# ON CERTAIN HYPERSURFACES IN A REAL SPACE FORM 

Dedicated to Professor Shigeo Sasaki on his 60th birthday

Takehiro Itoh and Hisao Nakagawa*)
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Using the formula of Simons' type, many and interested studies have recently been done for hypersurfaces in a real space from. As one of special situations, they have common pattern that the second fundamental form has distinct constant eigenvalues. On the other hand, T. Otsuki [1] has investigated the problem to determine all minimal hypersurfaces immersed in a sphere on which the number of distinct principal curvatures is equal to two.

The purpose of this paper is to study hypersurfaces in a real space form such that the second fundamental form has at most two distinct eigenvalues. In §2, we study hypersurfaces in a real space form such that the product of two distinct eigenvalues is equal to minus of the curvature in the ambient space. In § 3, we treat connected and complete hypersurfaces in a hyperbolic space which have the same curvature as that of the ambient space and we shall show that there exist many examples of such hypersurfaces which are not totally geodesic.

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1. Preliminaries. Let $M$ be an $m$-dimensional Riemannian manifold isometrically immersed in an $(m+1)$-dimensional Riemannian manifold $\bar{M}$ of constant curvature $\bar{c}$ with the immersion $f: M \rightarrow \bar{M}$. Let $F(M)$ and $F(\bar{M})$ be the bundles of all orthonormal frames over $M$ and $\bar{M}$ respectively. Let $B$ be the set of all elements $b=\left(x, e_{1}, e_{2}, \cdots, e_{m}, e_{m+1}\right) \in$ $F(\bar{M})$ such that $\left(x, e_{1}, e_{2}, \cdots, e_{m}\right) \in F(M)$, identifying $x \in M$ with $f(x)$ in $\bar{M}$ and $e_{i}$ with $d f\left(e_{i}\right)$ for $i=1,2, \cdots, m$. Then, $B$ is considered as a smooth submanifold of $F(\bar{M})$. We have, as is well known, a system of differential 1-forms $\omega_{i}, \omega_{i j}, \omega_{i m+1}(i, j=1,2, \cdots, m)$ and $\omega_{m+1}$ on $B$ associated with the immersion $f$ such that

[^0]\[

\left\{$$
\begin{array}{l}
\omega_{i j}=-\omega_{j i}, \omega_{i m+1}=-\omega_{m+1 i}, \omega_{m+1}=0  \tag{1.1}\\
d \omega_{i}=\sum_{j=1}^{m} \omega_{i j} \wedge \omega_{j}, \\
d \omega_{i j}=\sum_{k=1}^{m} \omega_{i k} \wedge \omega_{k j}+\omega_{i m+1} \wedge \omega_{m+1 j}-\bar{c} \omega_{i} \wedge \omega_{j} \\
d \omega_{i m+1}=\sum_{j=1}^{m} \omega_{i j} \wedge \omega_{j m+1},
\end{array}
$$\right.
\]

and

$$
\begin{equation*}
\omega_{i m+1}=\sum_{j=1}^{m} A_{i j} \omega_{j}, \quad A_{i j}=A_{j i} \tag{1.2}
\end{equation*}
$$

Throughout this paper, we assume that $M$ has at most two distinct principal curvatures, say $\lambda$ and $\mu$. Then $\lambda$ and $\mu$ are continuous on $M$ and are differentiable on the set $N$ of all points at which one principal curvature is different from the other. Furthermore $N$ is clearly open in $M$. We can choose a neighborhood $U$ of a point $p \in N$ where there exists $b \in B$ such that

$$
\left\{\begin{array}{l}
\omega_{a m+1}=\lambda \omega_{a}, \quad \omega_{\alpha m+1}=\mu \omega_{\alpha},  \tag{1.3}\\
a=1,2, \cdots, r, \quad \alpha=r+1, r+2, \cdots, m
\end{array}\right.
$$

where $r$ is the multiplicity of $\lambda$. It follows from (1.3) that we have

$$
\left\{\begin{array}{l}
d \lambda \wedge \omega_{a}+(\lambda-\mu) \sum_{\alpha} \omega_{a \alpha} \wedge \omega_{\alpha}=0  \tag{1.4}\\
d \mu \wedge \omega_{\alpha}+(\lambda-\mu) \sum_{a} \omega_{a \alpha} \wedge \omega_{a}=0
\end{array}\right.
$$

2. Hypersurfaces with two distinct principal curvatures. In this section, we shall study principal curvatures of hypersurfaces in a Riemannian manifold $\bar{M}$ of non-zero constant curvature $\bar{c}$ which have at most two distinct principal curvatures, say $\lambda$ and $\mu$, such that $\lambda \mu+\bar{c}=0$ on $N$. We shall prove the following

Theorem. Let $M$ be an $m(\geqq 3)$-dimensional connected and complete Riemannian manifold which is isometrically immersed in an ( $m+1$ )-dimensional Riemannian manifold $\bar{M}$ of constant curvature $\bar{c}(\neq 0)$. If $M$ has at most two distinct principal curvatures $\lambda$ and $\mu$ at each point of $M$ and they satisfy $\lambda \mu+\bar{c}=0$ where $\lambda \neq \mu$, then $\lambda$ and $\mu$ are constant on $M$.

Proof. We shall use the same notation as that in § 1. To simplify the statement we may assume without any loss of generality that $\lambda>\mu$ on $N$ and we first consider the case that there exists a point of $N$ at which the multiplicity of $\lambda$ is equal to $r$, where $r$ satisfies the restriction $2 \leqq r \leqq m-2$. Let $E$ be the set of all points of $N$ at which the multiplicity of $\lambda$ is equal to $r$. Then $E$ is open in $N$, so it is also open in $M$. Since the multiplicities of the principal curvatures are both con-
stant on $E$, it is well known in [1] and [2] that $\lambda$ and $\mu$ are constant on $E$. It follows from the continuity of $\lambda$ that the multiplicity of $\lambda$ is equal to $r$ on the boundary of $E$, so it is closed in $M$. Since $M$ is connected, the multiplicity of $\lambda$ is constant $r$ on $M$, so that $\lambda$ and $\mu$ are constant on $M$.

Next, we shall consider the case that one of the principal curvatures is simple, that is, the multiplicity of one of the principal curvatures is 1 on $N$. Without loss of generality, we may assume that the multiplicity of $\lambda$ is equal to 1 on $N$. Let $G$ be the set of all points of $N$ at which the gradient of $\lambda$ is a non-zero vector. It is evident that $G$ is open in $N$, so that it is open in $M$. If the set $G$ is empty, then $\lambda$ and $\mu$ are constant on each component of $N$. Since $\lambda \neq \mu$ on $N$ and $\lambda$ and $\mu$ are continuous on $M$, we have the same property on the boundary of $N$. Accordingly $N$ is closed in $M$. It follows from the fact that $M$ is connected that $N$ must coincide with $M$ itself, so this implies that $\lambda$ and $\mu$ are constant on $M$. Therefore, we may consider the other case $G \neq \varnothing$. Then, on a neighborhood $V$ of a point $q \in G$ in $G$, there exist frame fields in $B$ satisfying the condition (1.3). Using the structure equations (1.1), we obtain

$$
\left\{\begin{array}{l}
d \lambda \wedge \omega_{1}+(\lambda-\mu) d \omega_{1}=0  \tag{2.1}\\
d \mu \wedge \omega_{\alpha}-(\lambda-\mu) \omega_{1} \wedge \omega_{1 \alpha}=0 \quad \text { for } \quad \alpha=2,3, \cdots, m
\end{array}\right.
$$

From the second equation of (2.1) we get

$$
\begin{equation*}
d \mu=\mu_{1} \omega_{1} \tag{2.2}
\end{equation*}
$$

because of the assumption of dimension and E. Cartan's lemma. By the condition $\lambda \mu=-\bar{c}=$ constant, we have

$$
\begin{equation*}
d \lambda=\lambda_{1} \omega_{1} \tag{2.3}
\end{equation*}
$$

It follows from the equations (2.1), (2.2) and (2.3) that we have

$$
\begin{equation*}
d \omega_{1}=0 \tag{2.4}
\end{equation*}
$$

which implies that there exists a function $u$ on a neighborhood $W$ in $V$ such that $\omega_{1}=d u$. In $W, u$ may be considered as a distance from the integral submanifold through $q$ corresponding to $\mu$. Since the multiplicities of $\lambda$ and $\mu$ are constant on $N$ and $M$ is complete, we may consider $u$ as a function defined on $N$. In particular, there exists a geodesic $\Gamma=\{\gamma(u)\}$ parametrized by arc length $u$ in such a way that

$$
\begin{equation*}
\gamma(0)=q, \quad \gamma^{\prime}(0)=e_{1}, \quad \omega_{1}=d u \tag{2.5}
\end{equation*}
$$

Since $M$ is complete, we can extend this geodesic $\Gamma$ infinitely in both
directions. We denote the extended geodesic by the same symbol $\Gamma=$ $\{\gamma(u)\}$. It follows from the equations (2.1) $\sim(2.4)$ that the principal curvature $\mu$ is constant along the integral submanifold corresponding to $\mu$, and $\mu$ is a function of $u$. From (2.1) we get

$$
\begin{equation*}
\omega_{1 \beta}=\left(\mu^{\prime} /(\lambda-\mu)\right) \omega_{\beta}, \quad \beta=2,3, \cdots, m \tag{2.6}
\end{equation*}
$$

where $\mu^{\prime}=d \mu / d u=\mu_{1}$. Using (1.1) and (1.2), from (2.6) we have

$$
\begin{equation*}
\left(\mu^{\prime} /(\lambda-\mu)\right)^{\prime}+\left(\mu^{\prime} /(\lambda-\mu)\right)^{2}=0 . \tag{2.7}
\end{equation*}
$$

Since $\mu^{\prime}=\operatorname{grad} \mu \neq 0$ on $G$, it follows from (2.7) on $G$ that the following equation

$$
\begin{equation*}
\mu^{\prime} /(\lambda-\mu)=1 /\left(u+c_{1}\right), \quad c_{1}=\text { constant } \neq 0 \tag{2.8}
\end{equation*}
$$

is obtained, so that on $G$ we have the solution

$$
\begin{equation*}
\mu^{2}+\bar{c}=c_{2} /\left(u+c_{1}\right)^{2}, \quad c_{2}=\text { constant } \neq 0 \tag{2.9}
\end{equation*}
$$

Now, we may consider the following two cases:
Case (1): $\quad \partial G \cap \Gamma=\varnothing, \quad$ Case (2): $\quad \partial G \cap \Gamma \neq \varnothing$.
In the first case, since $\gamma(u)$ is defined on $-\infty<u<\infty$, there exists $u_{0}=-c_{1} \neq 0$, so that we have

$$
\lim _{u \rightarrow u_{0}}\left(\mu^{2}+\bar{c}\right)=+\infty \text { or }-\infty,
$$

which contradicts the continuity of $\mu^{2}+\bar{c}$.
In the case (2), let $q_{1}=\gamma\left(u_{1}\right)$ be the first point at which the geodesic $\Gamma=\{\gamma(u)\}$ meets the boundary of $G$. In this case we may suppose that $0<u_{1}, \gamma(u) \in G$ for $0<\forall u<u_{1}$ and $\gamma\left(u_{1}\right) \notin G$. Then we can consider the following two cases:

$$
\text { Case (a) } \quad q_{1}=\gamma\left(u_{1}\right) \in N, \quad \text { Case (b) } \quad q_{1}=\gamma\left(u_{1}\right) \in \partial N
$$

In the case (a), we can see that

$$
\lim _{u \rightarrow u_{1}-0} \operatorname{grad} \mu \neq 0
$$

which contradicts grad $\mu=0$ at $q_{1}$. In the case (b), we have

$$
\lim _{u \rightarrow u_{1}-0}\left(\mu^{2}+\bar{c}\right) \neq 0,
$$

which contradicts $\mu^{2}+\bar{c}=0$ at $q_{1}$. Thus $G$ must be empty. This completes the proof.

Remark. Using Theorem in this section, we see that Theorem of S. Tanno and T. Takahashi [4] holds for $m=3$.
3. Hypersurfaces in a hyperbolic space. Let $M$ be an $m$-dimensional connected and complete Riemannian manifold isometrically immersed in an $(m+1)$-dimensional hyperbolic space $H^{m+1}(c)$ of constant curvature $c$. In this section, we assume that $M$ is also of constant curvature $c$. Then we shall give many examples of such hypersurfaces which are not totally geodesic.

Let $g=\left(g_{i j}\right), A=\left(A_{i j}\right)$ and $\left\{\begin{array}{c}i \\ j k\end{array}\right\}$ be the metric tensor of $M$, the second fundamental tensor of $M$ and the Christoffel's symbols of $g$. Then, in our situation, as is well known, the Gauss' and the Codazzi's equations are written by

$$
\begin{gather*}
A_{i k} A_{l j}-A_{i l} A_{j k}=0,  \tag{3.1}\\
A_{i j, k}+\sum_{l}\left\{\begin{array}{c}
l \\
i j
\end{array}\right\} A_{l k}=A_{i k, j}+\sum_{l}\left\{\begin{array}{c}
l \\
i k
\end{array}\right\} A_{l j}, \tag{3.2}
\end{gather*}
$$

where $A_{i j, k}=\partial A_{i j} / \partial x^{k}$ when ( $x^{1}, x^{2}, \cdots, x^{m}$ ) is a local coordinate system of $M$.

Now, as a model space of an $m$-dimensional hyperbolic space $H^{m}(c)$ of constant curvature $c$, we take the upper half space $R_{+}^{m}=\left\{\left(x^{1}, x^{2}, \cdots, x^{m}\right) \in\right.$ $\left.R^{m} \mid x^{m}>0\right\}$ with the metric tensor given by

$$
\begin{equation*}
g_{i j}=-\delta_{i j} /\left\{c\left(x^{m}\right)^{2}\right\} \tag{3.3}
\end{equation*}
$$

In this case, Christoffel's symbols of $g$ are

$$
\left\{\begin{array}{c}
k  \tag{3.4}\\
i j
\end{array}\right\}=-\left(\delta_{k j} \delta_{i m}+\delta_{k i} \delta_{j m}-\delta_{i j} \delta_{k m}\right) / x^{m}
$$

By Sasaki's Theorem 1 in [3], if we give a non-trivial symmetric tensor $A$ of type ( 0,2 ) on $R_{+}^{m}$ satisfying (3.1) and (3.2), then we obtain a hypersurface in $H^{m+1}(c)$ which has $A$ as its second fundamental tensor and is not totally geodesic. Hence, in order to find a complete hypersurface of constant curvature $c$ in $H^{m+1}(c)$ which is not totally geodesic, it is sufficient to find only a non-trivial symmetric tensor $A$ of type (0,2) on $R_{+}^{m}$ satisfying (3.1) and (3.2). From (3.1), we see that the matrix $A=\left(A_{i j}\right)$ is at most of rank 1 , so that we may consider the special case

$$
\begin{equation*}
A_{11}=\lambda \text { and } A_{i j}=0 \text { if }(i, j) \neq(1,1), \tag{3.5}
\end{equation*}
$$

where $\lambda$ is a differentiable function on $R_{+}^{m}$. Then, it is clear that (3.1) holds. Using (3.4) and (3.5), we see that (3.2) is equivalent to the following differential equations:

$$
\left\{\begin{array}{l}
\lambda_{, k}=0 \quad \text { for } k=2,3, \cdots, m-1  \tag{3.6}\\
\lambda, m / x^{m}
\end{array}\right.
$$

We easily see that a function

$$
\begin{equation*}
\lambda=\lambda\left(x^{1}, x^{m}\right)=g\left(x^{1}\right) / x^{m} \tag{3.7}
\end{equation*}
$$

is a solution of (3.6), where $g\left(x^{1}\right)$ is an arbitrary non-zero differentiable function on $R_{+}^{m}$ of $x^{1}$. For two distinct functions $g\left(x^{1}\right)$ and $\widetilde{g}\left(x^{1}\right)$, we have two distinct solutions $\lambda$ and $\tilde{\lambda}$ of (3.6), that is, two distinct non-trivial symmetric tensors $A$ and $\tilde{A}$ on $R_{+}^{m}$ satisfying (3.1) and (3.2). On the other hand, by Sasaki's Theorem 2 in [3], we see that there exist two hypersurfaces of constant curvature $c$ in $H^{m+1}(c)$ which have $A$ and $\widetilde{A}$ as their fundamental tensors respectively and they are not congruent in the large under the group of motions of $H^{m+1}(c)$. Thus, we obtain many examples of hypersurfaces of constant curvature $c$ in $H^{m+1}(c)$ which are not totally geodesic.

By the above argument, we have shown that there exist many examples of complete hypersurfaces with type number 1 in a hyperbolic space $H^{m+1}(c)$ of constant curvature $c$ which are not congruent in the large under the group of motions of $H^{m+1}(c)$.

## Bibliography

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