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A CHARACTERIZATION OF THE NORMAL DISTRIBUTION1

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1. Introduction. Using characteristic functions Lukacs [3] has shown that a necessary and sufficient condition for the independence of the sample mean and variance is that the parent population be normal. Geisser [2] has derived a similar theorem concerning the sample mean and the first order mean square successive difference. In section 2 of this note a general theorem of which Lukacs' and Geisser's results are particular cases has been proved.

Lukacs [3] has extended his theorem to the multivariate case, namely, that a necessary and sufficient condition that the sample mean vector is distributed independently of the variance-covariance matrix is that the parent population be multivariate normal. In section 3, the general theorem of section 2 is extended to the multivariate population of which Lukacs' theorem for the multivariate population is a particular case. To prove the necessity of this theorem, we extend, to the multivariate case, Daly's [1] result that if f(x) is the normal density, then the sample mean and $g(x_1 \cdots x_n)$ are independently distributed where $g(x_1 \cdots x_n) = g(x_1 + a, \cdots, x_n + a)$.

2. Univariate case. Let x_1, \dots, x_n be independent and identically distributed with density function f(x) and mean μ and variance σ^2 . Let.

$$(2.1) \bar{x} = n^{-1} \sum_{i=1}^{n} x_i \cdots$$

and

(2.2)
$$\delta^2 = \left(\sum_{t=1}^m \sum_{j=1}^n l_{tj}^2\right)^{-1} \sum_{t=1}^m (l_{t1}x_1 + \cdots + l_{tn}x_n)^2, \qquad m \ge 1$$

where

$$\sum_{j=1}^n l_{tj} = 0 \quad \text{for} \quad t = 1, \cdots, m.$$

The following theorem is proved.

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THEOREM 1. A necessary and sufficient condition that f(x) be the normal density is that \bar{x} and δ^2 are independent.

PROOF. Following Lukacs [3] we derive the sufficiency. Now,

$$E(\delta^{2}) = \left(\sum_{t=1}^{m} \sum_{j=1}^{n} l_{tj}^{2}\right)^{-1} \left\{\sum_{t}^{m} \sum_{j}^{n} l_{tj}^{2} E(x_{j}^{2}) + \sum_{t=1}^{m} \sum_{j \neq j'}^{n} l_{tj} l_{tj'} E(x_{j} x_{j'})\right\}$$

$$= \sigma^{2}$$

The joint characteristic function of \bar{x} and δ^2 is

$$\phi(t_1, t_2) = \int \int \cdots \int e^{it_1\bar{x}} e^{it_2\bar{x}^2} f(x_1) \cdots f(x_n) dx_1 \cdots dx_n.$$

Therefore

(2.3)
$$\frac{\partial}{\partial t_2} \phi(t_1, t_2) \mid_{t_2=0} = \phi_1(t_1) \frac{\partial}{\partial t_2} \phi_2(t_2) \mid_{t_2=0},$$

where

$$\phi_1(t_1) = \left[\psi(t_1/n) \right]^n$$

and

$$\psi(t_{1}) = \int e^{it_{1}x}f(x) dx,$$

$$\frac{\partial}{\partial t_{2}} \phi(t_{1}, t_{2}) |_{t_{2}=0} = i \left(\sum_{t} \sum_{j} l_{tj}^{2} \right)^{-1} \left\{ \left(\sum_{t} \sum_{j} l_{tj}^{2} \right) [\psi(t_{1}/n)]^{n-1} \int x^{2} e^{it_{1}x/n} f(x) dx + 2 \left(\sum_{t} \sum_{j \neq j'} l_{tj} l_{tj'} \right) [\psi(t_{1}/n)]^{n-2} \left[\int x e^{it_{1}x/n} f(x) dx \right]^{2} \right\}$$

$$= i \left\{ [\psi(t_{1}/n)]^{n-1} \int x^{2} e^{it_{1}x/n} f(x) dx - [\psi(t_{1}/n)]^{n-2} \left[\int x e^{it_{1}x/n} f(x) dx \right]^{2} \right\},$$

and

$$\frac{\partial}{\partial t_0} \phi_2(t_2) \mid_{t_2=0} = i\sigma^2.$$

Hence, Eq. (2.3) reduces to

$$(2.5) -\psi(t) \frac{d^2\psi(t)}{dt^2} + \left\lceil \frac{d\psi(t)}{dt} \right\rceil^2 = \sigma^2 [\psi(t)]^2,$$

the solution of which is the characteristic function of the normal distribution. The necessary condition follows from Daly [1] who has proved that \bar{x} and $g(x_1 \cdots x_n)$ are independent in the normal case, if

$$g(x_1 \cdots x_n) = g(x_1 + a, \cdots, x_n + a).$$

Since δ^2 is invariant under a translation, the theorem is proved.

In fact, the above result can easily be extended² to cover a more general class of quadratic forms, namely those which are invariant under a translation and have non-zero expected values. For, Lukacs' method can be applied even when δ^2 is defined as follows:

(2.6)
$$\delta^2 = \left(\sum_{i=1}^m \sum_{j=1}^n a_{iij}\right)^{-1} \left[\sum_{i=1}^m \sum_{i,j=1}^n a_{iij} x_i x_j\right], \qquad m \ge 1,$$

where $\sum_{j=1}^{n} a_{iij} = 0$ $(t = 1, \dots, m, i = 1, \dots, n)$, provided

$$\sum_{j=1}^n a_{tij} \neq 0 \ (t = 1, \cdots, m).$$

It will be noted that δ^2 defined in (2.2) above is a special case of δ^2 defined in (2.6) by putting $a_{tij} = l_{ti}l_{tj}$.

Particular Cases.

(a) To obtain Lukacs' result, put

$$l_{tj} = 1 - \frac{1}{n}$$
 for $t = j$
= $\frac{-1}{n}$ for $t \neq j$
and $m = n$.

(b) To get Geisser's result, put

$$l_{tj} = 1$$
 when $j = t + k$
 $= -1$ when $j = t$
 $= 0$ for other values of j
and $m = n - k$.

(c) An interesting extension of Geisser's result is: a necessary and sufficient condition for the independence of the sample mean and any order mean square successive difference is that the parent population be normal.

The rth order mean square successive difference is given by,

$$\delta_r^2 = (n-r)^{-1} \left\{ \binom{r}{0}^2 + \cdots + \binom{r}{r-1}^2 + \binom{r}{r}^2 \right\}^{-1} \sum_{t=1}^{n-r} (\Delta^r x_t)^2, \qquad r \geq 1.$$

where

$$\Delta^{r} x_{t} = \begin{pmatrix} r \\ 0 \end{pmatrix} x_{t+r} - \begin{pmatrix} r \\ 1 \end{pmatrix} x_{t+r-1} + \cdots + (-1)^{r} \begin{pmatrix} r \\ r \end{pmatrix} x_{t}.$$

To get the above result, put

$$l_{tj} = (-1)^{t+r-j} \binom{r}{t+r-j} \quad \text{when} \quad t \le j \le t+r$$

$$= 0 \quad \text{when} \quad 1 \le j \le t-1 \quad \text{and} \quad t+r+1 \le j \le n,$$
and $m = n-r.$

² I am indebted to the referee for pointing this out.

3. Multivariate case. The same reasoning applies also to the multivariate case. Denote by $x_{\alpha i}$ ($\alpha = 1, \dots, n$; $i = 1, \dots, p$) the α observation on the *i*th variate, by \bar{x}_i , the sample mean of the *i*th variate,

(3.1)
$$\delta_{ij} = \left[\left(\sum_{t=1}^{m} \sum_{\alpha=1}^{n} l_{t\alpha}^{2} \right) \right]^{-1} \sum_{t=1}^{m} \left\{ \sum_{\alpha,\alpha'}^{n} l_{t\alpha} l_{t\alpha'} x_{\alpha i} x_{\alpha' j} \right\},$$

or more generally.

(3.2)
$$\delta_{ij} = \left[\left(\sum_{t=1}^{m} \sum_{\alpha=1}^{n} a_{t\alpha\alpha} \right) \right]^{-1} \sum_{t=1}^{m} \left\{ \sum_{\alpha,\alpha'}^{n} a_{t\alpha\alpha'} x_{\alpha i} x_{\alpha' j} \right\} \qquad (i, j = 1, \dots, p),$$

where $\sum_{\alpha'=1}^{n} a_{t\alpha\alpha'} = 0$ $(t = 1, \dots, m; \alpha = 1, \dots, n)$, provided

$$\sum_{\alpha=1}^n a_{t\alpha\alpha} \neq 0 \ (t=1, \cdots, m).$$

Assuming that the distribution of $[\delta_{ij}]_{p \times p}$ is independent of the joint distribution of the p sample means $(\bar{x}_1, \dots, \bar{x}_p)$ one obtains the equation,

$$\frac{\psi_{ij}}{\psi} - \frac{\psi_i \psi_j}{\psi^2} = -\lambda_{ij},$$

where λ_{ij} is population covariance of the variates x_i and x_j ,

$$\psi = \psi(t_1, \dots, t_p) = \iint \dots \int e^{\iota(t_1 x_1 + \dots + t_p x_p)} f(x_1 \dots x_p) dx_1 \dots dx_p.$$

$$\psi_i = \frac{\partial \psi}{\partial t_i}, \qquad \psi_{ij} = \frac{\partial^2 \psi}{\partial t_i \partial t_i}$$

If (3.3) is true for $i, j = 1, \dots, p$, one has a set of partial differential equations which leads to the characteristic function to the multivariate normal distribution.

To prove the necessity, we give an extension of Daly's [1] lemma of which it is a particular casc.

THEOREM 2. Let $g_l(x_{11}, \dots, x_{n1}; \dots; x_{1p}, \dots, x_{np})$, $l = 1, \dots, r$, be functions of $(x_{11}, \dots, x_{n1}); \dots, (x_{1p}, \dots, x_{np})$ and are such that

$$g_l(x_{11} + a_1, \dots, x_{n1} + a_1; \dots; x_{1p} + a_p, \dots, x_{np} + a_p)$$

= $g_l(x_{11}, \dots, x_{n1}; \dots; x_{1p}, \dots, x_{np}).$

The sample means $(\bar{x}_1, \dots, \bar{x}_p)$ are independently distributed of these r functions if $f(x_1 \dots x_p)$ has a p-variate normal distribution.

PROOF. The joint characteristic function is

$$\phi(t_1, \dots, t_p; \xi_1, \dots, \xi_r)$$

$$= \frac{1}{(2\pi)^{np/2} |\lambda_{ij}|^{n/2}} \int \dots \int \exp\left\{\iota \sum_{\alpha=1}^n t_i x_{\alpha i}/n\right\} \exp\left\{\iota \sum_{l=1}^r \xi_l g_l\right\}$$

$$\exp\left\{-\frac{1}{2} \sum_{\alpha=1}^n \sum_{i,j=1}^p \lambda^{ij} x_{\alpha i} x_{\alpha j}\right\} \times \prod_{\alpha=1}^n [dx_{\alpha 1} \dots dx_{\alpha p}],$$
where $(\iota)^2 = -1$.

Make the contragradient transformation

$$x_{\alpha i} = \sum_{j=1}^{p} c_{ij} y_{\alpha j}, \qquad t_{i} = \sum_{j=1}^{p} c_{ij} u_{j} \qquad i = 1, \dots, p; \alpha = 1, \dots, n.$$

Then,

$$\phi(t_1, \cdots, t_p; \xi_1, \cdots, \xi_r)$$

$$= \frac{1}{(2\pi)^{np/2} |\lambda_{ij}|^{n/2}} \int \cdots \int \exp\left\{\iota \sum_{\alpha=1}^{n} \sum_{i=1}^{p} u_{i} y_{\alpha i} / n\right\} \exp\left\{\iota \sum_{l=1}^{r} \xi_{l} g'_{l}\right\}$$

$$\exp\left\{-\frac{1}{2} \sum_{\alpha=1}^{n} \sum_{i=1}^{p} y_{\alpha i}^{2} / \rho_{i}\right\} \times \prod_{\alpha=1}^{n} [dy_{\alpha 1} \cdots dy_{\alpha p}],$$

where ρ_1 , \cdots , ρ_p are latent roots of the variance-covariance matrix and

$$g'_{i}(y_{11} + a_{1}, \dots, y_{n1} + a_{1}; \dots; y_{1p} + a_{p}, \dots, y_{np} + a_{p})$$

$$= g'_{i}(y_{11}, \dots, y_{n1}; \dots; y_{1p}, \dots, y_{np}).$$

Put

$$\frac{y_{\alpha i}}{\sqrt{\rho_i}} - \frac{\iota u_i \sqrt{\rho_i}}{n} = Z_{\alpha i};$$

then

$$\phi(t_1, \cdots, t_p; \xi_1, \cdots, \xi_r)$$

$$= \frac{1}{(2\pi)^{np/2}} \int \cdots \int \exp\left\{-\frac{1}{2n} \sum_{i,j=1}^{p} \lambda_{ij} t_i t_j\right\} \exp\left\{\iota \sum_{l=1}^{r} \xi_l g_l^{\prime\prime}\right\}$$
$$\exp\left\{-\frac{1}{2} \sum_{\alpha=1}^{n} \sum_{i=1}^{p} Z_{\alpha i}^2\right\} \times \prod_{\alpha=1}^{n} [dZ_{\alpha 1} \cdots dZ_{\alpha p}],$$

where

$$g_i'' = g_i'(Z_{11}\sqrt{\rho_1}, \dots, Z_{n1}\sqrt{\rho_1}; \dots; Z_{1p}\sqrt{\rho_p}, \dots, Z_{np}\sqrt{\rho_p})$$

and hence is a function of $(Z_{11}, \dots, Z_{n1}); \dots; (Z_{1p}, \dots, Z_{np})$ only. Therefore,

$$\phi(t_1, \cdots, t_p; \xi_1, \cdots, \xi_r)$$

=
$$\exp\left\{-\frac{1}{2n}\sum_{i,j=1}^{p}\lambda_{ij} t_i t_j\right\} \times \text{(a function of } \xi_1, \dots, \xi_r \text{ only)}.$$

Hence the theorem.

Particular case. The sample mean vector $(\bar{x}_1 \cdots \bar{x}_p)$ is independently distributed of products moments of any order if $f(x_1 \cdots x_p)$ has a p-variate normal density.

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A NOTE ON P.B.I.B. DESIGN MATRICES

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Summary. The notation P.B.I.B. (m) will mean partially balanced incomplete block design with m associative classes.

It is found that the C matrix of a P.B.I.B (m) may be expressed as a linear function of m+1 commutative and linearly independent matrices. The author feels that this decomposition may be of interest to those studying the properties of P.B.I.B. designs.

1. The C matrix of a P.B.I.B. design. The reader should review the definition of partially balanced designs, and the relations among the parameters. See, for example, Bose and Shimamoto [2], or Bose [1], or Connor and Clatworthy [3].

The matrix

$$C = (c_{ij}),$$

where

$$c_{ii} = r(1 - 1/k),$$

 $c_{ij} = -\lambda_{ij}/k,$ $i \neq j$

is of special interest in incomplete block design theory.

In the case of a P.B.I.B. (m), the C matrix may be written in a particular form. We may write

(1.1)
$$kC = r(k-1)I - \sum_{i=1}^{m} \lambda_{i} B_{i},$$

where $B_s = [b_{ij}^{(s)}]$ for $s = 1, \dots, m$, where $b_{it}^{(s)} = 0$ and $b_{ij}^{(s)} = 1$ or 0 according as the treatments t and j are or are not sth associates. Note that I, B_1 , B_2 , \dots , B_m form a linearly independent set of matrices since a one in the (i, j)th position of any of them implies a zero in the (i, j)th position of all the others. $b_{hj}^{(s)}b_{ht}^{(s)}$ equals 1 if treatment j and treatment j are both sth associates of treatment j, but equals 0 otherwise. If $j \neq t$ then $\sum_i b_{ij}^{(s)}b_{it}^{(s)}$ is the number of treatments which are sth associates of both treatments j and t. But if j and t

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