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# On Four-dimensional Generalized Complex Space Forms

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#### Abstract

F. Tricerri and L. Vanhecke [8] proved that a 2n  $(n \ge 3)$ -dimensional generalized complex space is a real space form or a complex space form. In this note, we shall show that this result is extendable to 4-dimensional case.

## 1 Introduction

Let (V, g) be an *n*-dimensional real vector space with positive definite inner product gand denote by  $\mathcal{R}(V)$  the subspace of  $V^* \otimes V^* \otimes V^* \otimes V^*$  consisting of all tensors having the same symmetries as the curvature tensor of a Riemannian manifold, including the first Bianchi identity. F. Tricerri and L. Vanhecke [8] gave the complete and irreducible decomposition of  $\mathcal{R}(V)$  under the action of  $\mathcal{U}(n)$ . They then applied these algebraic results to the curvature tensors of almost Hermitian manifolds.

A  $2n \ (n \ge 2)$  - dimensional almost Hermitian manifold M = (M, J, g) is called a generalized complex space form if the curvature tensor R takes the following form:

(1.1) 
$$R = \frac{\tau + 3\tau^*}{16n(n+1)}(\pi_1 + \pi_2) + \frac{\tau - \tau^*}{16n(n-1)}(3\pi_1 - \pi_2)$$
$$= \frac{(2n+1)\tau - 3\tau^*}{8n(n-1)(n+1)}\pi_1 + \frac{(2n-1)\tau^* - \tau}{8n(n-1)(n+1)}\pi_2$$

for some smooth functions  $\tau$  and  $\tau^*$  and here

$$\pi_1(x,y)z = g(y,z)x - g(x,z)y$$

and

$$\pi_2(x,y)z = g(Jy,z)Jx - g(Jx,z)Jy - 2g(Jx,y)Jz$$

for all  $x, y, z \in T_p M, p \in M$ .

The concept of generalized complex space form is a natural generalization of a complex space form (i.e. Kähler manifold of constant holomorphic sectional curvature) which has been introduced by F. Tricerri and L. Vanhecke [8]. They showed

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that an almost Hermitian manifold is a generalized complex space form if and only if Einsteinian and weakly \*- Einsteinian and Bochner flat, i.e., B(R) = 0 and further proved that a  $2n \ (n \ge 3)$ -dimensional generalized complex space is a real space form or a complex space form.

In this paper, we shall show that the result of F. Tricerri and L. Vanhecke [8] is partially extendable to 4-dimensional case under compactness hypothesis, namely, we shall prove the following:

**Theorem A.** Let M = (M, J, g) be a 4-dimensional generalized complex space form. Then M is locally a real space form or globally conformal Kähler manifold. In the latter case,  $(M, J, g^*)$  with  $g^* = (3\tau^* - \tau)^{\frac{2}{3}}g$  is a Kähler manifold, where  $\tau$  and  $\tau^*$  are the scalar curvature and the \*-scalar curvature of M, respectively.

**Theorem B.** Let M = (M, J, g) be a compact 4-dimensional generalized complex space form. Then M is a real space form of constant non-positive sectional curvature or compact complex space form.

Remark. There is an example of 4-dimensional compact non-Hermitian, almost Hermitian flat manifold (cf. [1]). Further, there does not exist 4-dimensional compact Hermitian manifold of negative constant sectional curvature (cf. [5]). However, the author does not know whether there exist a 4-dimensional compact non-Hermitian almost Hermitian manifolds of negative constant sectional curvature or not.

#### **2** Preliminaries

Let M = (M, J, g) be a 2n-dimensional almost Hermitian manifold with the almost complex structure J and the metric g. We denote by  $\nabla$ , R,  $\rho$  and  $\tau$  the Levi-Civita connection, the Riemannian curvature tensor, the Ricci tensor and the scalar curvature tensor, respectively. We assume that the Riemannian curvature tensor Ris defined by

(2.1) 
$$R(X,Y)Z = \nabla_X(\nabla_Y Z) - \nabla_Y(\nabla_X Z) - \nabla_{[X,Y]}Z$$

for X, Y and  $Z \in \mathfrak{X}(M)$  ( $\mathfrak{X}(M)$  denotes Lie algebra of all smooth vector fields on M). Further, we denote by  $\rho^*$  and  $\tau^*$  the Ricci \*-tensor and the \*-scalar curvature of M, respectively. The tensor  $\rho^*$  is defined pointwisely by

(2.2) 
$$\rho^*(x,y) = trace(z \mapsto R(Jz,x)Jy)$$
$$= -\sum_{i=1.}^{2n} R(x,e_i,Jy,Je_i)$$
$$= -\frac{1}{2}\sum_{i=1}^{2n} R(x,Jy,e_i,Je_i),$$

for  $x, y, z \in T_pM$ ,  $p \in M$ , where R(x, y, z, w) = g(R(x, y)z, w) and  $\{e_i\}$  is an orthonormal basis of  $T_pM$ . The \*-scalar curvature of M is defined by  $\tau^* =$  trace of  $Q^*$ , where  $Q^*$  is the Ricci \* - operator defined by  $\rho^*(x, y) = g(Q^*x, y)$ , for  $x, y \in T_pM$ ,  $p \in M$ . We note that  $\rho^*$  satisfies  $\rho^*(Jx, Jy) = \rho^*(y, x)$  for  $x, y \in T_pM$ ,  $p \in M$ , but is not symmetric in general. An almost Hermitian manifold M is called a *weakly* \*-*Einstein manifold* if  $\rho^* = \frac{\tau^*}{2n}g$  (dimM = 2n) holds, and in addition, if  $\tau^*$  is constant-valued, then M is called \*-*Einstein manifold*. There exist many examples of weakly \* - Einstein but not \* - Einstein manifolds (cf. [9], [10] and [11]).

Now we return to 4-dimensional almost Hermitian manifold M = (M, J, g) under consideration. We denote by  $\wedge^2 M$  the real vector bundle of all the real 2-forms on M. The  $\wedge^2 M$  inherits a natural inner product coming from the Riemannian metric g and we have the following orthogonal decomposition:

(2.3) 
$$\wedge^2 M = \mathbb{R}\Omega \oplus LM \oplus \wedge_0^{1,1}M$$

where LM (resp.  $\wedge_0^{1,1}M$ ) is the bundle of J-skew invariant (J-invariant) effective 2-forms on M. We can identify the bundle  $\mathbb{R}\Omega \oplus LM$  (resp.  $\wedge_0^{1,1}M$ ) with the bundle  $\wedge_+^2 M$  (resp.  $\wedge_-^2 M$ ) of the self-dual (resp. anti-self dual) 2-forms on M. The bundle LM is endowed with the complex structure (denoted also by J) given by  $(J\Phi)(X,Y) = -\Phi(JX,Y)$ , for any local section of  $\Phi$  of LM and any  $X, Y \in \mathfrak{X}(M)$ . We note that the almost complex structure J acts also on 1-form  $\sigma$  by  $(J\sigma) =$  $-\sigma(JX)$ , for any  $X \in \mathfrak{X}(M)$ . Corresponding to the decomposition (2.3), we may set

(2.4) 
$$\nabla \Omega = \alpha \otimes \Phi + \beta \otimes J \Phi$$

for some local 1-forms  $\alpha$  and  $\beta$ , where  $\Phi, J\Phi$  is a local orthonormal basis of LM. It is well-known that the almost complex structure J of M is integrable if and only if  $(\nabla_X J)Y = (\nabla_{JX}J)JY$  holds for  $X, Y \in \mathfrak{X}(M)$ . So, from (2.4), we see that J is integrable if and only if  $\beta = J\alpha$  holds on a neighborhood of any point of M. Since the dim M = 4, we see that there does not exist effective 3-forms on M and hence, any 3-form  $\eta$  is represented as  $\eta = \sigma \wedge \Omega$  for some 1-form  $\sigma$ . Thus, we may set especially

$$(2.5) d\Omega = \omega \wedge \Omega$$

for some 1-form  $\omega$  on M. The 1-form  $\omega$  is called the *Lee form* of M, and is given by

(2.6) 
$$\omega = -\delta \Omega \circ J.$$

Let  $\{e_i\} = \{e_1, e_2 = Je_1, e_3, e_4 = Je_3\}$  be any (local) unitary basis of  $T_p M (p \in M)$ and  $\{e^i\} = \{e^1, e^2 = Je^1, e^3, e^4 = Je^3\}$  be the dual basis of  $\{e_i\}$ . Then, the Kähler

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form  $\Omega$  is represented by  $\Omega = e^1 \wedge e^2 + e^3 \wedge e^4$ . Further, we see that

$$\{\Phi, J\Phi\} = \{\frac{1}{\sqrt{2}}(e^{1} \wedge e^{3} - e^{2} \wedge e^{4}), \frac{1}{\sqrt{2}}(e^{1} \wedge e^{4} + e^{2} \wedge e^{3})\},$$

$$(2.7) \qquad \{\psi_{1}, \psi_{2}, \psi_{3}\} = \{\frac{1}{\sqrt{2}}(e^{1} \wedge e^{2} - e^{3} \wedge e^{4}), \frac{1}{\sqrt{2}}(e^{1} \wedge e^{3} - e^{2} \wedge e^{4}), \frac{1}{\sqrt{2}}(e^{1} \wedge e^{4} - e^{2} \wedge e^{3})\}$$

are (locally) orthonormal bases of LM and  $\wedge_0^{1,1}M = \wedge_-^2 M$ , respectively. In this paper, for any (local) unitary basis  $\{e_i\}$  of  $T_pM$  at any point  $p \in M$ , we shall adopt the following notational convention:

$$J_{ij} = g(Je_i, e_j)$$

$$(2.8) \qquad \nabla_i J_{jk} = g((\nabla_{e_i} J)e_j, e_k), ..., \nabla_{\bar{i}} J_{\bar{j}\bar{k}} = g((\nabla_{Je_i} J)Je_j, Je_k)$$

$$R_{ijkl} = g(R(e_i, e_j)e_k, e_l), ..., R_{\bar{i}\bar{j}\bar{k}\bar{l}} = g(R(Je_i, Je_j)Je_k, Je_l),$$

and so on where the latin indices ranges over 1, 2, 3, 4. Following this notational convention, from (2.6), we have

(2.9) 
$$\omega_k = \sum_{i,j} (\nabla_i J_{ij}) J_{kj}$$

### **3** Proofs of Theorem A and B

First we prove Theorem A.

Let M = (M, J, g) be a 4 - dimensional generalized complex space form. Then (1.1) reduces to

$$(3.1) R(x, y, z, w) = \frac{5\tau - 3\tau^*}{48} \{g(y, z)g(x, w) - g(x, z)g(y, w)\} + \frac{3\tau^* - \tau}{48} \{g(Jx, w)g(Jy, z) - g((Jy, w)g(Jx, z)) - 2g(Jx, y)g(Jz, w)\}$$

for  $x, y, z, w \in T_p M(p \in M)$ . First of all, from (3.1), we may note that M is Einstein $\left(\rho = \frac{\tau}{4}g\right)$  and weakly \*-Einstein  $\left(\rho^* = \frac{\tau^*}{4}g\right)$ ; and, further a space of pointwise constant holomorphic sectional curvature  $\frac{1}{24}(3\tau^* + \tau)$ . Now, from (3.1),

we also get

(3.2)

$$\begin{array}{l} (\nabla_{u}R)(x,y,z,w) \\ = -\frac{1}{16}u(\tau^{*})\{g(x,w)g(y,z) - g(y,w)g(x,z) \\ -g(Jx,w)g(Jy,z) + g(Jy,w)g(Jx,z) \\ +2g(Jx,y)g(Jz,w)\} + \frac{3\tau^{*}-\tau}{48}\{g(Jy,z)g((\nabla_{u}J)x,w) \\ +g(Jx,w)g((\nabla_{u}J)y,z) - g(Jx,z)g((\nabla_{u}J)y,w) \\ -g(Jy,w)g((\nabla_{u}J)x,z) - 2g(Jx,y)g((\nabla_{u}J)z,w) \\ -2g(Jz,w)g((\nabla_{u}J)x,y)\} \end{array}$$

for  $u, x, y, z, w \in T_p M (p \in M)$ .

Let  $\{e_i\}$  be any unitary basis of  $T_pM$  at any point  $p \in M$ . Then, since M is Einstein, from (3.2), we get

$$(3.3) 0 = (\nabla_w \rho)(y, z) - (\nabla_z \rho)(y, w) = \sum_{i=1}^4 (\nabla_{e_i} R)(e_i, y, z, w) = -\frac{1}{16} \{ w(\tau^*)g(y, z) - z(\tau^*)g(y, w) + (Jw)(\tau^*)g(Jy, z) - (Jz)(\tau^*)g(Jy, w) - 2(Jy)(\tau^*)g(Jz, w) \} + \frac{3\tau^* - \tau}{48} \{ -g((\nabla_{Jw}J)y, z) + g((\nabla_{Jz}J)y, w) + (J\omega)(w)g(Jy, z) - (J\omega)(z)g(Jy, w) - 2(J\omega)(y)g(Jz, w) + 2g((\nabla_{Jy}J)z, w) \}$$

for  $y, z, w \in T_p M (p \in M)$ .

By setting  $w = e_1$ ,  $y = z = e_3$  in (3.3) we get

(3.4) 
$$e_1(3\tau^* - \tau) + 3(3\tau^* - \tau)g((\nabla_{e_4}J)e_1, e_3) = 0.$$

Similarly, by setting  $w = e_1$ ,  $y = z = e_4$  in (3.3) we get

(3.5) 
$$e_1(3\tau^* - \tau) - 3(3\tau^* - \tau)g((\nabla_{e_3}J)e_1, e_4) = 0.$$

Further, we get the following:

(3.6) 
$$e_2(3\tau^* - \tau) + 3(3\tau^* - \tau)g((\nabla_{e_4}J)e_2, e_3) = 0,$$

(3.7) 
$$e_2(3\tau^* - \tau) - (3\tau^* - \tau)g((\nabla_{e_3}J)e_2, e_4) = 0,$$

(3.8) 
$$e_3(3\tau^*-\tau) - 3(3\tau^*-\tau)g((\nabla_{e_2}J)e_1,e_3) = 0,$$

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(3.9) 
$$e_3(3\tau^* - \tau) + 3(3\tau^* - \tau)g((\nabla_{e_1}J)e_2, e_3) = 0,$$

(3.10) 
$$e_4(3\tau^* - \tau) - 3(3\tau^* - \tau)g((\nabla_{e_2}J)e_1, e_4) = 0,$$

(3.11) 
$$e_4(3\tau^* - \tau) + 3(3\tau^* - \tau)g((\nabla_{e_1}J)e_2, e_4) = 0.$$

From  $(3.4)\sim(3.11)$ , taking the account of (2.4) and (2.7), we have

$$(3.12) \qquad (3\tau^* - \tau)(\beta - J\alpha) = 0.$$

Let  $M_o = \{p \in M | 3\tau^* - \tau = 0 \text{ at } p\}$ . Since M is Einstein, M is real analytic as Riemannian manifold. Thus, if the interior of  $M_o$  is not empty, then M is locally a real space form of dimension 4 by (3.1). In the sequel, we assume that the interior of  $M_o$  is empty. Then we see that the complement  $M'_o$  of  $M_o$  in M is an open dense subset of M, and  $\beta - J\alpha = 0$  holds on a neighborhood of any point  $M'_o$  by virtue (3.12). Thus, we see that J is integrable. Therefore, we get  $(\nabla_X J)Y = (\nabla_{JX}J)JY$ holds for any  $X, Y \in \mathfrak{X}(M)$ .

By direct calculation, we get

$$g((\nabla_{e_4}J)e_1, e_3) = -g((\nabla_{e_4}J)e_2, e_4) = g((\nabla_{e_4}J)e_4, e_2),$$
  
$$g((\nabla_{e_3}J)e_1, e_4) = g((\nabla_{e_3}J)e_2, e_3) = -g((\nabla_{e_3}J)e_3, e_2),$$

and hence

(3.13) 
$$-g((\nabla_{e_4}J)e_1, e_3) = g((\nabla_{e_3}J)e_1, e_4) = -\frac{1}{2}\omega_1$$

by virtue of (2.9). Similarly, we get

(3.14)  

$$-g((\nabla_{e_4}J)e_2, e_3) = g((\nabla_{e_3}J)e_2, e_4) = -\frac{1}{2}\omega_2,$$

$$g((\nabla_{e_2}J)e_1, e_3) = -g((\nabla_{e_1}J)e_2, e_3) = -\frac{1}{2}\omega_3,$$

$$g((\nabla_{e_2}J)e_1, e_4) = -g((\nabla_{e_1}J)e_2, e_4) = -\frac{1}{2}\omega_4.$$

Thus, by  $(3.4)\sim(3.11)$ , (3.13) and (3.14), we have finally the following differential equation

(3.15) 
$$d(3\tau^* - \tau) + \frac{3}{2}(3\tau^* - \tau)\omega = 0.$$

By (3.15) and our hypothesis, we can immediately see that the function  $3\tau^* - \tau$  vanishes nowhere on M. Thus, taking the exterior derivative of equality (3.15), we have further

$$(3.16) d\omega = 0 on M$$

Therefore, it follows from (3.16) that M is locally conformal Kähler manifold.

Now, we consider a new Riemannian metric  $g^*$  defined by  $g^* = (3\tau^* - \tau)^{\frac{4}{3}}g$ . Then, we see that  $(M, J, g^*)$  is a (real) 4-dimensional Hermitian manifold with the corresponding Kähler form  $\Omega^* = (3\tau^* - \tau)^{\frac{2}{3}}\Omega$ . By (2.5) and (3.15), we may easily check that  $d\Omega^* = 0$  holds on M, and hence, (M, J, g) is a Kähler manifold of real dimension 4. This completes the proof of Theorem A.

Next, we shall prove Theorem B. From (3.1), taking account of the result by Koda ([1], Prop. 4.1), we see that a 4-dimensional generalized complex space form is a self-dual Einstein manifold. On one hand, it is well-known that a 4-dimensional sphere does not admit almost complex structure. Therefore, we see that Theorem B follows immediately from the arguments in this section and the following result ([2] and [5])

**Theorem C.** Let M = (M, J, g) be a compact self-dual Einstein Hermitian surface. Then M is a compact complex space form.

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