# Solvability of a fractional integral equation with the concept of measure of noncompactness 

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#### Abstract

We study the existence of solutions for a new class of integral equations involving a fractional integral with respect to another function. Our techniques are based on the measure of non-compactness concept combined with a generalized version of Darbo's theorem. Some examples are presented to illustrate the obtained results.


## 1 Introduction

Many problems in several branches of science such as engineering, physics, biology and other disciplines can be modeled as an integral equation (see, for example $[10,23,32,34,35]$ ). The most used techniques to study the existence of solutions to an integral equation are based on fixed point arguments. For example, Banach contraction principle was used by several authors in order to establish existence results for different kinds of integral equations (see, for example [27, 29, 30, 33]). Similarly, many solvability results were derived via Schauder's fixed point theorem (see, for example [14, 25, 26]). On the other hand, in the absence of compacity and the Lipschitz condition, the above mentioned theorems cannot be applied. In such situation, the measure of non-compactness concept can be useful in order to avoid the mentioned problems.

Several existence results for integral equations were established using fixed point theorems involving measures of non-compactness. For more details, we

[^0]refer the reader to $[1,3,4,5,7,8,9,12,13,15,20,21,28]$ and the references therein. On the other hand, due to the importance of fractional calculus in modelling various problems from many fields of science and engineering, a great attention has been focused recently on the study of fractional integral equations (see, for example [ $2,6,11,16,17,18,24]$ ).

In this paper, we deal with a new class of fractional integral equations involving a fractional integral with respect to another function. Using a fixed point theorem involving measures of non-compactness, an existence result is established. Some numerical examples are also provided.

## 2 Problem formulation and preliminaries

The main purpose of this paper is to study the following integral equation

$$
\begin{equation*}
x(t)=f_{1}(t, x(t))+\frac{f_{2}(t, x(t))}{\Gamma(\alpha)} \int_{a}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau, \quad t \in[a, T] \tag{2.1}
\end{equation*}
$$

where $\alpha \in(0,1), 0 \leq a<T, k:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}, g:[a, T] \rightarrow \mathbb{R}$ and $f_{i}:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}(i=1,2)$, from the point of view of the theory of existence of solutions. Eq.(2.1) can be written in the form

$$
x(t)=f_{1}(t, x(t))+f_{2}(t, x(t)) I_{a, g}^{\alpha} k(\cdot, x(\cdot))(t), \quad t \in[a, T],
$$

where $I_{a, g}^{\alpha}$ is the fractional integral of order $\alpha$ with respect to the function $g$ defined by

$$
I_{a, g}^{\alpha} \psi(t)=\frac{1}{\Gamma(\alpha)} \int_{a}^{t} \frac{g^{\prime}(\tau) \psi(\tau)}{(g(t)-g(\tau))^{1-\alpha}} d \tau, \quad t \in[a, T] .
$$

In the particular case $g(\tau)=\tau$, Eq.(2.1) models some problems in the queuing theory and biology (see [19]). In such case, $I_{a, g}^{\alpha}$ is the Riemann-Liouville fractional integral defined by

$$
\begin{equation*}
I_{a}^{\alpha} \psi(t)=\frac{1}{\Gamma(\alpha)} \int_{a}^{t} \frac{\psi(\tau)}{(t-\tau)^{1-\alpha}} d \tau, \quad t \in[a, T] \tag{2.2}
\end{equation*}
$$

In the case $g(\tau)=\tau^{\beta}(\beta>0), I_{a, g}^{\alpha}$ is the Erdélyi-Kober fractional integral defined by

$$
\begin{equation*}
I_{a, \beta}^{\alpha} \psi(t)=\frac{\beta}{\Gamma(\alpha)} \int_{a}^{t} \frac{\tau^{\beta-1} \psi(\tau)}{\left(t^{\beta}-\tau^{\beta}\right)^{1-\alpha}} d \tau, \quad t \in[a, T] \tag{2.3}
\end{equation*}
$$

However, in the case $g(\tau)=\ln \tau$ and $a>0, I_{a, g}^{\alpha}$ is the Hadamard fractional integral defined by

$$
\begin{equation*}
J_{a}^{\alpha} \psi(t)=\frac{1}{\Gamma(\alpha)} \int_{a}^{t}\left(\ln \frac{t}{\tau}\right)^{\alpha-1} \frac{\psi(\tau)}{\tau} d \tau, \quad t \in[a, T] \tag{2.4}
\end{equation*}
$$

For more details on fractional calculus, we refer the reader to [31].

Using a measure of non-compactness in the set $C([a, T] ; \mathbb{R})$ of real continuous functions in $[a, T]$ introduced by Banaś and Goebel [8], we give sufficient conditions for the existence of at least one solution to Eq.(2.1). To the best of our knowledge, an integral equation of the type (2.1) has not been considered earlier.

Before presenting and proving the main results of this paper, we need to recall some basic concepts and present some preliminaries results that will be useful later.

Let $(H,\|\cdot\|)$ be a given Banach space. We denote by $B_{H}$ the family of all nonempty bounded subsets of $H$. A mapping $\eta: B_{H} \rightarrow[0, \infty)$ is said to be a measure of non-compactness (see [8]) if it satisfies the following axioms:
(A1) for all $B \in B_{H}$, we have

$$
\eta(B)=0 \Longrightarrow B \text { is precompact; }
$$

(A2) for every pair $\left(B_{1}, B_{2}\right) \in B_{H} \times B_{H}$, we have

$$
B_{1} \subseteq B_{2} \Longrightarrow \eta\left(B_{1}\right) \leq \eta\left(B_{2}\right) ;
$$

(A3) for every $B \in B_{H}$,

$$
\eta(\bar{B})=\eta(B)=\eta(\overline{\operatorname{co}} B),
$$

where $\overline{\mathrm{co}} B$ denotes the closed convex hull of $B$;
(A4) for every pair $\left(B_{1}, B_{2}\right) \in B_{H} \times B_{H}$ and $\lambda \in(0,1)$, we have

$$
\eta\left(\lambda B_{1}+(1-\lambda) B_{2}\right) \leq \lambda \eta\left(B_{1}\right)+(1-\lambda) \eta\left(B_{2}\right) ;
$$

(A5) if $\left\{B_{n}\right\}$ is a sequence of closed and decreasing (w.r.t $\subseteq$ ) sets in $B_{H}$ such that $\eta\left(B_{n}\right) \rightarrow 0$ as $n \rightarrow \infty$, then $B_{\infty}:=\bigcap_{n=1}^{\infty} B_{n}$ is nonempty and compact.

A function $\varphi:[0, \infty) \rightarrow[0, \infty)$ is said to be a comparison function if it satisfies the following properties:
(i) $\varphi$ is non-decreasing;
(ii) $\lim _{n \rightarrow \infty} \varphi^{(n)}(t)=0$, for all $t>0$, where $\varphi^{(n)}$ denotes the $n$-iteration of $\varphi$.

Examples of comparison functions are

$$
\varphi(t)=\lambda t, \lambda \in[0,1) ; \varphi(t)=\arctan t ; \varphi(t)=\ln (1+t) ; \varphi(t)=\frac{t}{1+t} .
$$

Through this paper, we denote by $\Phi$ the set of comparison functions.
In [5], Aghajani et al. proved the following useful result in order to prove that a function is a comparison function.

Lemma 2.1. Let $\varphi:[0, \infty) \rightarrow[0, \infty)$ be a non-decreasing and upper semi-continuous function. Then the following conditions are equivalent:
(i) $\lim _{n \rightarrow \infty} \varphi^{(n)}(t)=0$ for all $t>0$.
(ii) $\varphi(t)<t$ for all $t>0$.

In the same paper, the authors proved the following generalization of Darbo's theorem (see [1]).

Lemma 2.2. Let C be a nonempty, bounded, closed and convex subset of a Banach space H. Let $U: C \rightarrow C$ be a continuous mapping such that

$$
\eta(U W) \leq \varphi(\eta(W)), \quad W \subseteq C,
$$

where $\varphi \in \Phi$ and $\eta$ is a measure of non-compactness in $H$. Then $U$ has at least one fixed point.

For given functions $\varphi, \psi:[0, \infty) \rightarrow \mathbb{R}$ and a real number $\lambda$, define the operators $T_{\text {max }}$ and $T$ by

$$
T_{\max }(\varphi, \psi)(t)=\max \{\varphi(t), \psi(t)\}, \quad t \geq 0
$$

and

$$
T(\lambda, \varphi)(t)=\lambda \varphi(t), \quad t \geq 0
$$

Denote by $C([0, \infty) ; \mathbb{R})$ the set of real continuous functions in $[0, \infty)$ and by $\widetilde{\Phi}$ the set $\Phi \cap C([0, \infty) ; \mathbb{R})$.

The following lemma is interesting for our purpose.
Lemma 2.3. The following properties hold:
(i) $T_{\max }(\widetilde{\Phi} \times \widetilde{\Phi}) \subseteq \widetilde{\Phi}$.
(ii) $T([0,1] \times \widetilde{\Phi}) \subseteq \widetilde{\Phi}$.

Proof. Let $(\varphi, \psi) \in \widetilde{\Phi} \times \widetilde{\Phi}$. We have to prove that $T_{\max }(\varphi, \psi):[0, \infty) \rightarrow[0, \infty)$ belongs to $\widetilde{\Phi}$. Since the maximum of a finite number of continuous functions is continuous, we have $T_{\max }(\varphi, \psi) \in C([0, \infty) ; \mathbb{R})$. Moreover, since $(\varphi, \psi) \in \widetilde{\Phi} \times$ $\widetilde{\Phi} \subseteq \Phi \times \Phi$, then $\varphi$ and $\psi$ are non-decreasing functions, which yields $T_{\max }(\varphi, \psi)$ is also a non-decreasing function. From Lemma 2.1, we have

$$
\varphi(t)<t, \psi(t)<t, \quad t>0
$$

Then

$$
T_{\max }(\varphi, \psi)(t)<t, \quad t>0
$$

Again, by Lemma 2.1, we get

$$
\lim _{n \rightarrow \infty}\left[T_{\max }(\varphi, \psi)\right]^{(n)}(t)=0, \quad t>0
$$

Therefore, $T_{\max }(\varphi, \psi) \in \Phi$. As consequence, $T_{\max }(\varphi, \psi) \in \Phi \cap C([0, \infty) ; \mathbb{R})=\widetilde{\Phi}$, which proves (i). A similar argument can be used to prove (ii).

Let $H=C([a, T] ; \mathbb{R})$ be the set of real continuous functions in $[a, T]$. Such a set is a Banach space with respect to the norm

$$
\|v\|=\max \{|v(t)|: t \in[a, T]\}, \quad v \in C([a, T] ; \mathbb{R})
$$

We will use the following notations through this paper. Let $B \in B_{H}$. For $v \in B$ and $\rho \geq 0$, set

$$
\omega(v, \rho)=\sup \{|v(t)-v(s)|: t, s \in[a, T],|t-s| \leq \rho\} .
$$

We define the mapping $\Omega: B_{H} \times[0, \infty) \rightarrow[0, \infty)$ by

$$
\Omega(B, \rho)=\sup \{\omega(v, \rho): v \in B\}, \quad(B, \rho) \in B_{H} \times[0, \infty) .
$$

It was proved in [8] that the mapping $\eta: B_{H} \rightarrow[0, \infty)$ defined by

$$
\eta(B)=\lim _{\rho \rightarrow 0^{+}} \Omega(B, \rho), \quad B \in B_{H}
$$

is a measure of non-compactness in the Banach space $H$.
Now, we are ready to present our main results. This is the aim of the next section.

## 3 Main results

Our first existence result is obtained under the following hypotheses:
(H1) The functions $f_{i}:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}(i=1,2)$ are continuous.
(H2) There exist functions $\varphi_{1}, \varphi_{2}:[0, \infty) \rightarrow[0, \infty)$ such that
(i) $\varphi_{i}(0)=0, i=1,2$.
(ii) $\varphi_{1}$ is non-decreasing and continuous.
(iii) $\varphi_{2} \in \widetilde{\Phi}$.
(iv) There exist $\delta \geq 0$ and $\theta \in \widetilde{\Phi}$ such that

$$
\varphi_{1}(t) \leq \delta \theta(t), \quad t \geq 0
$$

(v) For all $(t, u, v) \in[a, T] \times \mathbb{R} \times \mathbb{R}$, we have

$$
\left|f_{i}(t, u)-f_{i}(t, v)\right| \leq \varphi_{i}(|u-v|), \quad i=1,2 .
$$

(H3) The function $k:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous and it satisfies

$$
|k(t, u)| \leq \varphi(|u|), \quad(t, u) \in[a, T] \times \mathbb{R},
$$

where $\varphi:[0, \infty) \rightarrow[0, \infty)$ is a non-decreasing function.
(H4) $g \in C([a, T] ; \mathbb{R}) \cap C^{1}((a, T] ; \mathbb{R})$ with $g^{\prime}(t)>0$, for all $t \in(a, T]$.
(H5) There exists $r_{0}>0$ such that

$$
\left(\varphi_{1}\left(r_{0}\right)+f_{1}^{*}\right) \Gamma(\alpha+1)+\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha} \leq r_{0} \Gamma(\alpha+1)
$$

and, moreover

$$
\delta+\frac{\varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}(g(T)-g(a))^{\alpha} \leq 1
$$

where

$$
f_{i}^{*}=\max \left\{\left|f_{i}(t, 0)\right|: t \in[a, T]\right\}, \quad i=1,2 .
$$

Our main result is the following.

Theorem 3.1. Under the assumptions (H1)-(H5), Eq.(2.1) has at least one solution $y^{*} \in C([a, T] ; \mathbb{R})$. Moreover, we have $\left\|y^{*}\right\| \leq r_{0}$.
Proof. Let us consider the operator $U$ defined on $H=C([a, T] ; \mathbb{R})$ by

$$
\begin{equation*}
(U x)(t)=f_{1}(t, x(t))+\frac{f_{2}(t, x(t))}{\Gamma(\alpha)} \int_{a}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau, \quad(x, t) \in H \times[a, T] \tag{3.1}
\end{equation*}
$$

At first, we show that the operator $U$ maps $H$ into itself. Set

$$
\begin{equation*}
(G x)(t)=\int_{a}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau, \quad(x, t) \in H \times[a, T] \tag{3.2}
\end{equation*}
$$

From assumption (H1), we have just to prove that $G$ maps $H$ into itself, that is, $G x:[a, T] \rightarrow \mathbb{R}$ is continuous for every $x \in H$. Observe that $G x$ is well-defined. In fact, for all $t \in[a, T]$, from assumption (H3), we have

$$
\begin{equation*}
|(G x)(t)| \leq \varphi(\|x\|) \int_{a}^{t} \frac{g^{\prime}(\tau)}{(g(t)-g(\tau))^{1-\alpha}} d \tau=\frac{\varphi(\|x\|)}{\alpha}(g(t)-g(a))^{\alpha}<\infty . \tag{3.3}
\end{equation*}
$$

Let us check the continuity of $G x$ at the point $a$. Let $\left\{t_{n}\right\}$ be a sequence in $[a, T]$ such that $t_{n} \rightarrow a^{+}$as $n \rightarrow \infty$. Using (3.3), for all $n \in \mathbb{N}$, we have

$$
\left|(G x)\left(t_{n}\right)\right| \leq \varphi(\|x\|) \int_{a}^{t_{n}} \frac{g^{\prime}(\tau)}{\left(g\left(t_{n}\right)-g(\tau)\right)^{1-\alpha}} d \tau=\frac{\varphi(\|x\|)}{\alpha}\left(g\left(t_{n}\right)-g(a)\right)^{\alpha}
$$

Letting $n \rightarrow \infty$ in the above inequality and using the continuity of $g$, we get

$$
\lim _{n \rightarrow \infty}(G x)\left(t_{n}\right)=0=(G x)(a),
$$

which proves the continuity of $G x$ at the point $a$. Now, let $t \in(a, T]$ be fixed and $\left\{t_{n}\right\}$ be a sequence in $(a, T]$ such that $t_{n} \rightarrow t$ as $n \rightarrow \infty$. Without restriction of the generality, we may assume that $t_{n} \geq t$ for $n$ large enough. We have

$$
\begin{aligned}
& \left|(G x)\left(t_{n}\right)-(G x)(t)\right|= \\
& \quad\left|\int_{a}^{t_{n}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{n}\right)-g(\tau)\right)^{1-\alpha}} d \tau-\int_{a}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau\right|, \quad n \in \mathbb{N} .
\end{aligned}
$$

For $n$ large enough, we can write

$$
\begin{aligned}
\mid(G x)\left(t_{n}\right)- & (G x)(t) \mid \\
\leq & \left|\int_{a}^{t}\left(\frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{n}\right)-g(\tau)\right)^{1-\alpha}}-\frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}}\right) d \tau\right| \\
& +\left|\int_{t}^{t_{n}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{n}\right)-g(\tau)\right)^{1-\alpha}} d \tau\right| \\
\leq & \varphi(\|x\|) \int_{a}^{t}\left(\frac{g^{\prime}(\tau)}{(g(t)-g(\tau))^{1-\alpha}}-\frac{g^{\prime}(\tau)}{\left(g\left(t_{n}\right)-g(\tau)\right)^{1-\alpha}}\right) d \tau \\
& +\varphi(\|x\|) \int_{t}^{t_{n}} \frac{g^{\prime}(\tau)}{\left(g\left(t_{n}\right)-g(\tau)\right)^{1-\alpha}} d \tau \\
= & \frac{\varphi(\|x\|)}{\alpha}\left((g(t)-g(a))^{\alpha}+\left(g\left(t_{n}\right)-g(t)\right)^{\alpha}-\left(g\left(t_{n}\right)-g(a)\right)^{\alpha}\right) \\
& +\frac{\varphi(\|x\|)}{\alpha}\left(g\left(t_{n}\right)-g(t)\right)^{\alpha} .
\end{aligned}
$$

Since $g$ is continuous in $[a, T]$, we have

$$
\begin{aligned}
\lim _{n \rightarrow \infty} \frac{\varphi(\|x\|)}{\alpha}\left((g(t)-g(a))^{\alpha}+\left(g\left(t_{n}\right)-g(t)\right)^{\alpha}-\right. & \left.\left(g\left(t_{n}\right)-g(a)\right)^{\alpha}\right)+ \\
& \frac{\varphi(\|x\|)}{\alpha}\left(g\left(t_{n}\right)-g(t)\right)^{\alpha}=0
\end{aligned}
$$

which yields $\lim _{n \rightarrow \infty}\left|(G x)\left(t_{n}\right)-(G x)(t)\right|=0$. Then $G x$ is continuous at $t$. As consequence, $G x \in H$, for all $x \in H$, and $U: H \rightarrow H$ is well-defined.

On the other hand, for an arbitrarily fixed $x \in H$ and $t \in[a, T]$, we have

$$
\begin{aligned}
|(U x)(t)| \leq & \left|f_{1}(t, x(t))\right|+\frac{\left|f_{2}(t, x(t))\right|}{\Gamma(\alpha)} \int_{a}^{t} \frac{g^{\prime}(\tau)|k(\tau, x(\tau))|}{(g(t)-g(\tau))^{1-\alpha}} d \tau \\
\leq & \left|f_{1}(t, x(t))-f_{1}(t, 0)\right|+\left|f_{1}(t, 0)\right| \\
& +\frac{\left|f_{2}(t, x(t))-f_{2}(t, 0)\right|+\left|f_{2}(t, 0)\right|}{\Gamma(\alpha)} \int_{a}^{t} \frac{g^{\prime}(\tau) \varphi(|x(\tau)|)}{(g(t)-g(\tau))^{1-\alpha}} d \tau \\
\leq & \varphi_{1}(|x(t)|)+f_{1}^{*}+\frac{\left(\varphi_{2}(|x(t)|)+f_{2}^{*}\right) \varphi(\|x\|)}{\Gamma(\alpha+1)}(g(t)-g(a))^{\alpha} \\
\leq & \varphi_{1}(\|x\|)+f_{1}^{*}+\frac{\left(\varphi_{2}(\|x\|)+f_{2}^{*}\right) \varphi(\|x\|)}{\Gamma(\alpha+1)}(g(T)-g(a))^{\alpha} .
\end{aligned}
$$

Then

$$
\|U x\| \leq \varphi_{1}(\|x\|)+f_{1}^{*}+\frac{\left(\varphi_{2}(\|x\|)+f_{2}^{*}\right) \varphi(\|x\|)}{\Gamma(\alpha+1)}(g(T)-g(a))^{\alpha}, \quad x \in H .
$$

From the above inequality, the fact that the functions $\varphi_{1}, \varphi_{2}, \varphi:[0, \infty) \rightarrow[0, \infty)$ are non-decreasing, and assumption (H5), we infer that the operator $U$ maps $\overline{B\left(0, r_{0}\right)}$ into itself, where

$$
\overline{B\left(0, r_{0}\right)}=\left\{x \in H:\|x\| \leq r_{0}\right\} .
$$

Now, we claim that the operator $U: \overline{B\left(0, r_{0}\right)} \rightarrow \overline{B\left(0, r_{0}\right)}$ is continuous. We write $U$ in the form

$$
U x=F_{1} x+\frac{1}{\Gamma(\alpha)} F_{2} x+G X, \quad x \in \overline{B\left(0, r_{0}\right)},
$$

where

$$
\left(F_{i} x\right)(t)=f_{i}(t, x(t)), \quad(x, t) \in \overline{B\left(0, r_{0}\right)} \times[a, T], i=1,2
$$

and $G$ is defined by (3.2). In order to prove our claim, it is sufficient to show that the operators $F_{i}(i=1,2)$ and $G$ are continuous on $\overline{B\left(0, r_{0}\right)}$. Firstly, we show that $F_{i}$ are continuous operators on $\overline{B\left(0, r_{0}\right)}$. To do this, we take a sequence $\left\{x_{n}\right\} \subset$ $\overline{B\left(0, r_{0}\right)}$ and $x \in \overline{B\left(0, r_{0}\right)}$ such that $\left\|x_{n}-x\right\| \rightarrow 0$ as $n \rightarrow \infty$, and we have to prove that $\left\|F_{i} x_{n}-F_{i} x\right\| \rightarrow 0$ as $n \rightarrow \infty$. In fact, for all $t \in[a, T]$, we have

$$
\begin{aligned}
\left|\left(F_{i} x_{n}\right)(t)-\left(F_{i} x\right)(t)\right| & =\left|f_{i}\left(t, x_{n}(t)\right)-f_{i}(t, x(t))\right| \\
& \leq \varphi_{i}\left(\left|x_{n}(t)-x(t)\right|\right) \\
& \leq \varphi_{i}\left(\left\|x_{n}-x\right\|\right) .
\end{aligned}
$$

Then

$$
\left\|F_{i} x_{n}-F_{i} x\right\| \leq \varphi_{i}\left(\left\|x_{n}-x\right\|\right), \quad n \in \mathbb{N}
$$

Letting $n \rightarrow \infty$ in the above inequality, using the continuity of the functions $\varphi_{i}$ $(i=1,2)$ and the fact that $\varphi_{i}(0)=0$, we get

$$
\lim _{n \rightarrow \infty}\left\|F_{i} x_{n}-F_{i} x\right\| \leq \varphi_{i}\left(\lim _{n \rightarrow \infty}\left\|x_{n}-x\right\|\right)=\varphi_{i}(0)=0
$$

This proves that $F_{i}$ is a continuous operator on $\overline{B\left(0, r_{0}\right)}$, for all $i=1,2$. Next, we show that $G$ is a continuous operator on $\overline{B\left(0, r_{0}\right)}$. To do this, we fix a real number $\varepsilon>0$ and we take arbitrary functions $x, y \in \overline{B\left(0, r_{0}\right)}$ such that $\|x-y\|<\varepsilon$. For all $t \in[a, T]$, we have

$$
\begin{aligned}
|(G x)(t)-(G y)(t)| & \leq \int_{a}^{t} \frac{g^{\prime}(\tau)|k(\tau, x(\tau))-k(\tau, y(\tau))|}{(g(t)-g(\tau))^{1-\alpha}} d \tau \\
& \leq u\left(r_{0}, \varepsilon\right) \int_{a}^{t} \frac{g^{\prime}(\tau)}{(g(t)-g(\tau))^{1-\alpha}} d \tau \\
& =\frac{u\left(r_{0}, \varepsilon\right)}{\alpha}(g(t)-g(a))^{\alpha} \\
& \leq \frac{u\left(r_{0}, \varepsilon\right)}{\alpha}(g(T)-g(a))^{\alpha}
\end{aligned}
$$

where

$$
u\left(r_{0}, \varepsilon\right)=\sup \left\{|k(\tau, v)-k(\tau, w)|: \tau \in[a, T], v, w \in\left[-r_{0}, r_{0}\right],|v-w|<\varepsilon\right\}
$$

Therefore,

$$
\|G x-G y\| \leq \frac{u\left(r_{0}, \varepsilon\right)}{\alpha}(g(T)-g(a))^{\alpha}
$$

Since $k$ is uniform continuous on the compact $[a, T] \times\left[-r_{0}, r_{0}\right]$, we have $u\left(r_{0}, \varepsilon\right) \rightarrow$ 0 as $\varepsilon \rightarrow 0^{+}$and, therefore, the last inequality gives us

$$
\lim _{\varepsilon \rightarrow 0^{+}}\|G x-G y\|=0
$$

Then $G$ is continuous on $\overline{B\left(0, r_{0}\right)}$ and $U$ maps continuously the set $\overline{B\left(0, r_{0}\right)}$ into itself.

Further, let $W$ be a nonempty subset of $\overline{B\left(0, r_{0}\right)}$. Let $\rho>0$ be fixed, $x \in W$ and $t_{1}, t_{2} \in[a, T]$ be such that $\left|t_{1}-t_{2}\right| \leq \rho$. Without restriction of the generality, we
may assume $t_{1} \geq t_{2}$. We have

$$
\begin{aligned}
& \left|(U x)\left(t_{1}\right)-(U x)\left(t_{2}\right)\right| \\
& \leq\left|f_{1}\left(t_{1}, x\left(t_{1}\right)\right)-f_{1}\left(t_{2}, x\left(t_{2}\right)\right)\right| \\
& +\left|\frac{f_{2}\left(t_{1}, x\left(t_{1}\right)\right)}{\Gamma(\alpha)} \int_{a}^{t_{1}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau-\frac{f_{2}\left(t_{2}, x\left(t_{2}\right)\right)}{\Gamma(\alpha)} \int_{a}^{t_{2}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{2}\right)-g(\tau)\right)^{1-\alpha}} d \tau\right| \\
& \leq\left|f_{1}\left(t_{1}, x\left(t_{1}\right)\right)-f_{1}\left(t_{2}, x\left(t_{2}\right)\right)\right| \\
& +\left|\frac{f_{2}\left(t_{1}, x\left(t_{1}\right)\right)}{\Gamma(\alpha)} \int_{a}^{t_{1}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau-\frac{f_{2}\left(t_{2}, x\left(t_{2}\right)\right)}{\Gamma(\alpha)} \int_{a}^{t_{1}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau\right| \\
& +\frac{\left|f_{2}\left(t_{2}, x\left(t_{2}\right)\right)\right|}{\Gamma(\alpha)}\left|\int_{a}^{t_{1}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau-\int_{a}^{t_{2}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{2}\right)-g(\tau)\right)^{1-\alpha}} d \tau\right| \\
& \leq\left|f_{1}\left(t_{1}, x\left(t_{1}\right)\right)-f_{1}\left(t_{1}, x\left(t_{2}\right)\right)\right|+\left|f_{1}\left(t_{1}, x\left(t_{2}\right)\right)-f_{1}\left(t_{2}, x\left(t_{2}\right)\right)\right| \\
& +\frac{\left|f_{2}\left(t_{1}, x\left(t_{1}\right)\right)-f_{2}\left(t_{1}, x\left(t_{2}\right)\right)\right|+\left|f_{2}\left(t_{1}, x\left(t_{2}\right)\right)-f_{2}\left(t_{2}, x\left(t_{2}\right)\right)\right|}{\Gamma(\alpha)} \int_{a}^{t_{1}} \frac{g^{\prime}(\tau)|k(\tau, x(\tau))|}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau \\
& +\frac{\left|f_{2}\left(t_{2}, x\left(t_{2}\right)\right)-f_{2}\left(t_{2}, 0\right)\right|+\left|f_{2}\left(t_{2}, 0\right)\right|}{\Gamma(\alpha)}\left|\int_{a}^{t_{1}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau-\int_{a}^{t_{2}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau\right| \\
& +\frac{\left|f_{2}\left(t_{2}, x\left(t_{2}\right)\right)-f_{2}\left(t_{2}, 0\right)\right|+\left|f_{2}\left(t_{2}, 0\right)\right|}{\Gamma(\alpha)}\left|\int_{a}^{t_{2}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau-\int_{a}^{t_{2}} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{\left(g\left(t_{2}\right)-g(\tau)\right)^{1-\alpha}} d \tau\right| \\
& \leq \varphi_{1}\left(\left|x\left(t_{1}\right)-x\left(t_{2}\right)\right|\right)+\omega_{f_{1}}\left(r_{0}, \rho\right)+\frac{\varphi_{2}\left(\left|x\left(t_{1}\right)-x\left(t_{2}\right)\right|\right)+\omega_{f_{2}}\left(r_{0}, \rho\right)}{\Gamma(\alpha+1)} \varphi\left(r_{0}\right)\left(g\left(t_{1}\right)-g(a)\right)^{\alpha} \\
& +\frac{\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)}{\Gamma(\alpha)} \int_{t_{2}}^{t_{1}} \frac{g^{\prime}(\tau)}{\left(g\left(t_{1}\right)-g(\tau)\right)^{1-\alpha}} d \tau \\
& +\frac{\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}\left(\left(g\left(t_{2}\right)-g(a)\right)^{\alpha}+\left(g\left(t_{1}\right)-g\left(t_{2}\right)\right)^{\alpha}-\left(g\left(t_{1}\right)-g(a)\right)^{\alpha}\right) \\
& \leq \varphi_{1}(\omega(x, \rho))+\omega_{f_{1}}\left(r_{0}, \rho\right)+\frac{\varphi_{2}(\omega(x, \rho))+\omega_{f_{2}}\left(r_{0}, \rho\right)}{\Gamma(\alpha+1)} \varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha} \\
& +\frac{2\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}\left(g\left(t_{1}\right)-g\left(t_{2}\right)\right)^{\alpha} \\
& \leq \varphi_{1}(\Omega(W, \rho))+\omega_{f_{1}}\left(r_{0}, \rho\right)+\frac{\varphi_{2}(\Omega(W, \rho))+\omega_{f_{2}}\left(r_{0}, \rho\right)}{\Gamma(\alpha+1)} \varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha} \\
& +\frac{2\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}[\omega(g, \rho)]^{\alpha},
\end{aligned}
$$

where
$\omega_{f_{i}}\left(r_{0}, \rho\right)=\sup \left\{\left|f_{i}(t, y)-f_{i}(s, u)\right|: u \in\left[-r_{0}, r_{0}\right], t, s \in[a, T],|t-s| \leq \rho\right\}, \quad i=1,2$.

## Therefore,

$$
\begin{aligned}
& \omega(U x, \rho) \leq \varphi_{1}(\Omega(W, \rho))+\omega_{f_{1}}\left(r_{0}, \rho\right)+ \\
& \quad \frac{\varphi_{2}(\Omega(W, \rho))+\omega_{f_{2}}\left(r_{0}, \rho\right)}{\Gamma(\alpha+1)} \varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha}+\frac{2\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}[\omega(g, \rho)]^{\alpha} .
\end{aligned}
$$

Passing to the limit as $\rho \rightarrow 0^{+}$, we obtain

$$
\eta(U W) \leq \varphi_{1}(\eta(W))+\frac{\varphi_{2}(\eta(W))}{\Gamma(\alpha+1)} \varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha} .
$$

Taking in consideration assumption (H2)-(iv), we get

$$
\begin{aligned}
\eta(U W) & \leq\left(\delta+\frac{\varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha}}{\Gamma(\alpha+1)}\right) T_{\max }\left(\theta, \varphi_{2}\right)(\eta(W)) \\
& =T\left(\lambda, T_{\max }\left(\theta, \varphi_{2}\right)\right)(\eta(W))
\end{aligned}
$$

where

$$
\lambda=\delta+\frac{\varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha}}{\Gamma(\alpha+1)}
$$

Since $\lambda \in[0,1]$ (see (H5)), from Lemma 2.3, $T\left(\lambda, T_{\max }\left(\theta, \varphi_{2}\right)\right) \in \Phi$. Finally, by Lemma 2.2, the operator $U$ has at least one fixed point $y^{*} \in \overline{B\left(0, r_{0}\right)}$, which is a solution to Eq.(2.1) satisfying $\left\|y^{*}\right\| \leq r_{0}$. This completes the proof.

If in Theorem 3.1 we add the following assumptions:
(H6) For $i=1,2, f_{i}([a, T] \times[0, \infty)) \subseteq[0, \infty)$ and $f_{i}$ is non-decreasing with respect to each variable on $[a, T] \times[0, \infty)$.
(H7) $k([a, T] \times[0, \infty)) \subseteq[0, \infty)$ and $k$ is non-decreasing with respect to each variable on $[a, T] \times[0, \infty)$.
Then we obtain the following result.
Theorem 3.2. Under the assumptions (H1)-(H7), Eq.(2.1) has at least one solution $y^{*} \in C([a, T] ; \mathbb{R})$ which is non-negative and non-decreasing on the interval $[a, T]$.

Proof. Let us consider the operator $U$ defined on $H=C([a, T] ; \mathbb{R})$ by (3.1). Following the proof of Theorem 3.1, we know that the operator $U$ maps $H$ into itself, and that, for $x \in H$, we have the estimate

$$
\|U x\| \leq \varphi_{1}(\|x\|)+f_{1}^{*}+\frac{\left(\varphi_{2}(\|x\|)+f_{2}^{*}\right) \varphi(\|x\|)}{\Gamma(\alpha+1)}(g(T)-g(a))^{\alpha}, \quad x \in H
$$

which yields $U\left(\overline{B\left(0, r_{0}\right)}\right) \subseteq \overline{B\left(0, r_{0}\right)}$. Now, we consider the subset $B_{r_{0}}^{+}$of $\overline{B\left(0, r_{0}\right)}$ defined by

$$
B_{r_{0}}^{+}=\left\{x \in \overline{B\left(0, r_{0}\right)}: x(t) \geq 0, t \in[a, T]\right\} .
$$

In virtue (H6) and (H7), we may infer that the operator $U$ maps $B_{r_{0}}^{+}$into itself. Following the same argument used in the proof of Theorem 3.1, we obtain that $U$ is a continuous operator on $B_{r_{0}}^{+}$. Next, we take the subset $Q$ of $B_{r_{0}}^{+}$defined by

$$
Q=\left\{x \in B_{r_{0}}^{+}: x \text { is non-decreasing }\right\} .
$$

Obviously, the set $Q$ is nonempty, bounded, closed and convex. Let us prove that the operator $U$ maps $Q$ into itself. To do this, let $x \in Q$ be fixed and $(t, s)$ be a pair of elements in $[a, T] \times[a, T]$ such that $t \geq s$. By assumption (H6), we have

$$
f_{i}(t, x(t)) \geq f_{i}(s, x(s)), \quad i=1,2 .
$$

So we have just to prove that

$$
\begin{equation*}
\int_{a}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau \geq \int_{a}^{s} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(s)-g(\tau))^{1-\alpha}} d \tau \tag{3.4}
\end{equation*}
$$

We have

$$
\begin{aligned}
& \int_{a}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau-\int_{a}^{s} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(s)-g(\tau))^{1-\alpha}} d \tau \\
& =\int_{a}^{s}\left(\frac{g^{\prime}(\tau)}{(g(t)-g(\tau))^{1-\alpha}}-\frac{g^{\prime}(\tau)}{(g(s)-g(\tau))^{1-\alpha}}\right) k(\tau, x(\tau)) d \tau \\
& +\int_{s}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau .
\end{aligned}
$$

Using assumption (H7), we obtain

$$
\begin{aligned}
& \int_{a}^{t} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(t)-g(\tau))^{1-\alpha}} d \tau-\int_{a}^{s} \frac{g^{\prime}(\tau) k(\tau, x(\tau))}{(g(s)-g(\tau))^{1-\alpha}} d \tau \\
& \geq k(s, x(s)) \int_{a}^{s}\left(\frac{g^{\prime}(\tau)}{(g(t)-g(\tau))^{1-\alpha}}-\frac{g^{\prime}(\tau)}{(g(s)-g(\tau))^{1-\alpha}}\right) d \tau \\
& +k(s, x(s)) \int_{s}^{t} \frac{g^{\prime}(\tau)}{(g(t)-g(\tau))^{1-\alpha}} d \tau \\
& =k(s, x(s))\left(\int_{a}^{t} \frac{g^{\prime}(\tau)}{(g(t)-g(\tau))^{1-\alpha}} d \tau-\int_{a}^{s} \frac{g^{\prime}(\tau)}{(g(s)-g(\tau))^{1-\alpha}} d \tau\right) \\
& =\frac{k(s, x(s))}{\alpha}\left((g(t)-g(a))^{\alpha}-(g(s)-g(a))^{\alpha}\right) \geq 0 .
\end{aligned}
$$

Then (3.4) holds and $U x$ is a non-decreasing function. Therefore, $u$ maps $Q$ into itself. Finally, using the same argument of the proof of Theorem 3.1, we obtain

$$
\eta(U W) \leq T\left(\lambda, T_{\max }\left(\theta, \varphi_{2}\right)\right)(\eta(W)), \quad W \subseteq Q,
$$

where

$$
\lambda=\delta+\frac{\varphi\left(r_{0}\right)(g(T)-g(a))^{\alpha}}{\Gamma(\alpha+1)} \in[0,1] .
$$

An application of Lemma 2.2 gives us the desired result.

## 4 Particular cases and examples

In this section, using Theorem 3.1, we give some existence results for some functional equations involving various types of fractional integrals. We present also some illustrative examples.

### 4.1 A functional equation involving Riemann-Liouville fractional integral

Let us consider the integral equation

$$
\begin{equation*}
x(t)=f_{1}(t, x(t))+\frac{f_{2}(t, x(t))}{\Gamma(\alpha)} \int_{a}^{t} \frac{k(\tau, x(\tau))}{(t-\tau)^{1-\alpha}} d \tau, \quad t \in[a, T] \tag{4.1}
\end{equation*}
$$

where $\alpha \in(0,1), 0 \leq a<T, k:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}$ and $f_{i}:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}(i=1,2)$. Eq.(4.1) can be written as

$$
x(t)=f_{1}(t, x(t))+f_{2}(t, x(t)) I_{a}^{\alpha} k(\cdot, x(\cdot))(t), \quad t \in[a, T],
$$

where $I_{a}^{\alpha}$ is the Riemann-Liouville fractional integral of order $\alpha$ defined by (2.2).
Take

$$
g(t)=t, \quad t \in[a, T]
$$

in Theorem 3.1, we obtain the following existence result.
Corollary 4.1. Suppose that all the assumptions (H1)-(H3) are satisfied. Moreover, suppose that there exists $r_{0}>0$ such that

$$
\left(\varphi_{1}\left(r_{0}\right)+f_{1}^{*}\right) \Gamma(\alpha+1)+\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)(T-a)^{\alpha} \leq r_{0} \Gamma(\alpha+1)
$$

and

$$
\delta+\frac{\varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}(T-a)^{\alpha} \leq 1 .
$$

Then (4.1) has at least one solution $y^{*} \in C([a, T] ; \mathbb{R})$. Moreover, we have $\left\|y^{*}\right\| \leq$ $r_{0}$.

We present the following example to illustrate the above result.
Example 4.2. Consider the integral equation

$$
\begin{equation*}
x(t)=\frac{t}{2}+\frac{\sqrt{\pi}}{8}\left(\frac{t}{3}+|x(t)|\right) \int_{0}^{t} \frac{x(\tau)}{\left(\tau^{2}+1\right) \sqrt{t-\tau)}} d \tau, \quad t \in[0,1] . \tag{4.2}
\end{equation*}
$$

The above equation can be written in the form (4.1) with $a=0, T=1, \alpha=\frac{1}{2}$,

$$
\begin{aligned}
f_{1}(t, u) & =\frac{t}{2}, \quad(t, u) \in[0,1] \times \mathbb{R} \\
f_{2}(t, u) & =\frac{\sqrt{\pi}}{8}\left(\frac{t}{3}+|u|\right), \quad(t, u) \in[0,1] \times \mathbb{R} \\
k(t, u) & =\frac{\sqrt{\pi}}{2} \frac{u}{\left(t^{2}+1\right)}, \quad(t, u) \in[0,1] \times \mathbb{R}
\end{aligned}
$$

We can check easily that all the assumptions (H1)-(H3) are satisfied with $\varphi_{1}(t)=$ $\theta(t)=\delta=0, \varphi_{2}(t)=\frac{\sqrt{\pi}}{8} t$ and $\varphi(r)=\frac{\sqrt{\pi}}{2} r$. Moreover, in this case, we have $f_{1}^{*}=\frac{1}{2}$ and $f_{2}^{*}=\frac{\sqrt{\pi}}{24}$. Observe that for $r_{0}=1$, we have

$$
\delta+\frac{\varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}(T-a)^{\alpha}=1 .
$$

Moreover,

$$
\left.\begin{array}{rl}
\left(\varphi_{1}\left(r_{0}\right)+f_{1}^{*}\right) \Gamma(\alpha+1)+\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)( & T-a)^{\alpha}
\end{array}\right) .
$$

Then all the required assumptions of Corollary 4.1 are satisfied. As consequence, Eq.(4.2) has at least one solution $y^{*} \in C([0,1] ; \mathbb{R})$ satisfying $\left\|y^{*}\right\| \leq 1$.

### 4.2 A functional equation involving Erdélyi-Kober fractional integral

Let us consider the integral equation

$$
\begin{equation*}
x(t)=f_{1}(t, x(t))+\frac{\beta f_{2}(t, x(t))}{\Gamma(\alpha)} \int_{a}^{t} \frac{\tau^{\beta-1} k(\tau, x(\tau))}{\left(t^{\beta}-\tau^{\beta}\right)^{1-\alpha}} d \tau, \quad t \in[a, T] \tag{4.3}
\end{equation*}
$$

where $\alpha \in(0,1), \beta>0,0 \leq a<T, k:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}$ and $f_{i}:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}$ ( $i=1,2$ ). Eq.(4.3) can be written as

$$
x(t)=f_{1}(t, x(t))+f_{2}(t, x(t)) I_{a, \beta}^{\alpha} k(\cdot, x(\cdot))(t), \quad t \in[a, T],
$$

where $I_{a, \beta}^{\alpha}$ is the Erdélyi-Kober fractional integral defined by (2.3).
Take

$$
g(t)=t^{\beta}, \quad t \in[a, T]
$$

in Theorem 3.1, we obtain the following existence result.
Corollary 4.3. Suppose that all the assumptions (H1)-(H3) are satisfied. Moreover, suppose that there exists $r_{0}>0$ such that

$$
\left(\varphi_{1}\left(r_{0}\right)+f_{1}^{*}\right) \Gamma(\alpha+1)+\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)\left(T^{\beta}-a^{\beta}\right)^{\alpha} \leq r_{0} \Gamma(\alpha+1)
$$

and

$$
\delta+\frac{\varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}\left(T^{\beta}-a^{\beta}\right)^{\alpha} \leq 1
$$

Then (4.3) has at least one solution $y^{*} \in C([a, T] ; \mathbb{R})$. Moreover, we have $\left\|y^{*}\right\| \leq r_{0}$.

We present the following example to illustrate the above result.
Example 4.4. We consider the integral equation
$x(t)=\frac{e^{-1} t}{10}+\frac{\beta e^{\frac{37}{19}}}{76 \Gamma(\alpha)}(t+1+\arctan |x(t)|) \int_{0}^{t} \frac{\tau^{\beta-1} x(\tau)}{\left(t^{\beta}-\tau^{\beta}\right)^{1-\alpha} \sqrt{\tau+1}} d \tau, \quad t \in[0,1]$,
where $\alpha \in(0,1)$ and $\beta>0$. The above equation can be written in the form (4.3) with $a=0, T=1$,

$$
\begin{aligned}
f_{1}(t, u) & =\frac{e^{-1} t}{10}, \quad(t, u) \in[0,1] \times \mathbb{R}, \\
f_{2}(t, u) & =\frac{t+1+\arctan |u|}{2}, \quad(t, u) \in[0,1] \times \mathbb{R}, \\
k(t, u) & =\frac{e^{\frac{37}{19}} u}{38 \sqrt{t+1}}, \quad(t, u) \in[0,1] \times \mathbb{R} .
\end{aligned}
$$

We can check easily that all the assumptions (H1)-(H3) are satisfied with $\varphi_{1}(t)=$ $\theta(t)=\delta=0, \varphi_{2}(t)=\frac{t}{2}$ and $\varphi(r)=\frac{e^{\frac{37}{19}}}{38} r$. Moreover, in this case, we have $f_{1}^{*}=\frac{e^{-1}}{10}$ and $f_{2}^{*}=1$. On the other hand, we have [22]

$$
\frac{e^{\frac{37}{19}}}{76}=0.0922 \ldots \leq 0.8856 \leq \Gamma(\alpha+1), \text { for } \alpha \in(0,1)
$$

Then for $r_{0}=\frac{1}{2}$, we have

$$
\delta+\frac{\varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}\left(T^{\beta}-a^{\beta}\right)^{\alpha}=\frac{\frac{\frac{37}{71}}{76}}{\Gamma(\alpha+1)} \leq 1
$$

Next, we have

$$
\begin{aligned}
& \left(\varphi_{1}\left(r_{0}\right)+f_{1}^{*}\right)+\frac{\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)\left(T^{\beta}-a^{\beta}\right)^{\alpha}}{\Gamma(\alpha+1)} \\
& =\frac{e^{-1}}{10}+\frac{5 e^{\frac{37}{19}}}{304 \Gamma(\alpha+1)} \leq 0.16698 \ldots \leq \frac{1}{2}=r_{0}
\end{aligned}
$$

Then all the required assumptions of Corollary 4.3 are satisfied. As consequence, Eq.(4.4) has at least one solution $y^{*} \in C([0,1] ; \mathbb{R})$ satisfying $\left\|y^{*}\right\| \leq \frac{1}{2}$.

### 4.3 A functional equation involving Hadamard fractional integral

We consider the integral equation

$$
\begin{equation*}
x(t)=f_{1}(t, x(t))+\frac{f_{2}(t, x(t))}{\Gamma(\alpha)} \int_{a}^{t}\left(\ln \frac{t}{\tau}\right)^{\alpha-1} \frac{k(\tau, x(\tau))}{\tau} d \tau, \quad t \in[a, T] \tag{4.5}
\end{equation*}
$$

where $0<a<T, \alpha \in(0,1), k:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}$ and $f_{i}:[a, T] \times \mathbb{R} \rightarrow \mathbb{R}(i=1,2)$. Eq.(4.5) can be written as

$$
x(t)=f_{1}(t, x(t))+f_{2}(t, x(t)) J_{a}^{\alpha} k(\cdot, x(\cdot))(t), \quad t \in[a, T],
$$

where $J_{a}^{\alpha}$ is the Hadamard fractional integral of order $\alpha$ defined by (2.4).
Take

$$
g(t)=\ln t, \quad t \in[a, T]
$$

in Theorem 3.1, we obtain the following existence result.
Corollary 4.5. Suppose that all the assumptions (H1)-(H3) are satisfied. Moreover, suppose that there exists $r_{0}>0$ such that

$$
\begin{equation*}
\left(\varphi_{1}\left(r_{0}\right)+f_{1}^{*}\right) \Gamma(\alpha+1)+\left(\varphi_{2}\left(r_{0}\right)+f_{2}^{*}\right) \varphi\left(r_{0}\right)\left(\ln \frac{T}{a}\right)^{\alpha} \leq r_{0} \Gamma(\alpha+1) \tag{4.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\delta+\frac{\varphi\left(r_{0}\right)}{\Gamma(\alpha+1)}\left(\ln \frac{T}{a}\right)^{\alpha} \leq 1 \tag{4.7}
\end{equation*}
$$

Then (4.5) has at least one solution $y^{*} \in C([a, T] ; \mathbb{R})$. Moreover, we have $\left\|y^{*}\right\| \leq$ $r_{0}$.

We end the paper with the following example that illustrates the above result.
Example 4.6. Let us consider the integral equation

$$
\begin{equation*}
x(t)=e^{-2} t+2 \alpha e^{-3} x(t) \int_{1}^{t}\left(\ln \frac{t}{\tau}\right)^{\alpha-1} x(\tau) d \tau, \quad t \in\left[1, e^{1}\right] \tag{4.8}
\end{equation*}
$$

where $\alpha \in(0,1)$. Eq.(4.8) can be written in the form (4.5) with $a=1, T=e^{1}$,

$$
\begin{aligned}
f_{1}(t, u) & =e^{-2} t, \quad(t, u) \in\left[1, e^{1}\right] \times \mathbb{R} \\
f_{2}(t, u) & =\frac{u}{2}, \quad(t, u) \in\left[1, e^{1}\right] \times \mathbb{R} \\
k(t, u) & =4 e^{-3} \Gamma(\alpha+1) t u, \quad(t, u) \in\left[1, e^{1}\right] \times \mathbb{R}
\end{aligned}
$$

We can check easily that all the assumptions (H1)-(H3) are satisfied with $\varphi_{1}(t)=$ $\theta(t)=\delta=0, \varphi_{2}(t)=\frac{t}{2}$ and $\varphi(r)=4 e^{-2} \Gamma(\alpha+1) r$. In this case, we have $f_{1}^{*}=e^{-1}$ and $f_{2}^{*}=0$. Moreover, for $r_{0}=\frac{e^{2}}{4}$, the inequalities (4.6) and (4.7) are satisfied. Therefore, by Corollary 4.5, Eq.(4.8) has at least one solution $y^{*} \in C\left(\left[1, e^{1}\right] ; \mathbb{R}\right)$ such that $\left\|y^{*}\right\| \leq \frac{e^{2}}{4}$.

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