem 7.1. Let $M$ be a complete manifold with normal ( $f, g, u, v, \lambda$ )-structure satisfying (5.1) and (5.2). If $\lambda\left(1-\lambda^{2}\right)$ is an almost everywhere non-zero function and $n>2$ then $M$ is isometric with an even dimensional sphere.

Proof. Differentiating (5.4) covariantly, we have

$$
\nabla_{j} \nabla_{i} \lambda=\nabla_{j} u_{i}-\phi \nabla_{j} v_{i},
$$

$\phi$ being a constant, from which, using (5.14) and (5.15),

$$
\begin{equation*}
\nabla_{j} \nabla_{i} \lambda=-\left(1+\phi^{2}\right) \lambda g_{j i} . \tag{7.1}
\end{equation*}
$$

Thus, $\lambda$ being not identically zero, by a famous theorem of Obata [6], $M$ is isometric with a sphere.

We next prove
Theorem 7.2. Let $M$ be a complete manifold with normal ( $f, g, u, v, \lambda$ )-structure satisfying

$$
\begin{equation*}
\nabla_{j} v_{i}=f_{j i} . \tag{7.2}
\end{equation*}
$$

If $\lambda\left(1-\lambda^{2}\right)$ is an almost everywhere non-zero function, then $M$ is isometric with an even dimensional sphere.

Proof. Differentiating

$$
v_{i} v^{2}=1-\lambda^{2}
$$

covariantly and using (7.2), we find

$$
f_{j i} v^{v}=-\lambda \nabla_{j} \lambda
$$

or

$$
\lambda\left(\nabla_{j} \lambda-u_{j}\right)=0,
$$

from which

$$
\nabla_{j} \lambda=u_{j} .
$$

This shows that

$$
\nabla_{j} u_{i}-\nabla_{i} u_{j}=0 .
$$

Equation (7.2) shows that

$$
\nabla_{j} v_{i}-\nabla_{i} v_{j}=2 f_{j i} .
$$

Thus all the assumptions of Theorem 7.1 are satisfied, and consequently $M$ is isometric with an even dimensional sphere.

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