

Chapter 5

Stochastic differential equations in Hilbert space

Throughout this chapter, H will be a separable Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\|\cdot\|$. $L(H, H)$ will denote the class of all continuous linear operators on H and $L_2(H, H)$ the class of all Hilbert-Schmidt operators. For an operator $A \in L_2(H, H)$, the Hilbert-Schmidt norm will be denoted by $\|\cdot\|_2$.

Let (Ω, \mathcal{F}, P) be a complete probability space with a given filtration (\mathcal{F}_t) assumed to satisfy the usual conditions. Let (W_t) be an (\mathcal{F}_t) -cylindrical Brownian motion (c.B.m) on H and let (B_t) be an (\mathcal{F}_t) -adapted H -valued Brownian with covariance Σ (cf. Section 3.2 for definition).

5.1 Diffusion equations in Hilbert spaces

Suppose that $A : H \rightarrow H$ and $G : H \rightarrow L(H, H)$ are two continuous mappings. We consider the following SDE on H :

$$X_t = X_0 + \int_0^t A(X_s) ds + \int_0^t G(X_s) dB_s. \quad (5.1.1)$$

It is possible to establish a unique solution for (5.1.1) by making use of weak convergence techniques and by following the method which will be developed in Chapter 6, i.e., first we obtain a solution for the corresponding martingale problem by approximation and then get a weak solution by the representation theorems given in Chapter 3; finally we establish a unique strong solution by the Yamada-Watanabe argument. However, in this section, we shall adopt the approach given by Leha and Ritter [37] to establish a unique strong directly.

Definition 5.1.1 $\{X_t\}$ is called a strong solution of (5.1.1) with explosion time τ if

(i)

$$\limsup_{t \rightarrow \tau} \|X_t\| = \infty \quad \text{on the set } \{\tau < \infty\}.$$

(ii) There exists a sequence $\{\tau_n\}$ of stopping times, increasing to τ , such that

(a)

$$E \int_0^{t \wedge \tau_n} \|A(X_s)\| ds < \infty.$$

(b)

$$E \int_0^{t \wedge \tau_n} \|G(X_s)\|_{L(H,H)}^2 ds < \infty.$$

(c)

$$X_{t \wedge \tau_n} = X_0 + \int_0^{t \wedge \tau_n} A(X_s) ds + \int_0^{t \wedge \tau_n} G(X_s) dB_s$$

where the stochastic integral is defined as $I_t(f)$ (cf. Section 3.3) with

$$f(s, \omega) = G(X_s) \Sigma^{\frac{1}{2}} 1_{s \leq \tau_n} \in L_{(2)}(H, H).$$

As

$$E \int_0^t \|f(s, \omega)\|_{(2)}^2 ds \leq \|\Sigma\|_{(1)} E \int_0^{t \wedge \tau_n} \|G(X_s)\|_{L(H,H)}^2 ds < \infty,$$

$I_t(f)$ is well-defined, where $\|\cdot\|_{(1)}$ denotes the nuclear norm of nuclear operators on H .

Theorem 5.1.1 (Leha-Ritter) Suppose that X_0 has a finite second moment and A, G satisfy Lipschitz conditions on bounded sets, i.e., $\forall n, \exists L_n$ such that $\forall x, y \in H, \|x\| \leq n, \|y\| \leq n$, we have

$$\|A(x) - A(y)\| + \|G(x) - G(y)\|_{L(H,H)} \leq L_n \|x - y\|.$$

Then there is a unique strong solution to the SDE (5.1.1).

Proof: First assume the global Lipschitz conditions for A and G , i.e. $L_n = L$. We construct a Picard sequence as follows:

$$\begin{aligned} X_t^0 &\equiv X_0, \\ X_t^{m+1} &\equiv X_0 + \int_0^t A(X_s^m) ds + \int_0^t G(X_s^m) dB_s. \end{aligned} \quad (5.1.2)$$

By induction, it is easy to show that $\forall t \geq 0$

$$E \int_0^t \|X_s^m\|^2 ds < \infty \quad \forall m \geq 0,$$

and consequently, $\{X_t^m\}$ is well-defined by (5.1.2).

Note that, by Theorem 3.3.2,

$$\begin{aligned} & E \sup_{0 \leq t \leq r} \left\| \int_0^t (G(X_s^m) - G(X_s^{m-1})) dB_s \right\|^2 \\ & \leq 4E \int_0^r \left\| (G(X_s^m) - G(X_s^{m-1})) \Sigma^{\frac{1}{2}} \right\|_2^2 ds \\ & \leq 4\|\Sigma\|_{(1)} L^2 \int_0^r \|X_s^m - X_s^{m-1}\|^2 ds. \end{aligned}$$

Therefore

$$\begin{aligned} D_r^m & \equiv E \sup_{0 \leq t \leq r} \|X_s^m - X_s^{m-1}\|^2 \\ & \leq 2E \sup_{0 \leq t \leq r} \left\| \int_0^t (G(X_s^m) - G(X_s^{m-1})) dB_s \right\|^2 \\ & \quad + 2E \sup_{0 \leq t \leq r} \left\| \int_0^t (A(X_s^m) - A(X_s^{m-1})) ds \right\|^2 \\ & \leq 2L^2(4\|\Sigma\|_{(1)} + r) \int_0^r D_s^{m-1} ds. \end{aligned} \quad (5.1.3)$$

Let $K(r) = 2L^2(4\|\Sigma\|_{(1)} + r)$. Then

$$D_r^m \leq D_r^0 \frac{(K(r)r)^m}{m!} \quad (5.1.4)$$

where

$$D_r^0 \leq 2E \sup_{0 \leq t \leq r} \left\| \int_0^t G(X_0) dB_s \right\|^2 + 2E \sup_{0 \leq t \leq r} \left\| \int_0^t A(X_0) ds \right\|^2 < \infty.$$

$\forall r > 0$, let

$$\Omega_r = \left\{ \omega : \sum_{m=1}^{\infty} \sup_{0 \leq t \leq r} \|X_t^m - X_t^{m-1}\| < \infty \right\}.$$

As

$$\begin{aligned} E \sum_{m=1}^{\infty} \sup_{0 \leq t \leq r} \|X_t^m - X_t^{m-1}\| & \leq \sum_{m=1}^{\infty} \sqrt{E \sup_{0 \leq t \leq r} \|X_t^m - X_t^{m-1}\|^2} \\ & \leq \sum_{m=1}^{\infty} \sqrt{D_r^0 \frac{(K(r)r)^m}{m!}} < \infty, \end{aligned}$$

$P(\Omega_r) = 1$ and hence, $P(\Omega') = 1$ where $\Omega' = \cup_{r=1}^{\infty} \Omega_r$. It is clear that $\forall \omega \in \Omega', \exists X(\omega) \in C([0, \infty), H)$ s.t. $\forall T > 0$

$$\sup_{0 \leq t \leq T} \|X_t^m(\omega) - X_t(\omega)\| \rightarrow 0. \quad (5.1.5)$$

By (5.1.4), it is easy to show that, $\forall r > 0$

$$K_1(r) \equiv \sup_{m \geq 0} E \sup_{0 \leq t \leq r} \|X_t^m\|^2 < \infty \quad (5.1.6)$$

and

$$\lim_{m \rightarrow \infty} E \sup_{0 \leq t \leq r} \|X_t^m - X_t\|^2 \rightarrow 0. \quad (5.1.7)$$

By Fatou's lemma, we then have

$$E \sup_{0 \leq t \leq r} \|X_t\|^2 \leq K_1(r). \quad (5.1.8)$$

Now we show that $\{X_t\}$ satisfies the conditions of Definition 5.1.1 with $\tau \equiv \infty$. (i) is trivially true. For (ii), (a) and (b) follows from (5.1.8) and the global Lipschitz conditions on A and G . (c) follows from (5.1.7) and (5.1.2). Hence X is a strong solution of (5.1.1).

Suppose that \tilde{X} is another solution and let

$$\tilde{D}_r = E \sup_{0 \leq t \leq r} \|X_s - \tilde{X}_s\|^2.$$

As in (5.1.3) we have

$$\tilde{D}_r \leq 2L^2(4\|\Sigma\|_{(1)} + r) \int_0^r \tilde{D}_s ds$$

and hence $\tilde{D} \equiv 0$. This proves the uniqueness of the solution.

Finally, we return to the general case. Define

$$G_n(x) = \begin{cases} G(x) & \text{if } \|x\| \leq n \\ G\left(\frac{nx}{\|x\|}\right) & \text{otherwise.} \end{cases}$$

A_n can be defined similarly. Then A_n, G_n satisfy the global Lipschitz conditions and hence by the first part of the proof there is a unique strong solution ξ^n for (5.1.1) with A, G replaced by A_n, G_n respectively. Let τ_n be the first exit time of ξ^n from $\{x \in H : \|x\| \leq n\}$. Then $\{\tau_n\}$ is a non-decreasing sequence of stopping times and

$$\xi_t^{n+1} = \xi_t^n \quad \forall t \leq \tau_n.$$

Let $\tau = \sup_n \tau_n$ and

$$X_t = \xi_t^n \quad \forall t \leq \tau_n.$$

Then

$$\limsup_{t \rightarrow \tau} \|X_t\| \geq \lim_{n \rightarrow \infty} \|X_{\tau_n}\| = \infty.$$

This proves (i) of Definition 5.1.1. The condition (ii) follows directly from the construction of $\{X_t\}$. Hence X is a solution of (5.1.1) upto time τ . ■

It follows from the proof of the above theorem that $\tau = \infty$ a.s. if A and G satisfy the global Lipschitz conditions. The following theorem gives the same result under weaker conditions.

Theorem 5.1.2 (Leha-Ritter) *If, in addition to the conditions of Theorem 5.1.1, A and G satisfy the following: There exists a positive constant K such that for any $x \in H$,*

$$\langle x, A(x) \rangle \leq K(1 + \|x\|^2)$$

and

$$\|G(x)\|_{L(H,H)}^2 \leq K(1 + \|x\|^2),$$

then $\{X_t\}$ has infinite explosion time, i.e., $\tau = \infty$ a.s.

Proof: We use the same notation as in the proof of Theorem 5.1.1. It follows from Itô's formula that

$$\begin{aligned} \|\xi_{t \wedge \tau_n}^n\|^2 &= \|X_0\|^2 + 2 \int_0^{t \wedge \tau_n} \langle G(\xi_s^n)^* \xi_s^n, dB_s \rangle \\ &\quad + 2 \int_0^{t \wedge \tau_n} \langle \xi_s^n, A(\xi_s^n) \rangle ds + \int_0^{t \wedge \tau_n} \|G(\xi_s^n) \Sigma^{\frac{1}{2}}\|_2^2 ds \end{aligned}$$

where $G(\xi_s^n)^*$ denotes the adjoint operator of $G(\xi_s^n)$. Therefore

$$\begin{aligned} E\|\xi_{t \wedge \tau_n}^n\|^2 &\leq E\|X_0\|^2 + 2K \int_0^t (1 + E\|\xi_{s \wedge \tau_n}^n\|^2) ds \\ &\quad + \|\Sigma\|_{(1)} K \int_0^t (1 + E\|\xi_{s \wedge \tau_n}^n\|^2) ds. \end{aligned}$$

By Gronwall's inequality, we have

$$E\|\xi_{t \wedge \tau_n}^n\|^2 \leq (1 + E\|X_0\|^2) e^{\|\Sigma\|_{(1)} K t} \equiv g(t) < \infty, \quad \forall t > 0.$$

Hence

$$P(\tau \leq t) \leq P(\tau_n \leq t) \leq P(\|\xi_{t \wedge \tau_n}^n\| \geq n) \leq n^{-2} g(t),$$

i.e. $P(\tau \leq t) = 0 \quad \forall t > 0$ and hence, $\tau = \infty$ a.s. ■

5.2 Stochastic evolution equations in Hilbert space

We are going to consider the following SDE

$$dX_t = -LX_t dt + G(t, X_t) dW_t + A(t, X_t) dt \quad (5.2.1)$$

where X_0 is independent of (W_t) . Here the operator L is assumed to satisfy the following conditions:

$$T_t \equiv e^{-tL} \text{ is a contraction semigroup on } H, \quad (5.2.2)$$

$$L^{-1} \text{ is a bounded self-adjoint operator with discrete spectrum.} \quad (5.2.3)$$

Let $\{\phi_k\}$ be the eigenfunctions of L , which constitutes a CONS in H and let $\{\lambda_k\}$ be the corresponding eigenvalues. We assume also that $A : [0, T] \times H \rightarrow H$ and $G : [0, T] \times H \rightarrow L(H, H)$ are continuous functions satisfying

$$|\langle A(t, h), \phi_k \rangle| \leq a_k (1 + \|h\|^2)^{\frac{1}{2}} \quad (5.2.4)$$

$$\|G^*(t, h)\phi_k\| \leq b_k (1 + \|h\|^2)^{\frac{1}{2}} \quad (5.2.5)$$

$$|\langle A(t, h_1) - A(t, h_2), \phi_k \rangle| \leq a_k \|h_1 - h_2\| \quad (5.2.6)$$

$$\|(G^*(t, h_1) - G^*(t, h_2))\phi_k\| \leq b_k \|h_1 - h_2\| \quad (5.2.7)$$

for all $k \geq 1$, $t \in [0, T]$, $h, h_1, h_2 \in H$, where G^* is the adjoint of the operator G and $\{a_k\}, \{b_k\}$ satisfy

$$\sum_{k=1}^{\infty} a_k^2 \lambda_k^{-1} \equiv C_{2,1} < \infty \quad (5.2.8)$$

$$\sum_{k=1}^{\infty} b_k^2 \lambda_k^{-1} \equiv C_{2,2} < \infty. \quad (5.2.9)$$

Under these conditions the stochastic integral $\int_0^t G(s, X_s) dW_s$ may not be defined. However, for any predictable process (X_t) ,

$$\begin{aligned} \int_0^t \|T_{t-s} G(s, X_s)\|_2^2 ds &\leq \int_0^t \sum_{k=1}^{\infty} e^{-2(t-s)\lambda_k} b_k^2 (1 + \|X_s\|^2) ds \\ &= \int_0^t f_G(t-s) (1 + \|X_s\|^2) ds \end{aligned} \quad (5.2.10)$$

where

$$f_G(t) = \sum_{k=1}^{\infty} e^{-2\lambda_k t} b_k^2. \quad (5.2.11)$$

Since $\int_0^t f_G(u)du \leq \sum_{k=1}^{\infty} b_k^2 \lambda_k^{-1} = C_{2,2}$ it follows that the stochastic integral referred to above exists if

$$\int_0^T \|X_s\|^2 ds < \infty \quad a.s. \quad (5.2.12)$$

Similarly

$$\begin{aligned} \left[\int_0^t \|T_{t-s}A(s, X_s)\| ds \right]^2 &\leq T \int_0^t \sum_{k=1}^{\infty} e^{-2(t-s)\lambda_k} a_k^2 (1 + \|X_s\|^2) ds \\ &= \int_0^t f_A(t-s)(1 + \|X_s\|^2) ds \end{aligned} \quad (5.2.13)$$

where

$$f_A(t) = T \sum_{k=1}^{\infty} e^{-2\lambda_k t} a_k^2 \quad (5.2.14)$$

and again we have that $\int_0^t f_A(u)du \leq TC_{2,1}$. Thus for every ω such that (5.2.12) holds, we also have that the integral

$$\int_0^t T_{t-s}A(s, X_s) ds \quad (5.2.15)$$

is well defined.

We will prove the existence and uniqueness of the above equation (5.2.1). The details are taken from Bhatt, Kallianpur, Karandikar and Xiong [1].

Definition 5.2.1 *A predictable process (X_t) is said to be a mild solution or evolution solution to (5.2.1) if (5.2.12) holds and for every t*

$$X_t = T_t X_0 + \int_0^t T_{t-s}G(s, X_s)dW_s + \int_0^t T_{t-s}A(s, X_s)ds \quad a.s. \quad (5.2.16)$$

Note that the predictability of (X_t) implies that X_0 is independent of (W_t) . It is easy to see that if (X_t) is a solution and (X'_t) is a predictable modification of (X_t) , i.e. $P(X_t = X'_t) = 1$ for all t , then (X'_t) is also a solution to (5.2.1).

It is convenient to define a new probability measure \tilde{P} on \mathcal{F} ,

$$\tilde{P}(C) = \int_C \exp\{-\|X_0\|\} dP \bigg/ \int \exp\{-\|X_0\|\} dP. \quad (5.2.17)$$

Clearly, \tilde{P} and P are mutually absolutely continuous and the Radon-Nikodym derivative $\frac{d\tilde{P}}{dP}$ is \mathcal{F}_0 measurable. Hence (W_t) is again a c.B.m on $(\Omega, \mathcal{F}, \tilde{P})$. If $M_t = \int_0^t F_s dW_s$ on (Ω, \mathcal{F}, P) and $\tilde{M} = \int_0^t F_s dW_s$ on $(\Omega, \mathcal{F}, \tilde{P})$ where $\int_0^T \|F_s\|_2^2 ds < \infty$ a.s. (P or \tilde{P}), then

$$P(M_t = \tilde{M} \text{ for all } t) = \tilde{P}(M_t = \tilde{M} \text{ for all } t) = 1.$$

Thus (X_t) is a solution to (5.2.1) on (Ω, \mathcal{F}, P) if and only if (X_t) is a solution to (5.2.1) on $(\Omega, \mathcal{F}, \tilde{P})$. Further, we have for all $p < \infty$,

$$E^{\tilde{P}} \|X_0\|^p < \infty.$$

Here is a version of Gronwall's lemma which will be used in proving existence and uniqueness results for the solution.

Lemma 5.2.1 *i) Let f, g and δ be nonnegative functions on $[0, T]$. Let $\alpha \in [0, \infty)$ such that $\int_0^T e^{-\alpha t} f(t) dt \leq \frac{1}{2}$. Suppose that either g is bounded or g is integrable and δ is bounded. If for all $t \leq T$,*

$$g(t) \leq c + \int_0^t f(s) \{g(t-s) + \delta(t-s)\} ds, \quad (5.2.18)$$

then there exists a nonnegative Borel measure μ on $[0, T]$ such that $\mu[0, t] \leq e^{\alpha t}$ and

$$g(t) \leq c(1 + e^{\alpha t}) + \int_0^t \delta(t-s) \mu(ds). \quad (5.2.19)$$

ii) Let f, g be positive functions on $\{0, 1, \dots, n\}$. Let $\alpha \in [0, \infty)$ such that $\sum_{i=1}^n e^{-\alpha i} f(i) \leq \frac{1}{2}$. If for all $0 \leq i \leq n$

$$g(i) \leq c + \sum_{j=1}^i f(j) g(i-j), \quad (5.2.20)$$

then

$$g(i) \leq c(1 + e^{\alpha i}). \quad (5.2.21)$$

Proof: Iterating the inequality (5.2.18) we get

$$\begin{aligned} g(t) &\leq c + \int_0^t f(s_1) \delta(t-s_1) ds_1 + & (5.2.22) \\ &\int_0^t f(s_1) \left[c + \int_0^{t-s_1} f(s_2) \{g(t-s_1-s_2) + \delta(t-s_1-s_2)\} ds_2 \right] ds_1 \\ &= c + \int_0^t \{c + \delta(t-s_1)\} f(s_1) ds_1 \\ &\quad + \int_0^t \int_0^t \{g(t-s_1-s_2) + \delta(t-s_1-s_2)\} f(s_1) f(s_2) 1_{s_1+s_2 \leq t} ds_1 ds_2 \\ &\leq \dots \dots \\ &\leq c + \sum_{j=1}^k \int_0^t \{c + \delta(t-s)\} \mu_j(ds) - c \mu_k([0, t]) + \int_0^t g(t-s) \mu_k(ds) \end{aligned}$$

where

$$\mu_j([0, t]) = \int_0^t \dots \int_0^t f(s_1) \dots f(s_j) 1_{s_1 + \dots + s_j \leq t} ds_1 \dots ds_j.$$

As

$$\begin{aligned}\mu_j([0, t]) &\leq e^{\alpha t} \int_0^t \cdots \int_0^t e^{-\alpha(s_1 + \cdots + s_j)} f(s_1) \cdots f(s_j) ds_1 \cdots ds_j \\ &\leq e^{\alpha t} \left(\frac{1}{2}\right)^j\end{aligned}$$

$\mu(C) \equiv \sum_{j=1}^{\infty} \mu_j(C)$, $C \in \mathcal{B}([0, T])$ is a well-defined nonnegative Borel measure on $[0, T]$ such that $\mu[0, t] \leq e^{\alpha t}$. Letting $k \rightarrow \infty$ on the right hand side of (5.2.22), we have

$$g(t) \leq c(1 + e^{\alpha t}) + \int_0^t \delta(t-s)\mu(ds) + \liminf_{k \rightarrow \infty} \int_0^t g(t-s)\mu_k(ds). \quad (5.2.23)$$

If g is bounded, then $\liminf_{k \rightarrow \infty} \int_0^t g(t-s)\mu_k(ds) = 0$ and hence (5.2.19) holds. If g is integrable and δ is bounded, then

$$\begin{aligned}\int_0^T \liminf_{k \rightarrow \infty} \int_0^t g(t-s)\mu_k(ds) dt &\leq \liminf_{k \rightarrow \infty} \int_0^T \int_0^t g(t-s)\mu_k(ds) dt \\ &\leq \int_0^T g(t) dt \liminf_{k \rightarrow \infty} \mu_k([0, T]) = 0,\end{aligned}$$

i.e. $\liminf_{k \rightarrow \infty} \int_0^t g(t-s)\mu_k(ds) = 0$ for a.e. $t \in [0, T]$ and hence, for a.e. $t \in [0, T]$

$$g(t) \leq c(1 + e^{\alpha t}) + \|\delta\|_{\infty} e^{\alpha t}.$$

By (5.2.18), $\forall t \in [0, T]$

$$g(t) \leq c + \int_0^T f(s) ds (c + \|\delta\|_{\infty}) (1 + e^{\alpha T})$$

i.e. g is bounded and hence (5.2.19) holds. (5.2.21) can be proved similarly. ■

We will now obtain an estimate on the second moment of a solution.

Theorem 5.2.1 *If (X_t) is a solution to (5.2.1) satisfying $E\|X_0\|^2 < \infty$, then*

$$\sup_{t \leq T} E\|X_t\|^2 \leq C_{2,3}[1 + E\|X_0\|^2] \quad (5.2.24)$$

where $C_{2,3}$ is a constant depending only on the constants $C_{2,1}$, $C_{2,2}$.

Proof: Let (X_t) be a solution to (5.2.1) satisfying (5.2.12). Then it follows that

$$\begin{aligned}\langle X_t, \phi_k \rangle &= e^{-\lambda_k t} \langle X_0, \phi_k \rangle + \int_0^t \left\langle e^{-\lambda_k(t-s)} G^*(s, X_s) \phi_k, dW_s \right\rangle \\ &\quad + \int_0^t e^{-\lambda_k(t-s)} \langle A(s, X_s), \phi_k \rangle ds\end{aligned} \quad (5.2.25)$$

and hence that

$$d\langle X_t, \phi_k \rangle = \langle G^*(t, X_t)\phi_k, dW_t \rangle + \langle A(t, X_t) - \lambda_k X_t, \phi_k \rangle dt. \quad (5.2.26)$$

Fix n and define a stopping time τ_n by

$$\tau_n = \inf \left\{ t \geq 0 : \int_0^t \|X_s\|^2 ds \geq n \right\} \wedge T \quad (5.2.27)$$

and let

$$\xi_t^k \equiv e^{\lambda_k(t \wedge \tau_n)} \langle X_{t \wedge \tau_n}, \phi_k \rangle.$$

Note that $\tau_n \rightarrow T$ since (X_t) is assumed to satisfy (5.2.12). It is easy to see that

$$\begin{aligned} \xi_t^k &= \xi_0^k + \int_0^{t \wedge \tau_n} e^{\lambda_k s} \langle G^*(s, X_s)\phi_k, dW_s \rangle \\ &\quad + \int_0^{t \wedge \tau_n} e^{\lambda_k s} \langle A(s, X_s), \phi_k \rangle ds \end{aligned}$$

and hence from (5.2.4) and (5.2.5) we have

$$\begin{aligned} E|\xi_t^k|^2 &\leq 3E \left[|\xi_0^k|^2 + \int_0^{t \wedge \tau_n} e^{2\lambda_k s} \|G^*(s, X_s)\phi_k\|^2 ds \right. \\ &\quad \left. + t \int_0^{t \wedge \tau_n} e^{2\lambda_k s} \langle A(s, X_s), \phi_k \rangle^2 ds \right] \\ &\leq 3 \left[E|\xi_0^k|^2 + \int_0^t e^{2\lambda_k s} (b_k^2 + T a_k^2) E \left\{ (1 + \|X_s\|^2) 1_{s < \tau_n} \right\} ds \right]. \end{aligned}$$

From the inequality $E[\|X_t\|^2 1_{t < \tau_n}] \leq \sum_k e^{-2\lambda_k t} E|\xi_t^k|^2$ we get

$$\begin{aligned} &E[\|X_t\|^2 1_{t < \tau_n}] \\ &\leq 3 \left[E\|X_0\|^2 + \int_0^t \sum_k e^{-2\lambda_k(t-s)} (b_k^2 + T a_k^2) E \left\{ (1 + \|X_s\|^2) 1_{s < \tau_n} \right\} ds \right] \\ &\leq 3 \left[E\|X_0\|^2 + T C_{2,1} + C_{2,2} + \int_0^t f_0(t-s) E\{\|X_s\|^2 1_{s < \tau_n}\} ds \right] \end{aligned}$$

where $f_0(u) = f_G(u) + f_A(u)$ is an integrable function (see (5.2.11), (5.2.14)). Since $\int_0^T E[\|X_s\|^2 1_{s < \tau_n}] ds \leq n$ by the choice of τ_n , $\delta = 0$ and there exists α such that

$$3 \sum_{k=1}^{\infty} \frac{T a_k^2 + b_k^2}{\alpha + 2\lambda_k} \leq \frac{1}{2}, \quad (5.2.28)$$

we can use Lemma 5.2.1i) to conclude that

$$E[\|X_t\|^2 1_{t < \tau_n}] \leq C[1 + E\|X_0\|^2]$$

where the constant C does not depend on n . Now the result follows from Fatou's lemma by letting $n \rightarrow \infty$. ■

The next result proves the existence and uniqueness of the solution to (5.2.1).

Theorem 5.2.2 *Suppose that L, A, G satisfy (5.2.2)-(5.2.9). Let X_0 be an \mathcal{F}_0 -measurable H -valued random variable and let (W_t) be an (\mathcal{F}_t) -cylindrical Brownian motion. Then*

(i) *There exists a solution (\hat{X}_t) of (5.2.1) satisfying (5.2.12) with $\hat{X}_0 = X_0$.*

(ii) *If $\{X_t\}$ and $\{U_t\}$ are solutions to (5.2.1) satisfying (5.2.12) such that $X_0 = U_0$, then*

$$P(X_t = U_t) = 1 \quad \text{for all } t. \quad (5.2.29)$$

Proof: (i) Let \tilde{P} be defined by (5.2.17). It suffices to construct a solution on $(\Omega, \mathcal{F}, \tilde{P})$. For $n \geq 1$, let $t_i^n = \frac{i}{n}T$, $0 \leq i \leq n$. Let $X_0^n = X_0$ and define $\{X_t^n, t_i^n < t \leq t_{i+1}^n\}$ $i \geq 0$ inductively as follows. For $t_i^n < t \leq t_{i+1}^n$, let

$$\begin{aligned} X_t^n &= T_{t-t_i^n} X_{t_i^n}^n + \int_{t_i^n}^t T_{t-u} G(u, X_{t_i^n}^n) dW_u \\ &\quad + \int_{t_i^n}^t T_{t-u} A(u, X_{t_i^n}^n) du. \end{aligned} \quad (5.2.30)$$

As in (5.2.10), (5.2.13), $\forall t_i^n < t \leq t_{i+1}^n$, we have

$$\begin{aligned} \tilde{E} \|X_t^n\|^2 &\leq 3 \left[\tilde{E} \|X_{t_i^n}^n\|^2 + \int_{t_i^n}^t \sum_k e^{-2\lambda_k(t-s)} (b_k^2 + T a_k^2) \tilde{E} (1 + \|X_{t_i^n}^n\|^2) ds \right] \\ &\leq 3(1 + TC_{2,1} + C_{2,2})(1 + \tilde{E} \|X_{t_i^n}^n\|^2). \end{aligned} \quad (5.2.31)$$

Let $Y_t^n = X_{t_i^n}^n$ for $t_i^n < t \leq t_{i+1}^n$. Then

$$X_t^n = T_t X_0 + \int_0^t T_{t-u} G(u, Y_u^n) dW_u + \int_0^t T_{t-u} A(u, Y_u^n) du. \quad (5.2.32)$$

Proceeding as in (5.2.10), (5.2.13), it follows that

$$\tilde{E} \|X_t^n\|^2 \leq 3 \left[\tilde{E} \|X_0\|^2 + TC_{2,1} + C_{2,2} + \int_0^t f_0(t-s) \tilde{E} \|Y_s^n\|^2 ds \right] \quad (5.2.33)$$

where $f_0 = f_A + f_G$. Let $g_n(i) = \tilde{E} \|X_{t_i^n}^n\|^2$, $0 \leq i \leq n$. By (5.2.31) and induction in i , it is easy to show that $g_n(i)$ is a finite valued function on $i \in \{0, 1, \dots, n\}$. It follows from (5.2.33) that

$$g_n(i) \leq 3 \left[\tilde{E} \|X_0\|^2 + TC_{2,1} + C_{2,2} \right]$$

$$\begin{aligned}
& + \sum_{j=0}^{i-1} \int_{t_j^n}^{t_{j+1}^n} \sum_k (b_k^2 + T a_k^2) e^{-2\lambda_k(t_i^n - s)} ds g_n(j) \Big] \\
& \leq 3(\tilde{E}\|X_0\|^2 + TC_{2,1} + C_{2,2}) + \sum_{j=1}^i f_n(j) g_n(i-j) \quad (5.2.34)
\end{aligned}$$

where

$$f_n(i) = 3 \sum_k \frac{b_k^2 + T a_k^2}{2\lambda_k} e^{-2\lambda_k t_i^n} \left(e^{\frac{2\lambda_k T}{n}} - 1 \right).$$

Let α be given by (5.2.28). Then

$$\begin{aligned}
\sum_{i=1}^n f_n(i) e^{-\frac{\alpha T}{n} i} &= \sum_{i=1}^n 3 \sum_k \frac{b_k^2 + T a_k^2}{2\lambda_k} e^{-\frac{2\lambda_k T + \alpha T}{n} i} \left(e^{\frac{2\lambda_k T}{n}} - 1 \right) \\
&\leq 3 \sum_{k=1}^{\infty} \frac{T a_k^2 + b_k^2}{2\lambda_k} \frac{e^{\frac{2\lambda_k T}{n}} - 1}{e^{\frac{2\lambda_k + \alpha}{n} T} - 1} \\
&\leq 3 \sum_{k=1}^{\infty} \frac{T a_k^2 + b_k^2}{\alpha + 2\lambda_k} \leq \frac{1}{2}
\end{aligned}$$

and hence, by (5.2.34) and Lemma 5.2.1(ii)

$$\tilde{E}\|X_{t_i^n}^n\|^2 = g_n(i) \leq 3(\tilde{E}\|X_0\|^2 + TC_{2,1} + C_{2,2})(1 + e^{\frac{\alpha T}{n} i}).$$

It then follows from (5.2.31) again that

$$\sup_{n \geq 1} \sup_{0 \leq t \leq T} \tilde{E}\|X_t^n\|^2 \leq C'[1 + \tilde{E}\|X_0\|^2] = C''. \quad (5.2.35)$$

Using (5.2.32) for n, m and using the Lipschitz conditions on A, G we get (the calculations are similar to those in (5.2.10), (5.2.13))

$$\begin{aligned}
\tilde{E}\|X_t^n - X_t^m\|^2 &\leq 2\tilde{E} \left\{ \int_0^t \|T_{t-u}(G(u, Y_u^n) - G(u, Y_u^m))\|_2^2 du \right. \\
&\quad \left. + T \int_0^t \|T_{t-u}(A(u, Y_u^n) - A(u, Y_u^m))\|^2 du \right\} \\
&\leq 2 \int_0^t f_0(t-u) \tilde{E}\|Y_u^n - Y_u^m\|^2 du.
\end{aligned}$$

Let $g_{n,m}(t) = \tilde{E}\|X_t^n - X_t^m\|^2$ and $\delta_{n,m}(t) = \tilde{E}\|X_t^n - Y_t^n\|^2 + \tilde{E}\|X_t^m - Y_t^m\|^2$. Then $g_{n,m}, \delta_{n,m}$ are uniformly bounded (by (5.2.35)) and

$$\begin{aligned}
& g_{n,m}(t) \\
& \leq 2 \int_0^t f_0(t-u) 3(\tilde{E}\|Y_u^n - X_u^n\|^2 + \|X_u^n - X_u^m\|^2 + \|X_u^m - Y_u^m\|^2) du \\
& \leq \int_0^t 6f_0(t-u) \{g_{n,m}(u) + \delta_{n,m}(u)\} du.
\end{aligned}$$

Similar to (5.2.31), it follows from (5.2.30) and (5.2.35) that, for $t_i^n < t \leq t_{i+1}^n$

$$\begin{aligned} \tilde{E}\|X_t^n - Y_t^n\|^2 &= \tilde{E}\|X_t^n - X_{t_i^n}^n\|^2 \\ &\leq 3 \sum_{k=1}^{\infty} \left(e^{-\frac{\lambda_k T}{n}} - 1 \right)^2 \tilde{E} \langle X_{t_i^n}^n, \phi_k \rangle^2 \\ &\quad + 3(1 + C'') \sum_{k=1}^{\infty} \frac{Ta_k^2 + b_k^2}{2\lambda_k} \left(1 - e^{-2\frac{\lambda_k T}{n}} \right). \end{aligned} \quad (5.2.36)$$

It follows from (5.2.32) that

$$\begin{aligned} \langle X_t^n, \phi_k \rangle &= e^{-\lambda_k t} \langle X_0, \phi_k \rangle + \int_0^t e^{-\lambda_k(t-u)} \langle G(u, Y_u^n)^* \phi_k, dW_u \rangle \\ &\quad + \int_0^t e^{-\lambda_k(t-u)} \langle A(u, Y_u^n), \phi_k \rangle du \end{aligned}$$

and then

$$\begin{aligned} \tilde{E} \langle X_t^n, \phi_k \rangle^2 &\leq 3\tilde{E} \langle X_0, \phi_k \rangle^2 \\ &\quad + 3 \int_0^t (b_k^2 + Ta_k^2) e^{-2\lambda_k(t-u)} (1 + \tilde{E}\|Y_u^n\|^2) du \\ &\leq 3\tilde{E} \langle X_0, \phi_k \rangle^2 + 3(1 + C'') \frac{b_k^2 + Ta_k^2}{2\lambda_k}. \end{aligned}$$

Hence, by the dominated convergence theorem, it follows from (5.2.36) that $\delta_{n,m}(t) \rightarrow 0$. By Lemma 5.2.1(i) and the dominated convergence theorem again,

$$g_{n,m}(t) \leq \int_0^T \delta_{n,m}(t) \mu(dt) \rightarrow 0.$$

Therefore

$$\sup_{t \leq T} \tilde{E}\|X_t^n - X_t^m\|^2 \rightarrow 0, \quad \sup_{t \leq T} \tilde{E}\|Y_t^n - Y_t^m\|^2 \rightarrow 0. \quad (5.2.37)$$

Note that since Y^n is a piecewise constant, left-continuous, adapted process it is predictable. In view of (5.2.37) we can choose a subsequence $\{n_k\}$ such that $Z_s^k \equiv Y_s^{n_k}$ satisfies

$$\sup_{s \leq T} \tilde{E}\|Z_s^k - Z_s^{k+1}\|^2 \leq 2^{-k}.$$

Then it follows that $\sum_k \|Z_s^k - Z_s^{k+1}\| < \infty$ a.s. for all s . Thus Z_s^k converges a.s. for each s . Define

$$\hat{X}_s(\omega) = \begin{cases} \lim_{k \rightarrow \infty} Z_s^k(\omega) & \text{if it exists in } \mathbb{H} \\ 0 & \text{otherwise.} \end{cases}$$

Then \hat{X}_s is a predictable process. Further, it follows from (5.2.37) that

$$\sup_{s \leq T} \tilde{E} \|Y_s^n - \hat{X}_s\|^2 \rightarrow 0, \quad \sup_{s \leq T} \tilde{E} \|X_s^n - \hat{X}_s\|^2 \rightarrow 0.$$

From this, it can be verified that \hat{X} is a solution to (5.2.1) (on $(\Omega, \mathcal{F}, \tilde{P})$) with $\hat{X}_0 = X_0$ and that (5.2.12) holds. This completes the proof of (i).

For (ii), again, let \tilde{P} be given by (5.2.17). Then $\{X_t\}$ and $\{U_t\}$ are solutions to (5.2.1) on $(\Omega, \mathcal{F}, \tilde{P})$ and in view of Theorem 5.2.1, $\int_0^T \tilde{E} \|X_s - U_s\|^2 ds < \infty$. Using the Lipschitz conditions on A, G , we deduce that

$$\tilde{E} \|X_t - U_t\|^2 \leq 2 \left[\int_0^t f_0(t-s) \tilde{E} \|X_s - U_s\|^2 ds \right].$$

An application of Lemma 5.2.1, with $c = 0$ and $\delta = 0$, yields

$$\tilde{E} \|X_t - U_t\|^2 = 0$$

for all t . Thus $\tilde{P}(X_t = U_t) = 1$ and hence (5.2.29) follows. \blacksquare

We are now in a position to obtain an estimate on the growth of the p^{th} moment of the solution.

Theorem 5.2.3 *Let $\{X_t\}$ be a solution to (5.2.1) satisfying (5.2.12). Then for $p \geq 2$, there exists a constant C'_p depending only on the constant C_p in Theorem 3.3.2 and on $C_{2,1}, C_{2,2}$ such that if $E \|X_0\|^p < \infty$, then*

$$\sup_{s \leq T} E \|X_s\|^p \leq C'_p [1 + E \|X_0\|^p]. \quad (5.2.38)$$

Proof: Let X_t^n be the approximation constructed in the proof of the previous theorem. Using Theorem 3.3.2, it follows from (5.2.30) that for $t_i^n < t \leq t_{i+1}^n$,

$$\begin{aligned} E \|X_t^n\|^p &\leq 3^{p-1} \left[E \|X_{t_i^n}^n\|^p + C_p E \left(\int_{t_i^n}^t f_G(t-s) ds (1 + \|X_{t_i^n}^n\|^2) \right)^{\frac{p}{2}} \right. \\ &\quad \left. + E \left(\int_{t_i^n}^t f_A(t-s) ds (1 + \|X_{t_i^n}^n\|^2) \right)^{\frac{p}{2}} \right] \quad (5.2.39) \\ &\leq 3^{p-1} \left[E \|X_{t_i^n}^n\|^p + (C_p C_{2,2}^{\frac{p}{2}} + (TC_{2,1})^{\frac{p}{2}}) E (1 + \|X_{t_i^n}^n\|^2)^{\frac{p}{2}} \right]. \end{aligned}$$

Let $h_n(i) = \tilde{E} \|X_{t_i^n}^n\|^p$, $0 \leq i \leq n$. By (5.2.39) and by induction in i , we see that $h_n(\cdot)$ is a finite valued function. By (5.2.32), proceeding as in (5.2.39), we have

$$\begin{aligned} E \|X_t^n\|^p &\leq 3^{p-1} \left[E \|X_0\|^p + C_p E \left(\int_0^t f_G(t-s) (1 + \|Y_s^n\|^2) ds \right)^{\frac{p}{2}} \right. \\ &\quad \left. + E \left(\int_0^t f_A(t-s) (1 + \|Y_s^n\|^2) ds \right)^{\frac{p}{2}} \right]. \quad (5.2.40) \end{aligned}$$

Using Hölder's inequality for the ds integrals, we get

$$\begin{aligned} E\|X_t^n\|^p &\leq 3^{p-1} \left[E\|X_0\|^p \right. \\ &\quad + C_p \left(\int_0^t f_G(t-s) ds \right)^{\frac{p}{2}-1} E \left(\int_0^t f_G(t-s) (1 + \|Y_s^n\|^2)^{\frac{p}{2}} ds \right) \\ &\quad \left. + \left(\int_0^t f_A(t-s) ds \right)^{\frac{p}{2}-1} E \left(\int_0^t f_A(t-s) (1 + \|Y_s^n\|^2)^{\frac{p}{2}} ds \right) \right]. \end{aligned} \quad (5.2.41)$$

It then follows from similar arguments as in (5.2.33)-(5.2.35) that there exists a constant C'_p depending only on p and on $C_{2,1}, C_{2,2}$ such that

$$\sup_{n \geq 1} \sup_{0 \leq t \leq T} E\|X_t^n\|^p \leq C'_p [1 + E\|X_0\|^p]. \quad (5.2.42)$$

As noted in the previous result, a subsequence of X_t^n converges to \hat{X}_s , where \hat{X} is a solution to (5.2.1). Hence, using Fatou's lemma, it follows that the required moment estimate holds for \hat{X} . The result follows from this as \hat{X}, X have the same finite dimensional distributions by the uniqueness part of the previous theorem. ■

We now look at regularity of paths of the solution to (5.2.1).

In order to prove sample continuity of the solution, we impose a stronger condition than (5.2.9):

$$\sum_{k=1}^{\infty} b_k^2 \lambda_k^{-\theta} \equiv C_{2,4} < \infty \quad (5.2.43)$$

for some $\theta, 0 < \theta < 1$.

Theorem 5.2.4 *Let (X_t) be a solution to (5.2.1). Then (X_t) admits a continuous modification, which is of course, a solution to (5.2.1).*

Proof: Let \tilde{P} be defined by (5.2.17). It suffices to prove that X has a continuous modification on $(\Omega, \mathcal{F}, \tilde{P})$. Let us write

$$X_t = T_t X_0 + Y_t + Z_t$$

where $Y_t = \int_0^t T_{t-u} G(u, X_u) dW_u$ and $Z_t = \int_0^t T_{t-u} A(u, X_u) du$. Clearly, $T_t X_0(\omega)$ is continuous for all ω . For $0 \leq s \leq t \leq T$,

$$\begin{aligned} &\|Z_t - Z_s\|^2 \\ &= \left\| \int_0^s (T_{t-u} - T_{s-u}) A(u, X_u) du + \int_s^t T_{t-u} A(u, X_u) du \right\|^2 \end{aligned}$$

$$\begin{aligned}
&\leq 2 \left[\int_0^s \|(T_{t-u} - T_{s-u})A(u, X_u)\| du \right]^2 + 2 \left[\int_s^t \|T_{t-u}A(u, X_u)\| du \right]^2 \\
&\leq 2 \left[\int_0^s \left\{ \sum_k \left(e^{-\lambda_k(t-u)} - e^{-\lambda_k(s-u)} \right)^2 a_k^2 (1 + \|X_u\|^2) \right\}^{\frac{1}{2}} du \right]^2 \\
&\quad + 2 \left[\int_s^t \left\{ \sum_k e^{-2\lambda_k(t-u)} a_k^2 (1 + \|X_u\|^2) \right\}^{\frac{1}{2}} du \right]^2 \\
&\leq 2 \left[\int_0^T (1 + \|X_u\|^2) du \right] \alpha(s, t) \tag{5.2.44}
\end{aligned}$$

by Hölder's inequality where

$$\begin{aligned}
\alpha(s, t) &= \int_0^s \sum_k \left(e^{-\lambda_k(t-u)} - e^{-\lambda_k(s-u)} \right)^2 a_k^2 du \\
&\quad + \int_s^t \sum_k e^{-2\lambda_k(t-u)} a_k^2 du.
\end{aligned}$$

It is easy to verify that $\alpha(s, t) \leq \beta(t - s)$ where

$$\beta(\delta) \equiv \sum_{k=1}^{\infty} \frac{a_k^2}{2\lambda_k} \left[\left(1 - e^{-\delta\lambda_k} \right)^2 + \left(1 - e^{-2\delta\lambda_k} \right) \right]. \tag{5.2.45}$$

Clearly (5.2.8) implies $\beta(\delta) \rightarrow 0$ as $\delta \rightarrow 0$. Using (5.2.12), it follows that

$$\lim_{\delta \rightarrow 0} \sup_{0 \leq t-s \leq \delta} \|Z_t - Z_s\|^2 = 0 \quad a.s.$$

Thus $\{Z_t\}$ is continuous a.s.

It remains to show that $\{Y_t\}$ admits a continuous modification. We shall achieve this via the Kolmogorov criterion. Choose p such that $(1 - \theta)p > 2$, where θ is as in (5.2.43). Recall that by the choice of \tilde{P} , $\tilde{E}\|X_0\|^p < \infty$ and hence by Theorem 5.2.3, $\sup_{s \leq T} \tilde{E}\|X_s\|^p < \infty$. As before, \tilde{E} stands for the integral with respect to \tilde{P} . For $s \leq t \leq T$, writing

$$Y_t - Y_s = \int_0^s (T_{t-u} - T_{s-u})G(u, X_u) dW_u + \int_s^t T_{t-u}G(u, X_u) dW_u$$

and using Theorem 3.3.2, we get

$$\begin{aligned}
&\tilde{E}\|Y_t - Y_s\|^p \\
&= 2^{p-1} C_p \tilde{E} \left[\left\{ \int_0^s \|(T_{t-u} - T_{s-u})G^*(u, X_u)\|_2^2 du \right\}^{\frac{p}{2}} \right]
\end{aligned}$$

$$\begin{aligned}
& + \left\{ \int_s^t \|T_{t-u}G^*(u, X_u)\|_2^2 du \right\}^{\frac{p}{2}} \\
= & 2^{p-1} C_p \tilde{E} \left[\left\{ \int_0^s \sum_k \left(e^{-\lambda_k(t-u)} - e^{-\lambda_k(s-u)} \right)^2 b_k^2 (1 + \|X_u\|^2) du \right\}^{\frac{p}{2}} \right. \\
& \left. + \left\{ \int_s^t \sum_k e^{-2\lambda_k(t-u)} b_k^2 (1 + \|X_u\|^2) du \right\}^{\frac{p}{2}} \right]. \tag{5.2.46}
\end{aligned}$$

Let us write

$$\psi_1(u) = \sum_k \left(e^{-\lambda_k(t-u)} - e^{-\lambda_k(s-u)} \right)^2 b_k^2$$

and

$$\psi_2(u) = \sum_k e^{-2\lambda_k(t-u)} b_k^2.$$

Now

$$\begin{aligned}
& \tilde{E} \left[\int_0^s \psi_1(u) (1 + \|X_u\|^2) du \right]^{\frac{p}{2}} \\
\leq & \tilde{E} \left[\left(\int_0^s \psi_1(u) du \right)^{\frac{p}{2}-1} \int_0^s \psi_1(u) (1 + \|X_u\|^2)^p du \right] \\
\leq & C'_p (1 + \tilde{E} \|X_0\|^p) \left(\int_0^s \psi_1(u) du \right)^{\frac{p}{2}}
\end{aligned}$$

by Hölder's inequality and (5.2.38). Similarly, estimating the second term in (5.2.46), we get

$$\tilde{E} \|Y_t - Y_s\|^p \leq C'_p (1 + \tilde{E} \|X_0\|^p) \left[\left(\int_0^s \psi_1(u) du \right)^{\frac{p}{2}} + \left(\int_0^s \psi_2(u) du \right)^{\frac{p}{2}} \right]. \tag{5.2.47}$$

Evaluating the integrals, one obtains

$$\begin{aligned}
\tilde{E} \|Y_t - Y_s\|^p \leq & C'_p \tilde{E} (1 + \|X_0\|)^p \left[\left(\sum_k \frac{b_k^2}{2\lambda_k} \left(1 - e^{-\lambda_k(t-s)} \right)^2 \right)^{\frac{p}{2}} \right. \\
& \left. + \left(\sum_k \frac{b_k^2}{2\lambda_k} \left(1 - e^{-2\lambda_k(t-s)} \right) \right)^{\frac{p}{2}} \right].
\end{aligned}$$

Now using the obvious inequality $1 - e^x \leq x \wedge 1 \leq x^\delta$ for $x > 0$, $0 < \delta \leq 1$, for $\delta = \frac{1-\theta}{2}$ and $\delta = 1 - \theta$ respectively, we get

$$\tilde{E} \|Y_t - Y_s\|^p$$

$$\begin{aligned}
&\leq C'_p \tilde{E}(1 + \|X_0\|)^p \left[\left(\sum_k \frac{b_k^2}{2\lambda_k} (\lambda_k(t-s))^{1-\theta} \right)^{\frac{p}{2}} \right. \\
&\quad \left. + \left(\sum_k \frac{b_k^2}{2\lambda_k} (2\lambda_k(t-s))^{1-\theta} \right)^{\frac{p}{2}} \right] \\
&\leq C'_p \tilde{E}(1 + \|X_0\|)^p \left(\frac{1}{2^{p/2}} + \frac{1}{2^{p\theta/2}} \right) \left(\sum_k \frac{b_k^2}{\lambda_k^\theta} \right)^{\frac{p}{2}} (t-s)^{(1-\theta)p/2}.
\end{aligned}$$

Recalling the assumption (5.2.43) and noting that by our choice of p , $\frac{p}{2}(1-\theta) > 1$, we conclude that

$$\tilde{E}\|Y_t - Y_s\|^p \leq C_{2,5}|t-s|^{1+\delta} \quad (5.2.48)$$

with $\delta = \frac{p}{2}(1-\theta) - 1$, where $C_{2,5}$ depends only on p , $C_{2,4}$. Thus $\{Y_t\}$ has a continuous modification. ■

Now the existence and uniqueness result, Theorem 5.2.2, can be recast as follows.

Theorem 5.2.5 *There exists a continuous solution X to the SDE (5.2.1). Further, if X' is any other solution to (5.2.1) with continuous paths, then*

$$P(X_t = X'_t \text{ for all } t, 0 \leq t \leq T) = 1.$$

Our next step is to prove uniqueness in law of solutions to (5.2.1).

Theorem 5.2.6 *Let $\{X_t\}$ be a solution to (5.2.1) [on (Ω, \mathcal{F}, P)] and let $\{X'_t\}$ be a solution to (5.2.1) on $(\Omega', \mathcal{F}', P')$ with respect to some P' -c.B.m. on H . Suppose that X, X' have continuous paths and suppose $P \circ X_0^{-1} = P' \circ X'_0^{-1}$. Then*

$$P \circ X^{-1} = P' \circ X'^{-1}. \quad (5.2.49)$$

Proof: Let $\{X_t^n\}$ be the approximation constructed in the previous theorem and let $\{V_t^n\}$ be the approximation defined analogously on $(\Omega', \mathcal{F}', P')$ (with X'_0 in place of X_0 and $\{W'_t\}$ in place of $\{W_t\}$ in (5.2.30)). It is easy to see that the finite dimensional distributions of $\{X_t^n\}$ and $\{V_t^n\}$ are the same. Now $\tilde{E}\|X_t^n - X_t\|^2 \rightarrow 0$ implies that $P(\|X_t^n - X_t\| > \delta) \rightarrow 0$ for all $\delta > 0$. Similarly, $P'(\|V_t^n - X'_t\| > \delta) \rightarrow 0$. Thus the finite dimensional distributions of $\{X_t\}$ and $\{X'_t\}$ are the same. Since X, X' have continuous paths, this yields (5.2.49). ■

We will now consider the martingale problem corresponding to (5.2.1).

For $f \in C_0^2(\mathbf{R}^n)$, $n \geq 1$, let $U_n f : H \rightarrow \mathbf{R}$ be defined by

$$(U_n f)(h) = f(\langle h, \phi_1 \rangle, \dots, \langle h, \phi_n \rangle). \quad (5.2.50)$$

For $f \in C_0^2(\mathbf{R}^n)$, we will write $f_i = (\partial/\partial x_i)f$ and $f_{ij} = (\partial/\partial x_j)f_i$. Let

$$\mathcal{D} = \{U_n f : f \in C_0^2(\mathbf{R}^n), n \geq 1\}. \quad (5.2.51)$$

Define \mathbf{L}_t on \mathcal{D} by

$$\begin{aligned} \mathbf{L}_t(U_n f)(h) &= \frac{1}{2} \sum_{i,j=1}^n \langle G^*(t, h)\phi_i, G^*(t, h)\phi_j \rangle (U_n f_{ij})(h) \\ &\quad + \sum_{i=1}^n \langle A(t, h) - \lambda_i h, \phi_i \rangle (U_n f_i)(h). \end{aligned} \quad (5.2.52)$$

If $\{X_t\}$ is a solution to (5.2.1), then we have seen that (5.2.26) holds and hence it follows that for all $g \in \mathcal{D}$,

$$g(X_t) - g(X_0) - \int_0^t (\mathbf{L}_s g)(X_s) ds \quad (5.2.53)$$

is also a martingale. In other words, if $\{X_t\}$ is a solution to (5.2.1) then $\{X_t\}$ is a solution to the $\{\mathbf{L}_t\}$ -martingale problem. The converse is also true is proved next.

Theorem 5.2.7 *Let (X_t) be a predictable process satisfying (5.2.12) such that (5.2.52) is a martingale for all $g \in \mathcal{D}$. Then on an extension $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P}, \tilde{\mathcal{F}}_t)$ of the stochastic basis $(\Omega, \mathcal{F}, P, \mathcal{F}_t)$ there exists a H -cylindrical Brownian motion (W_t) such that (a) (X_t) is $(\tilde{\mathcal{F}}_t)$ -predictable and (b) (X_t) is a solution to (5.2.1).*

Proof: Using (5.2.52) for $g = U_n f$, $f \in C_0^2(\mathbf{R}^n)$, we can first conclude that $(\langle X_t, \phi_i \rangle, 1 \leq i \leq n)$ has a r.c.l.l. modification and then further it has a continuous modification. (this follows using arguments in Theorem IV 3.6 in [9] and exercise 4.6.3 in [53].) Let us denote the continuous version of $\langle X_t, \phi_i \rangle$ by Y^i . Then we also deduce that

$$M_t^i = Y_t^i - Y_0^i - \int_0^t \lambda_i Y_s^i ds - \int_0^t \langle A(s, X_s), \phi_i \rangle ds$$

is a continuous local martingale and that

$$\langle M^i, M^j \rangle_t = \int_0^t \langle G^*(s, X_s)\phi_i, G^*(s, X_s)\phi_j \rangle ds.$$

As a consequence, recalling the definition (5.2.27) of τ_n , and using (5.2.9) we have

$$E \sup_{t \leq \tau_n} |M_t^k|^2 \leq 4E \langle M^k, M^k \rangle_{\tau_n} \leq b_k^2(1+n). \quad (5.2.54)$$

Let $N_t^k \equiv \lambda_k^{-1/2} M_t^k$. Then using (5.2.9) and (5.2.54) we get

$$E \sup_{t \leq \tau_n} \left\| \sum_{k=m}^r N_t^k \phi_k \right\|^2 \rightarrow 0 \quad m, r \rightarrow \infty.$$

Hence $N_t \equiv \sum_{k=1}^{\infty} N_t^k \phi_k$ is an H -valued continuous local martingale. Hence

$$\begin{aligned} \langle N^k, N^j \rangle_t &= \int_0^t \lambda_k^{-1/2} \lambda_j^{-1/2} \langle G^*(s, X_s) \phi_k, G^*(s, X_s) \phi_j \rangle ds \\ &= \int_0^t \langle f_s^* \phi_k, f_s^* \phi_j \rangle ds \end{aligned}$$

where $f_s(\omega) = L^{-1/2} G(s, X_s)$. Note that

$$\int_0^T \|f_s(\omega)\|_2^2 ds < \infty$$

in view of the assumption (5.2.9). It follows from Theorem 3.3.5 that on an extension $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P}, \tilde{\mathcal{F}}_t)$ of $(\Omega, \mathcal{F}, P, \mathcal{F}_t)$, there exists an H -c.B.m W_t such that

$$N_t = \int_0^t f_s dW_s.$$

Then $N_t^k = (N_t, \phi_k) = \int_0^t \langle \lambda_k^{-1/2} G^*(s, X_s) \phi_k, dW_s \rangle$ and hence

$$M_t^k = \int_0^t \langle G^*(s, X_s) \phi_k, dW_s \rangle.$$

From here, it follows that $\{X_t\}$ satisfies (5.2.26) and hence $\{X_t\}$ is a solution to (5.2.1). ■

In the light of Theorem 5.2.5, some of the results concerning the equation (5.2.1) proved earlier can be recast for the $\{\mathbf{L}_t\}$ -martingale problem as follows.

Theorem 5.2.8 (a) *Let (X_t) be a predictable process satisfying (5.2.12) and suppose that (X_t) is a solution to the $\{\mathbf{L}_t\}$ -martingale problem. Then (X_t) admits a continuous modification.*

(b) *For all $\mu \in \mathcal{P}(H)$, there exists a continuous process (X_t) such that (5.2.53) is a martingale for every $g \in \mathcal{D}$ and such that the law of X_0 is μ . Further, the law of the process X is uniquely determined.*

(c) *For $0 \leq s \leq T$, $x \in H$, there is a unique measure $P_{s,x}$ on $C([0, T], H)$ such that (writing the co-ordinate process on $C([0, T], H)$ as η_t),*

(i) $P_{s,x}(\eta(u) = x, 0 \leq u \leq s) = 1$.

(ii) $g(\eta_t) - \int_s^t (\mathbf{L}_u g)(\eta_u) du, t \geq s$ is a $P_{s,x}$ -martingale.

(d) Further, (η_t) is a time inhomogeneous Markov process on the probability space $(\Omega', \mathcal{F}', P_{s,x})$ (where Ω' is $C([0, T], H)$ and \mathcal{F}' is the Borel σ -field on Ω') for each $(s, x) \in [0, T] \times H$. The (common) transition probability function $P(r, y, t, C)$ is given by

$$P(r, y, t, C) = P_{r,y}(\eta_t \in C)$$

for $r \leq t \leq T$, $y \in H$, C Borel in H .

Proof: (a), (b) follow from Theorem 5.2.2, 5.2.4, 5.2.5 and 5.2.7. (c) is the same as (b)-with a change of origin from 0 to s in the time variable. For (d), let us note that if for each n , \mathcal{C}_n is a countable dense subset of $C_0^2(\mathbf{R}^n)$ (in the norm, $\|f\|_0 = \|f\| + \sum_i \|f_i\| + \sum_{i,j} \|f_{ij}\|$, $\|\cdot\|$, being sup norm) then

$$\mathcal{D}_0 = \{U_n f : f \in \mathcal{C}_n\}$$

is a countable set and for every $g = U_n f \in \mathcal{D}$ we can get $g_k \in \mathcal{D}_0$ such that $g_k \rightarrow g$ and $\mathbf{L}_t g_k \rightarrow \mathbf{L}_t g$. Just take $g_k = U_n f_k$ where $f_k \in \mathcal{C}_n$ approximate f in $\|\cdot\|_0$ norm. Hence the Markov property of (η_t) under $\{P_{s,x}\}$ and the expression for the transition function follow from the uniqueness of solution to the martingale problem. (See Theorem 6.2.2 in Stroock and Varadhan [53]) ■

