RELATIVELY INVARIANT SYSTEMS AND THE SPECTRAL MAPPING THEOREM

BY ROBIN HARTE

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- 1. **Introduction**. In this note we consider the extension of the spectral mapping theorem ([2], [3]) to certain noncommuting systems of elements, notably the 'quasi-commuting' systems of McCoy [5]. Full proofs and more detail are to appear elsewhere [4].
- 2. **Relative joint spectra.** Suppose $a = (a_1, a_2, ..., a_n)$ is a system of elements in a complex Banach algebra A, with identity 1: then the *joint spectrum* of a with respect to A is ([2]; [3, Definition 1.1]) the set $\sigma(a) = \sigma_A^{\text{joint}}(a)$ of those systems $s = (s_1, s_2, ..., s_n)$ of complex numbers for which the system $a s = (a_1 s_1, a_2 s_2, ..., a_n s_n)$ generates a proper left, or proper right, ideal in A. The 'one-way' spectral mapping theorem ([2]; [3, Theorem 3.2]) is the inclusion

$$(2.1) f\sigma(a) \subseteq \sigma f(a),$$

valid for an arbitrary system $a \in A^n$ of elements and an arbitrary system $f = (f_1, f_2, \dots, f_m): A^n \to A^m$ of 'polynomials' in several variables on A. Equality

(2.2)
$$\sigma f(a) = f\sigma(a)$$

is attained [3, Corollary 3.3] if the system of polynomials has a 'left inverse' $g: A^m \to A^n$ for which g(f(a)) = a, or alternatively if the system of elements is commutative ([2]; [3, Theorem 4.3]). This second case is our 'spectral mapping theorem', of which we here consider the extension.

DEFINITION 1. The joint spectrum of $b \in A^m$ relative to $a \in A^n$ in A is the set

(2.3)
$$\sigma_{a=a}(b) = \{t \in \sigma(b) : \exists s \in \sigma(a), (s,t) \in \sigma(a,b)\}.$$

The idea is to offer a measurement of the failure of equality in (2.1); for example there is equality

(2.4)
$$\sigma_{f(a)=f(a)}(a) = \sigma(a)$$

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for arbitrary systems of elements and of polynomials, using (2.1). Equality in (2.1) for arbitrary systems of elements and 'left invertible' polynomials is derived [3, Corollary 3.3] from the equality

(2.5)
$$\sigma_{a=a}f(a) = f\sigma(a),$$

valid without restriction. The spectral mapping theorem is derived from the result ([2]; [3, Theorem 4.2]) that if $b \in A^m$ is an arbitrary system of elements, and $a \in A^n$ a commuting system commuting with b, then

(2.6)
$$\sigma(b) = \sigma_{a=a}(b).$$

To derive (2.2) for a commuting system of elements we substitute b = f(a) in (2.6) and combine with (2.5).

3. **Relatively invariant systems.** The next idea is taken straight from the proof of (2.6):

DEFINITION 2. The system $b \in A^m$ is invariant under the system $a \in A^n$ in A if there is inclusion, for each element a_i ,

(3.1)
$$\left(\text{closure } \sum_{k=1}^{m} Ab_k \right) a_j \subseteq \text{closure } \sum_{k=1}^{m} Ab_k$$

and

(3.2)
$$a_j \left(\text{closure } \sum_{k=1}^m b_k A \right) \subseteq \text{closure } \sum_{k=1}^m b_k A;$$

if $b - t \in A^m$ is invariant under $a \in A^n$ for every system $t \in C^m$ of scalars then $b \in A^m$ is completely invariant under a.

For example if $t \in C^m$ is not in the joint spectrum $\sigma(b)$ then $b - t \in A^m$ is invariant under arbitrary systems $a \in A^n$; if $a \in A^n$ commutes with $b \in A^m$ then b is completely invariant under a. For a fixed system $b \in A^m$ the set of elements $c \in A$ which leave b invariant form a closed subalgebra:

LEMMA 1. If $b-t \in A^m$ is invariant under $a \in A^n$ then also b-t is invariant under $f(a) \in A^p$, for an arbitrary system of polynomials $g: A^{n+m} \to A^p$ there is also inclusion, for each i,

(3.3)
$$g_i(a,b) - g_i(a,t) \in \left(\text{closure } \sum_{k=1}^m A(b_k - t_k)\right) \cap \left(\text{closure } \sum_{k=1}^m (b_k - t_k)A\right).$$

This result is built up for sums of products of polynomials $g_i(a, b) = b_k$ and $g_i(a, b) = f(a)$. An immediate corollary has applications in the theory of 'operator matrices':

COROLLARY 1. If $b - t \in A^m$ is invariant under $a \in A^n$ and $g: A^{n+m} \to A^p$ is a system of polynomials then there is logical equivalence, for $r \in C^p$,

$$(3.4) (t,r) \in \sigma(b,g(a,b)) \Leftrightarrow (t,r) \in \sigma(b,g(a,t)).$$

Equality (2.6) holds for a commuting system $a \in A^n$ of elements leaving the system $b \in A^m$ invariant:

THEOREM 1. If $b \in A^m$ is completely invariant under the commuting system $a \in A^n$ then there is equality $\sigma(b) = \sigma_{a=a}(b)$.

The proof is the same as in the case ([2]; [3, Theorem 4.2]) in which $a \in A^n$ commutes with $b \in A^m$. Recalling the induction (on the length n of the system $a \in A^n$), it is clear that it is far from necessary, here, for the system $a \in A^n$ to be commutative. Sufficient, for example, would be that, for each j = 1, 2, ..., n - 1,

(3.5)
$$(a_1, a_2, ..., a_i)$$
 is completely invariant under a_{i+1} .

Also it is always sufficient, for equality (2.6), that there exist some system $c \in A^p$ satisfying

(3.6)
$$\sigma(b) = \sigma_{c=c}(b) \quad and \quad \sigma(b,c) = \sigma_{a=a}(b,c).$$

We need the extension of Theorem 1 by the principle (3.6) to handle the 'quasicommuting' systems of the next section.

4. Quasicommuting systems. The idea of a 'quasicommuting' pair of matrices is due to McCoy [5]. To extend this to systems of Banach algebra elements we introduce a somewhat artificial 'commutator' for two systems of elements:

DEFINITION 3. The commutator of $a \in A^n$ with respect to $b \in A^m$ is the system of mn elements

$$(4.1) ba - ab = (b_1a_1 - a_1b_1, b_1a_2 - a_2b_1, \\ \dots, b_1a_n - a_nb_1, b_2a_1 - a_1b_2, \dots, b_ma_n - a_nb_m).$$

The system $b \in A^m$ is said to quasicommute with the system $a \in A^n$ if

$$(4.2) ba - ab \in A^{mn} commutes with (a, b) \in A^{n+m};$$

if this is true with b = a then a is called a quasicommuting system.

Observe that the relation (4.2) is symmetric in a and b. We make frequent use of the *Kleinecke-Sirokov* theorem [1, Problem 184]: if $a \in A^n$ and $b \in A^m$, and if the commutator ba - ab commutes either with $a \in A^n$ or with $b \in A^m$ then there is inclusion

$$(4.3) \sigma(ba-ab) \subseteq \{(0,0,\ldots,0)\} \subseteq C^{mn}.$$

LEMMA 2. Suppose $a \in A^n$ and $b \in A^m$: if the commutator ba - ab commutes with the system a then

$$(4.4)$$
 $(b, ba - ab)$ is completely invariant under a.

If ba - ab commutes with (a, b) then for an arbitrary system $f: A^m \to A^p$ of polynomials

(4.5)
$$(f(b), ba - ab)$$
 is completely invariant under a.

The first part of this follows at once, using (4.3). For the second we associate with each polynomial f_i a system $f'_i:A^m \to A^m$ for which, whenever an element a_i quasicommutes with the system $b \in A^m$,

(4.6)
$$f_i(b)a_j - a_j f_i(b) = \sum_{k=1}^m f'_{ik}(b)(b_k a_j - a_j b_k).$$

THEOREM 2. Suppose $a \in A^n$ and $b \in A^m$: if the commutator ba - ab is commutative and commutes with the system b then there is equality

(4.7)
$$\sigma(b) = \sigma_{ba-ab=ba-ab}(b).$$

If instead the system a is quasicommutative and commutes with ba - ab then there is equality

$$(4.8) \sigma(b, ba - ab) = \sigma_{a=a}(b, ba - ab).$$

If $a \in A^n$ is quasicommutative and quasicommutes with $b \in A^m$, and if $g: A^{n+m} \to A^p$ is a system of polynomials, then there is equality

(4.9)
$$\sigma g(a,b) = \sigma_{a=a}g(a,b).$$

The first part (4.7) follows straight from Theorem 1. For a single element $a = a_1$ the second part (4.8) uses Theorem 1, together with the easy part (4.4) of Lemma 2; then we proceed by induction on n, using the argument of (3.6).

Towards (4.9) it is another application of Theorem 1 that there is equality $\sigma g(a, b) = \sigma_{ba-ab=ba-ab}g(a, b)$, since our assumptions make ba-ab commutative and commute with g(a, b). Also for a single element $a=a_1$ we apply the second part (4.5) of Lemma 2, with (b, a) in place of b, to see that (g(a, b), ba-ab) is completely invariant under a, and again apply Theorem 1, to obtain $\sigma(g(a, b), ba-ab) = \sigma_{a=a}(g(a, b), ba-ab)$. Another induction on n, and then (3.6), establish (4.9).

COROLLARY 2. If $a \in A^n$ is quasicommutative and $f: A^n \to A^m$ is a system of polynomials then there is equality $\sigma f(a) = f\sigma(a)$.

For substitute g(a, b) = f(a) in (4.9) and use (2.5).

The extension of (2.6) to quasicommutative systems is clear from (4.7) and (4.8), and uses only the first part (4.4) of Lemma 2. We are unable to simply substitute b = f(a) at this stage because the system f(a) does not always quasicommute with a quasicommuting system $a \in A^n$.

If A is the algebra of 'upper triangular' $q \times q$ matrices then it is apparent [3, Example 2.3] that the conclusions of Theorem 2 and Corollary 2 hold for arbitrary systems $a \in A^n$ and $b \in A^m$: it follows that neither the conditions for (4.7) nor the conditions for (4.8) are necessary for (4.9). Equally neither condition is separately sufficient:

Example. In the algebra of all 3×3 complex matrices take

$$U = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \quad V = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \quad and \quad W = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & -1 \end{pmatrix}$$

then VU - UV = U but $\sigma(V) \neq \sigma_{U=U}(V)$. Also W = VU + UV + Vbut $\sigma(W) \neq \sigma_{V=V}(W)$.

We are unable to settle whether or not the conditions for (4.7) are sufficient for equality (2.6); recall for example [6, §2-3] the derivation of (2.6) when $a = a_1$ and ba - ab = b.

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DEPARTMENT OF MATHEMATICS, UNIVERSITY COLLEGE, CORK, IRELAND